

Fig. 2: Example of system software graphic tools, including pixel reflectivity plots and common radar maps for validation.

### 3. Radar module.

Radar information is used in the system in different ways. On the one hand, radar products are available in the system for consistency and validation purposes. On the other hand, for real time surveillance we have developed a module in order to improve the detection and monitoring of risky situations associated with convection.

The input of the detection and warning function is a PCAPPI image (2 km, 100 km range). Specifically, it is a Rainbow® (GEMATRONIK) file corresponding to the decompressed binary part of the product. In order to avoid assigning erroneous warning areas, the image is processed by applying a static mask of the ground clutter (Maruri et al 2010).

The output product is a second-level product which is applied on the PCAPPI 2 km (dBZ). The identification of risk regions, potentially flash flood precursors, is based on a series of predetermined criteria. It has been established as a potential warning an area with a minimum diameter of 5 km, with 50% of its pixels exceeding 45 dBZ (Table 1). It is a common procedure widely used for the identification of convective cells (e.g. Rainbow® by Gematronik).

Threshold	Reflectivity to be exceeded	45 dBZ
Fill Factor	Minimum fill factor for warning area	50 %
Diameter	Minimum diameter of the warning area	5 km

Table 1: Warning parameters.

#### 3.1. The identification function

The identification function creates a mask from the original image, detecting those convective systems that meet the requirements detailed above. The body of this function is composed by a routine written in IDL® language (Exelis Visual Information Solutions) named “blob\_analyzer\_routine” (Fanning Software Consulting, Inc.), with the appropriate modifications to adapt it to our needs. The purpose of this routine is to create a system for analyzing regions of interest inside images (ROIs), also known as “blobs”. In particular, given a radar image, the program will automatically select blobs and capture their properties (Table 2).

Methods	Purpose
NumberOfBlobs	Returns the number of blob identified in the image
GetIndices	Returns the indices of a particular blob
GetStat	Returns a data structure with the statistics of a particular blob
FitEllipse	Fits an ellipse to the blob
ReportStats	Reports the statistics of each blob found in the image

Table 2. Blob analyzer methods

The first step in detecting blobs is to prepare a binary image, in which pixels that meet the first condition (reflectivity to be exceeded) are selected. Then, “label\_region” function consecutively labels all regions or blobs of two-dimensional image with a unique index, obtained by the density function. The latter is returned by the “histogram” function, that is, the function returns an array containing a list of the original array subscripts that contributed to each histogram bin. This list, commonly called the reverse index list, efficiently determines which array elements are accumulated in a set of histogram bin. All this process is known as *blob coloring*. The process continues by analyzing the other parameters for warning: diameter parameter control and fill factor parameter control (Fig 3). For that purpose, some statistics of each blob are used (Table 3).

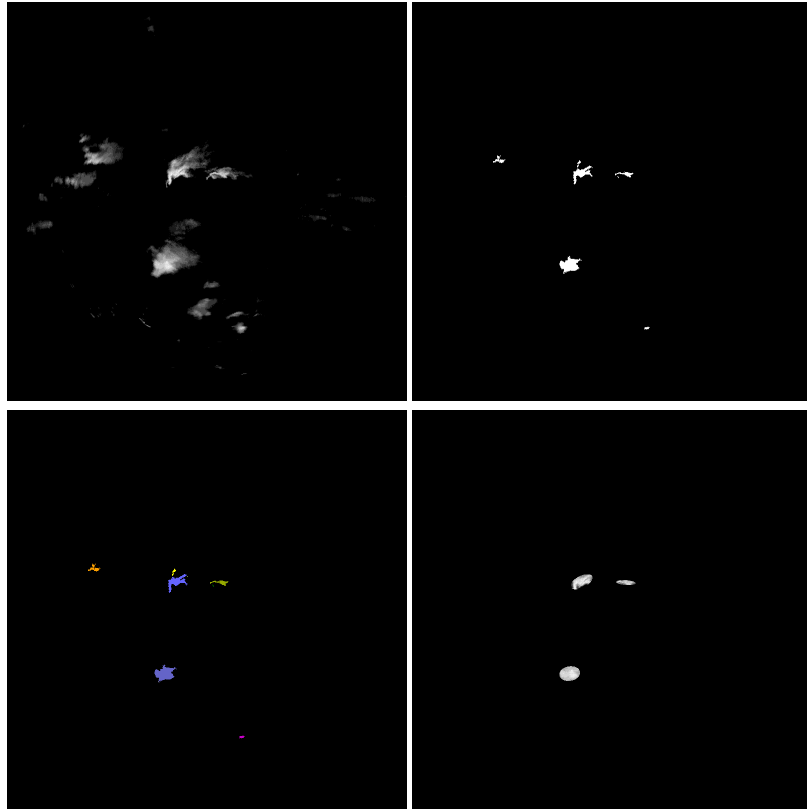


Fig. 3: Original data (PCAPPI >10 dBZ) (upper left); mask image with pixels greater than threshold (upper right); image of unique regions from “Label\_Region” function (bottom left); ellipse mask for minimum diameter and fill factor (bottom right). Date: 2009/07/01 14:50.

