



Doppler Radar Assimilation

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Special thanks to the MetOffice Radar Team



Outline

- Introduction
- Doppler Radial Wind at the Met Office
- NDP
- Proposed modifications
- Results
- Conclusion



Introduction

Aim: Develop a NWP-based system to replace our current Lagrangian advection-based nowcasting system to focus on hazardous weather, especially flood risk

Radar data are the “perfect” candidate for assimilation:

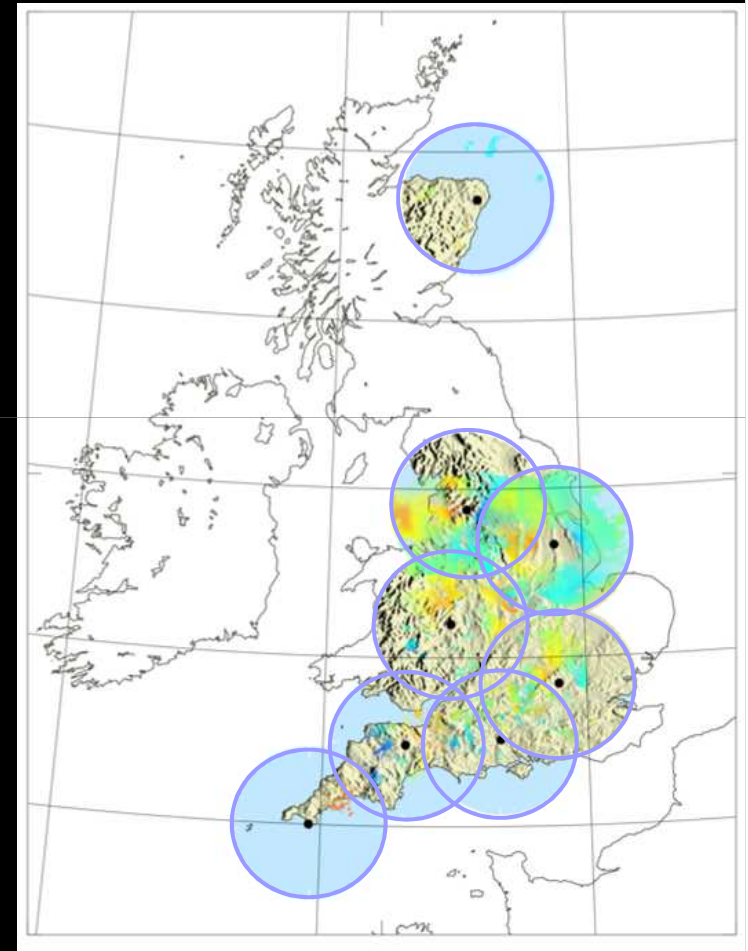
- High resolution / High repetition time / Large coverage

The Nowcasting Demonstration Project (NDP) system has been running in real-time since May 2012



Doppler Wind at the Met Office

- Doppler Radar:
 - 8 Doppler capable Radars (C Band)
 - Unambiguous velocity 48 m/s
 - 5 Elevations (1, 2, 4, 6, 9)
 - One volume scan every 5 minutes
- Preprocessing:
 - Centralised processing and QC (RadarNet)
 - Doppler PPI scan with QC flag
- Before Assimilation:
 - Additional QC (unfolding) using Model Background





Doppler Wind at the Met Office

Operational setup

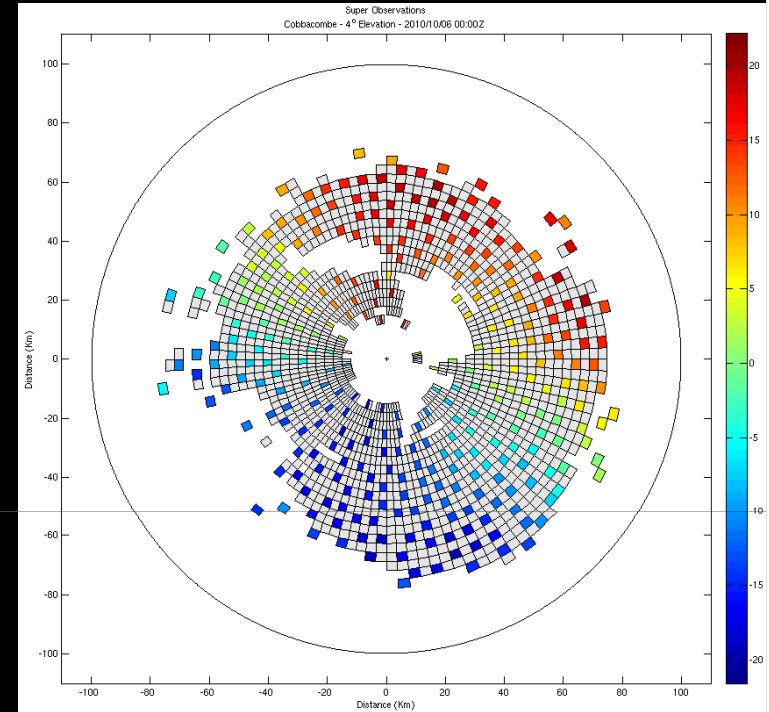
- Operationally used in UKV and UK4 from June 2011
- PPI scan (1 per Analysis – All elevation):
- Super-Observation:
 - 3° x 5 range gates - thinned (6km for UKV – 8km for UK4)