Output keyword	Description
Index	the index number of this blob
Count	the number of indices in this blob
Perimeter_Pts	a [2,n] array of points that describe the blob perimeter
Pixel_Area	the area as calculated by pixels in the blob
Perimeter_Area	the area as calculated by the blob perimeter
Center	the [x,y] array that identifies the centroid of the blob
Perimeter_Length	the perimeter length
Scale	the [xscale, yscale] array used in scaling
Mincol	the minimum column index in the blob
Maxcol	the maximum column index in the blob
Minrow	the minimum row index in the blob
Maxrow	the maximum row index in the blob

Table 3. Data structure with the statistics of a particular blob

### 3.2. Reports and Visualization.

The blob analyzer contains a method responsible for reporting the statistics of each blob found in the image. This information is dumped to a text file, with different fields (Table 4).

Index	ID number
LON/LAT	Geographical coordinates of the centroid
N° pixels	Number of cells that are part of the blob
Area	Blob surface calculated from the number of cells
Perimeter	Length of the perimeter
dBZ_Med	Average of the reflectivities
dBZ_Max	Maximum reflectivity
dBZ_vza	Variance of the reflectivity
Max axis	Length of the mayor axis of the ellipse fitted to the blob
Min axis	Length of the minor axis of the ellipse fitted to the blob
Angle	Orientation of the ellipse fitted to the blob
Comarca	Name of the region where is located the centroid of the blob

Table 4: blob statistics fields

The application results are shown as a PCAPPI image, including colour palette, background image and limit boundaries. The image fusion, with original PCAPPI product, is performed using RGBA space, adding the alpha channel (transparency) to the original RGB space. The detected blobs are represented on the image with their fitted ellipses (Fig 4). The centroid index is also included in its position. The final composition is stored in a graphics file format.

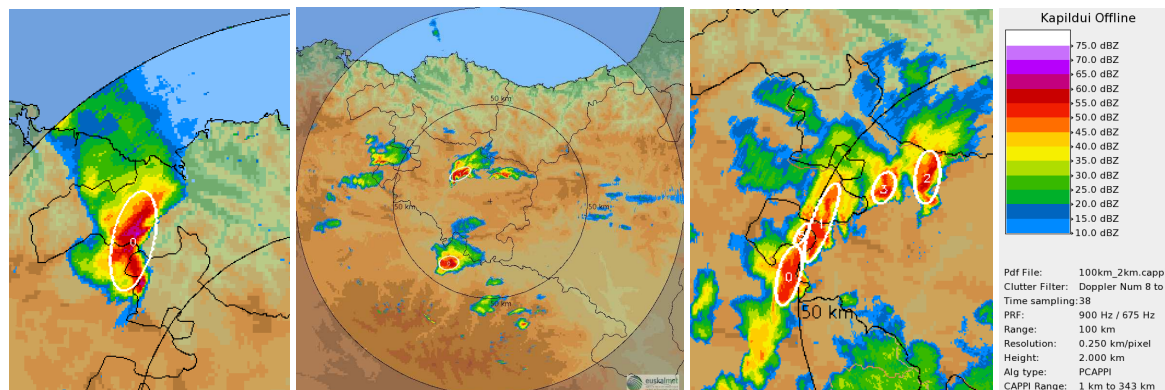


Fig. 4: Example images of warning product. Images correspond to hail storms. Dates: 2006/07/04 14:22 (left), 2009/07/01 14:50 (centre), 2011/05/30 14:00 (right) (note that the static mask of the ground clutter was not operative yet).

#### 4. Summary and conclusions

Basque Meteorology Agency (Euskalmet) responsibilities include issuing severe weather warnings (Gaztelumendi et al 2011). In this sense, the project first establishes internal criteria and thresholds for detection of heavy rain episodes based on data from Kapildui radar reflectivity. The warnings are visible to the user at two different levels: i) the risky areas are displayed together with the PCAPPI product; ii) a summary of risky areas properties are written in a text file.

The module of identification of risky regions from radar data, potentially flash flood precursors, is written in a fourth generation programming language, well suited to digital processing of images. This allows some flexibility to develop operational software for monitoring and nowcasting.

Pre-operational system is a first step in the development of a rainfall early warning system. All the system, including the radar module, must be checked with more detailed studies on severe weather scenarios. In the future we will define other criteria based on different radar products in order to improve the system and complement the information obtained in real-time from the AWS network.

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