- Observation Operator:

$$v_r = u \sin \phi \cos \theta + v \cos \phi \cos \theta + w \sin \theta$$

- Observation error:

- Range from 2 to 3m/s with range





- Motivation
- Doppler Radial Wind at the Met Office
- NDP

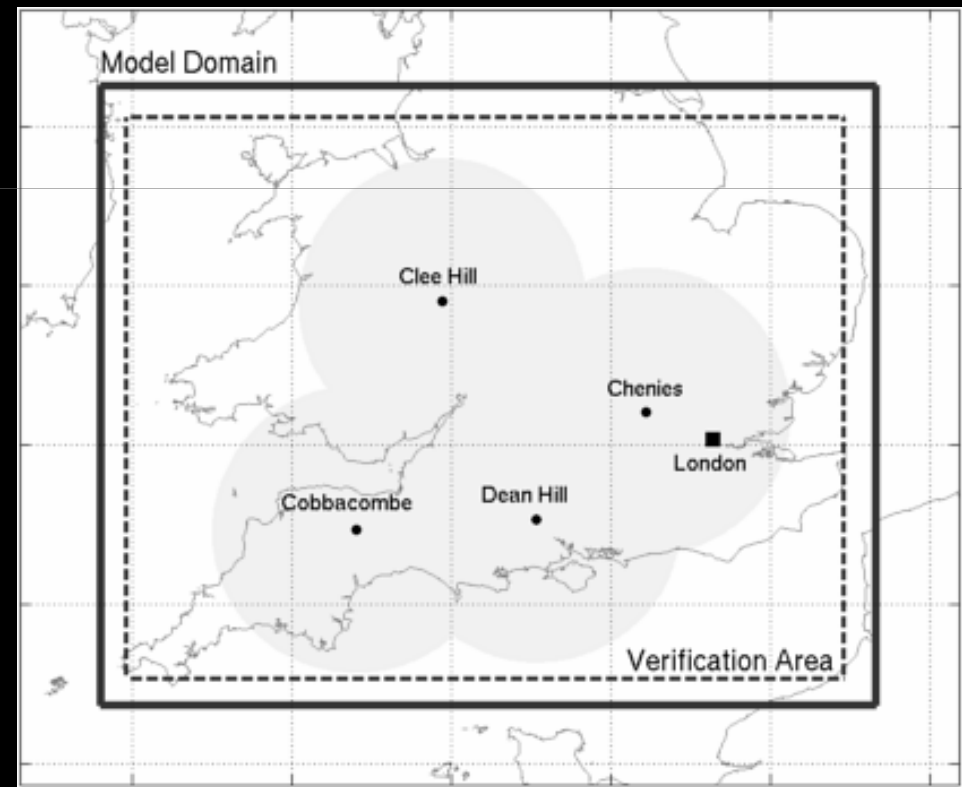
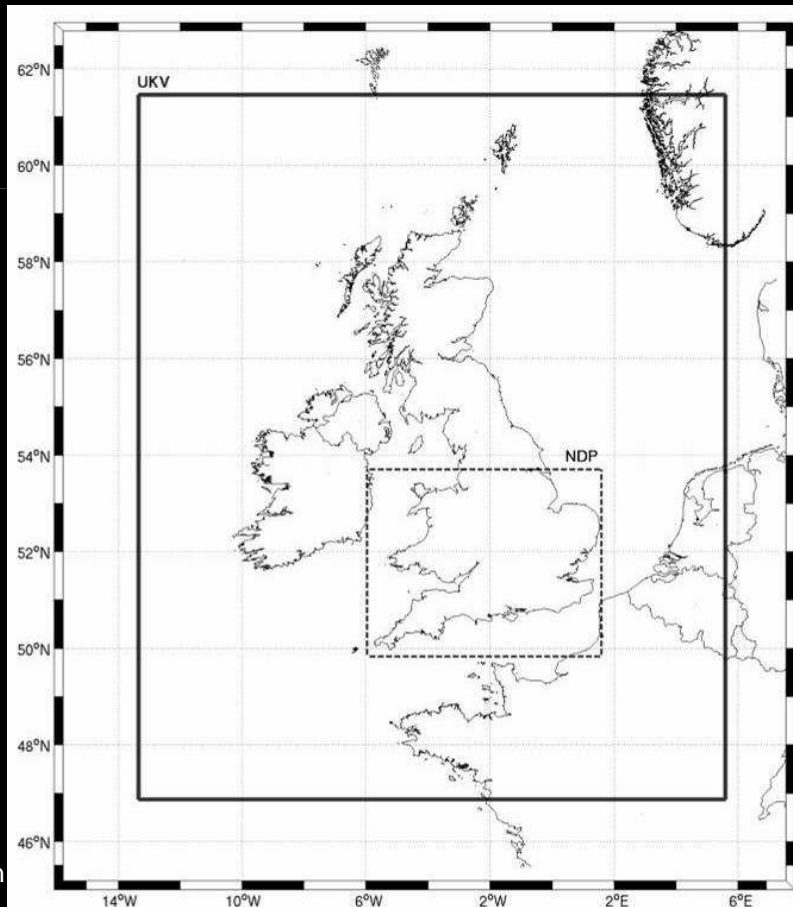


Met Office

NDP

Model Domain

Model	Resolution	VAR	Time Window	Cycling	Forecast Length	Doppler
UKV	1.5km	3D-Var	3	3 h	T+36	1 Vol. Scan
NDP	1.5 km	4D-Var	1	1 h	T+7	6 Vol. Scan

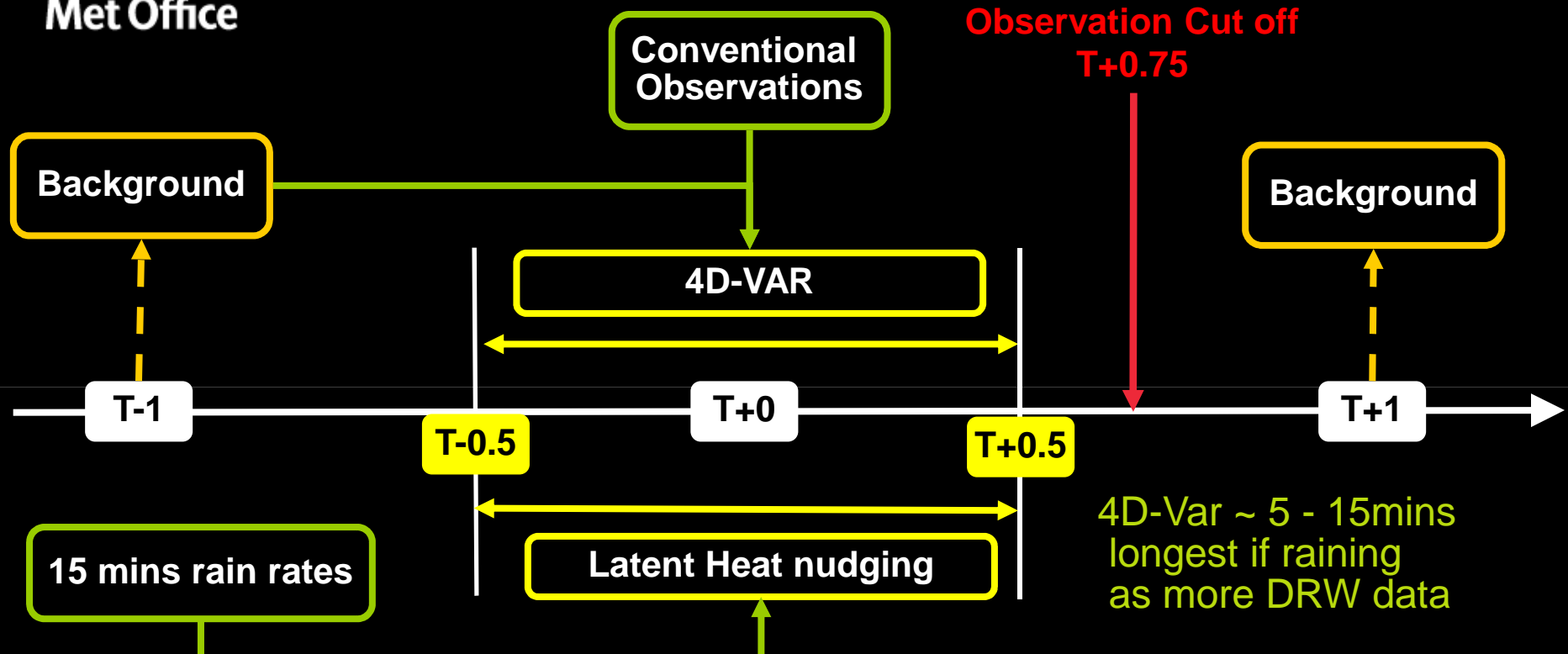


Nested in UKV. LBCs updated every 30mins; refreshed every 6 hours



NDP

Assimilation setup



Background Error Covariance:

Training data generated using the NMC method
A set of 75 lagged NDP forecast differences (6h-3h)
where forecast pairs used the same LBCs

4D-Var ~ 5 - 15mins
longest if raining
as more DRW data

7-hr fcst from T-0.5
Takes ~10mins

Available at T+1.25



NDP

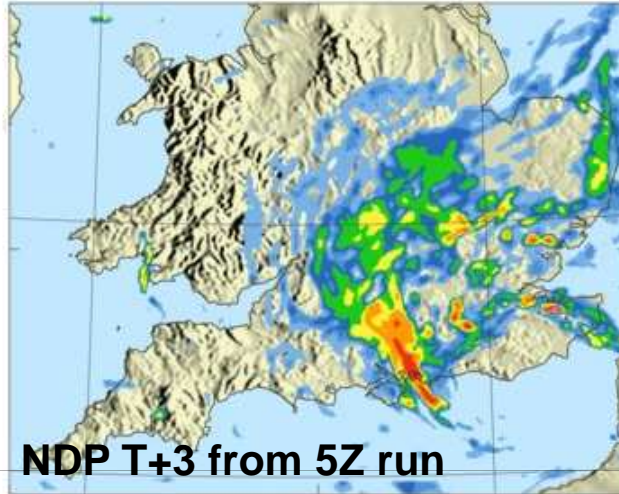
Observations usage

- 4 radars Doppler radial wind 6 times per hour
- 4 wind profilers every 15mins
- SEVIRI channel 5 (clear and over low cloud) and channel 6 (clear) every 15mins plus clear window channels over sea
- 3D moisture derived from cloud observations (satellite + surface reports)
- AMV (atmospheric motion vector)
- AMDAR 1 per hour
- hourly surface T,RH, wind, P, visibility
- Latent heat nudging with radar derived rain rates every 15mins

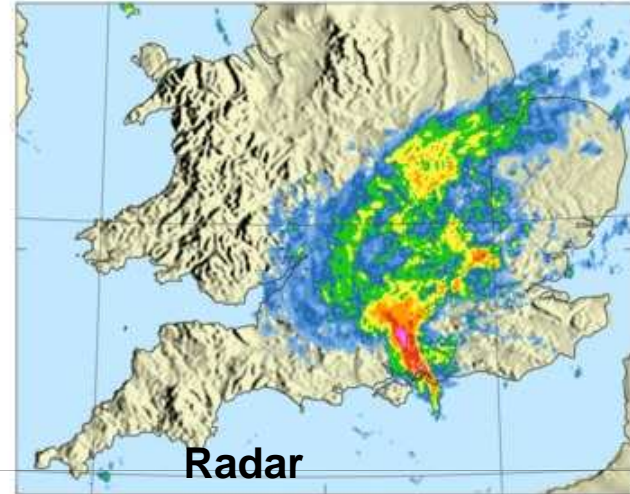


NDP Example 11th June 2012

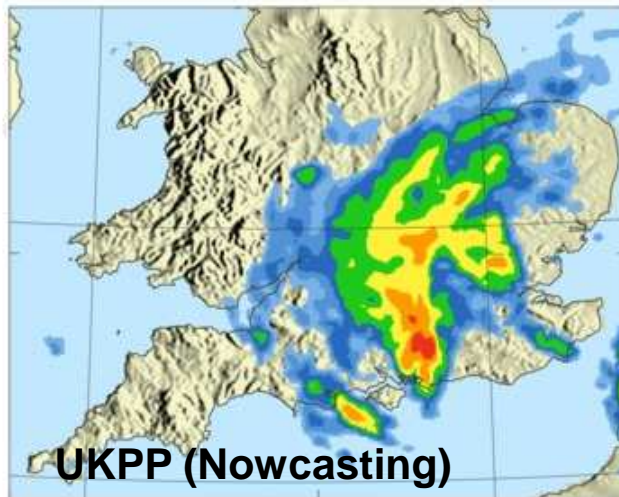
NDP - Rain Rate
At 08:00Z on 11/ 6/2012, from 05:00Z on 11/ 6/2012



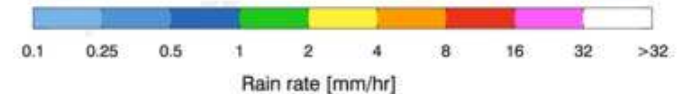
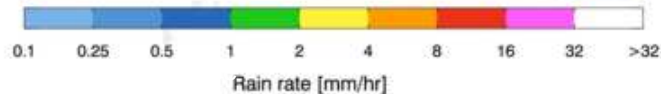
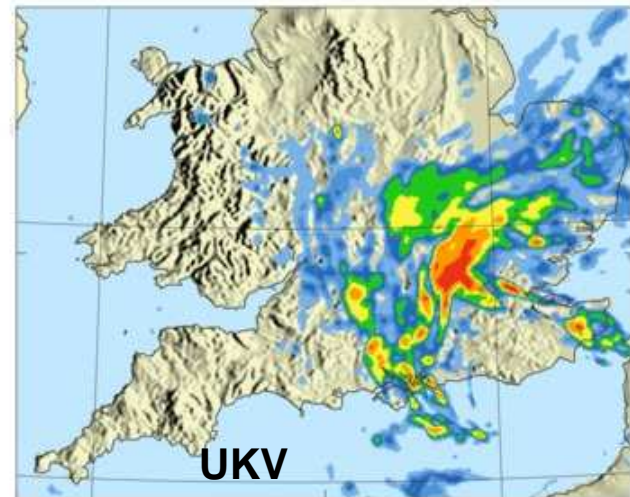
Radar Rainfall Rate (composite:1km)
For 0800Z on 11/06/2012



STEPS rainrate (rate:2km)
For 0800Z on 11/06/2012



AAABO surface Atmos large scale rainfall rate kg/m2/s
At 08:00Z on 11/ 6/2012, from 21:00Z on 10/ 6/2012





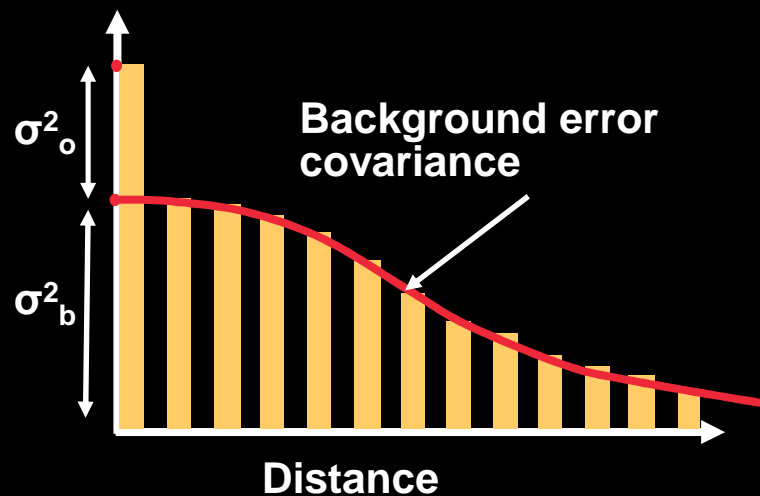
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 - Observation Error



Observation Error:

Hollingsworth–Lonnberg

- Rely on the use of departure between the background and observation (innovations)
- Construct a histogram of background departure covariance against distance (d)



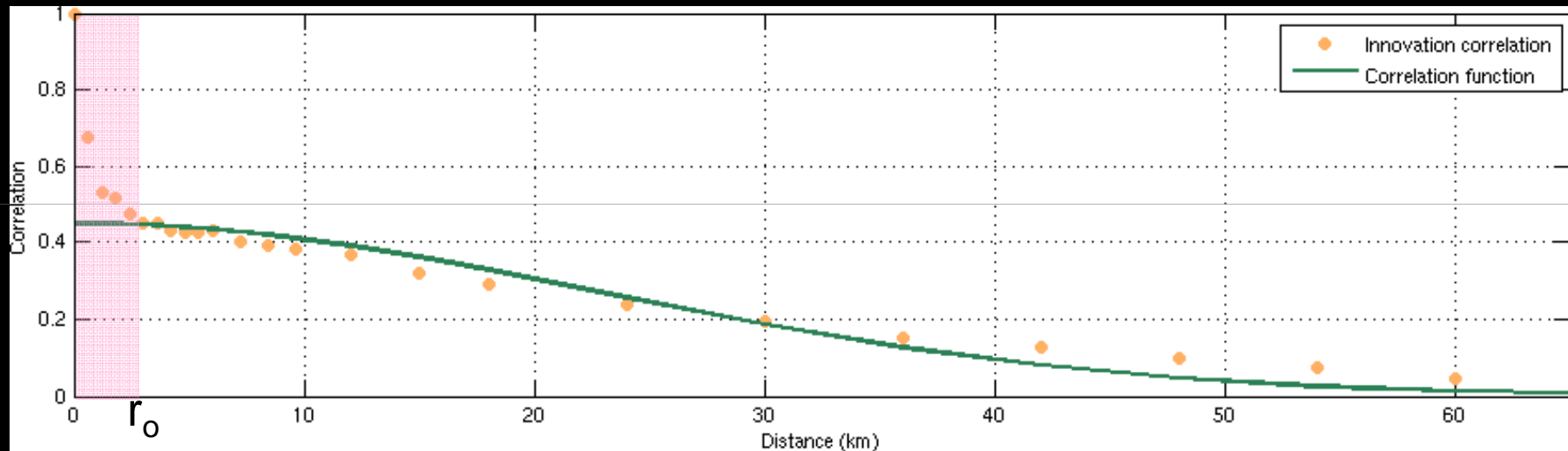
$$\text{At } d = 0 \rightarrow \sigma^2_o + \sigma^2_b$$
$$\text{At } d > 0 \rightarrow \sigma^2_b$$

$$\sigma^2_o = \text{Inst. Error} + \text{Rep. Error}$$



Observation Error: Hollingworth–Lonnberg

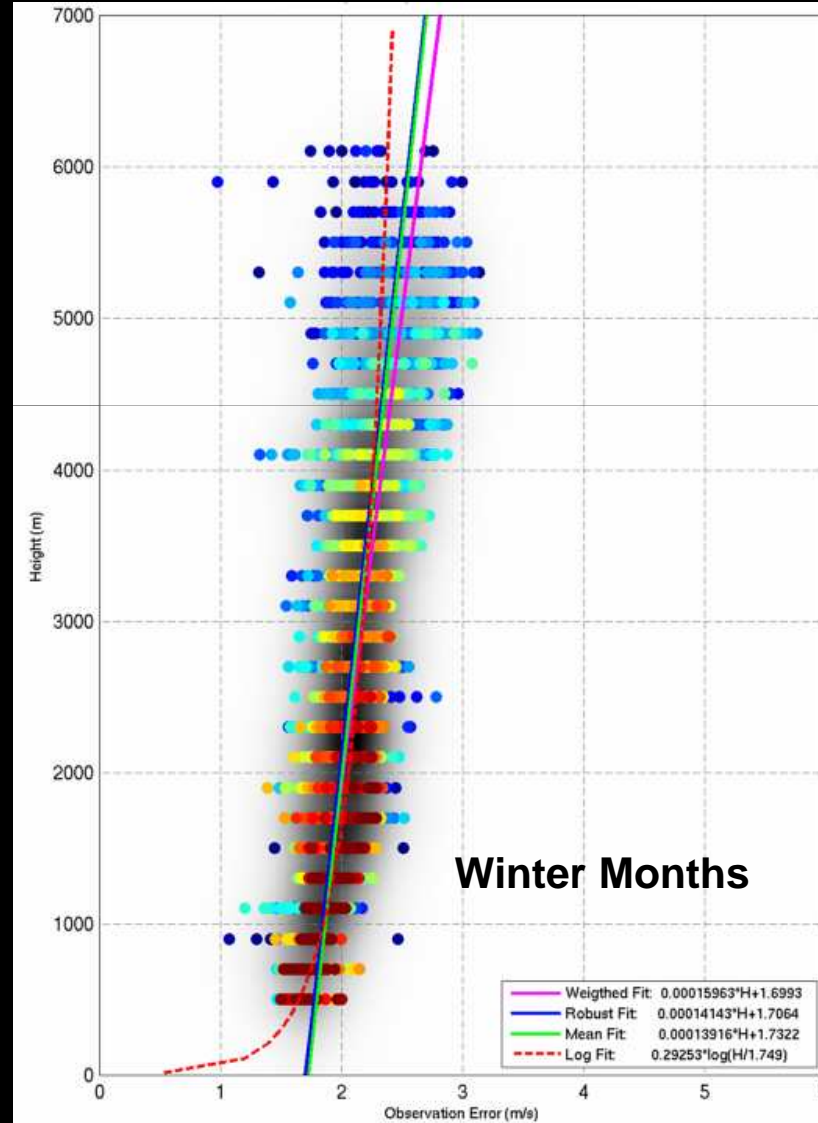
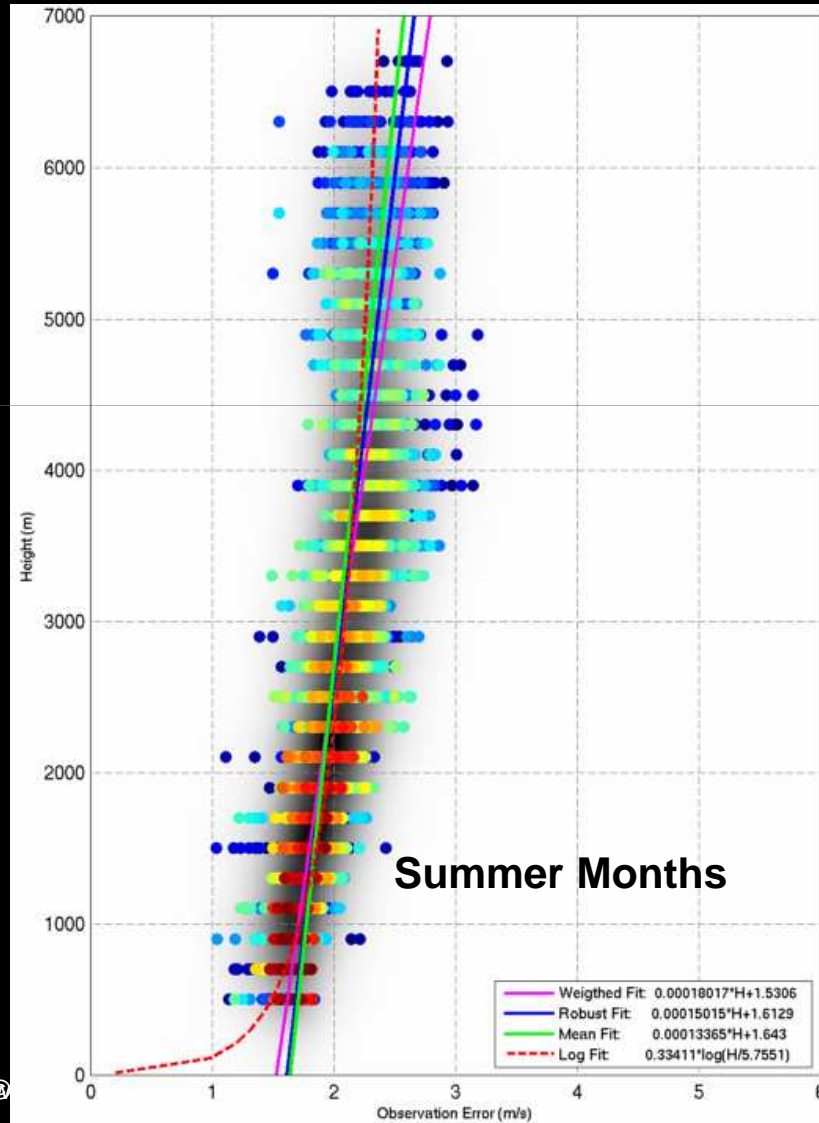
Clee Hill – Height: 1700m - Winter



Observation Correlation length: 1-3 km
Equivalent to 2 to 5 gates



Observation Error: Hollingsworth–Lonnberg





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 - Beam Broadening



New Observation Operator

Radar measurement is a volume measurement

- **Beam broadening:**

$$w(\theta_z) = \exp\left[-3 \times \ln 2 \left(\frac{\theta_z^2}{\theta_3^2}\right)\right]$$

$$\theta_z^2 = \phi^2 - \theta^2$$

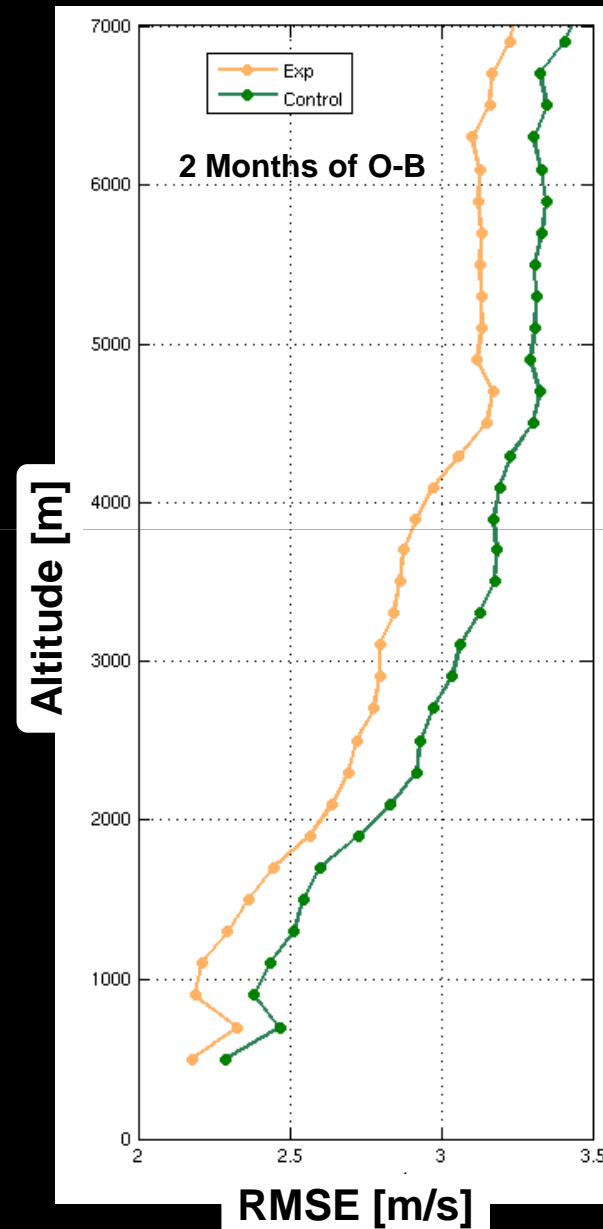
$$\theta_3^2 = 1^\circ$$

With ϕ the beam elevation and θ the beam centre elevation.

- **Reflectivity weighting:**

Profile Definition

- -6dB below Bb
- -2dB above Bb
- Bb +10 dB



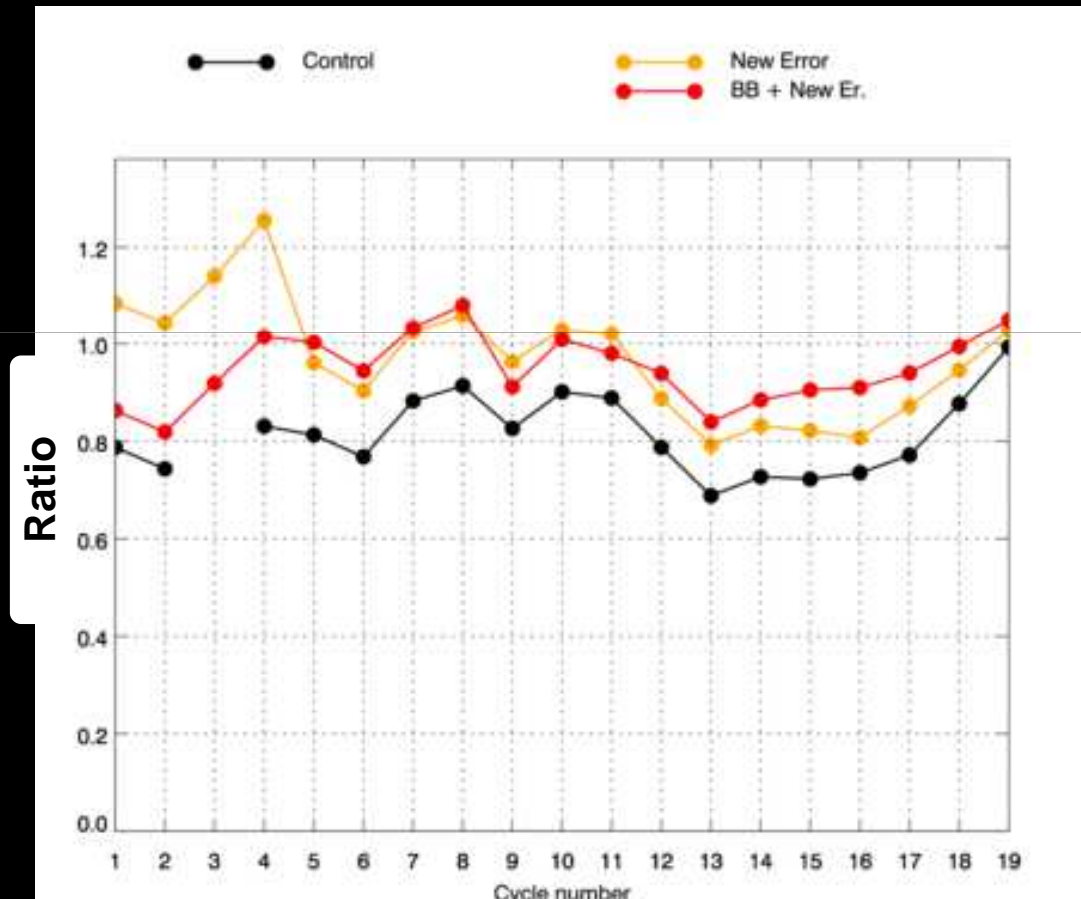


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Results

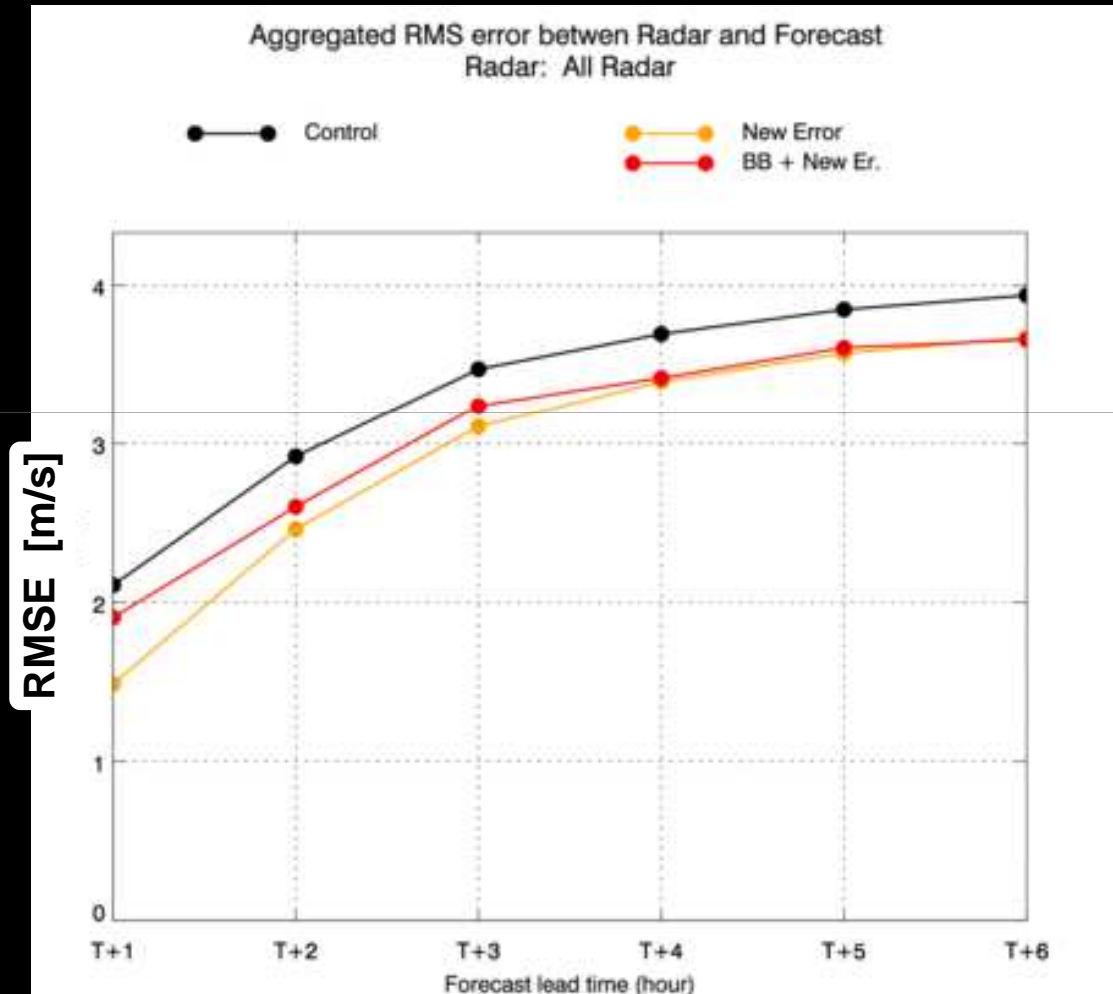
Var Statistics: Bennet and Talagrand Index





Results

Verification: Forecast vs Radial wind





Impact on Precipitation

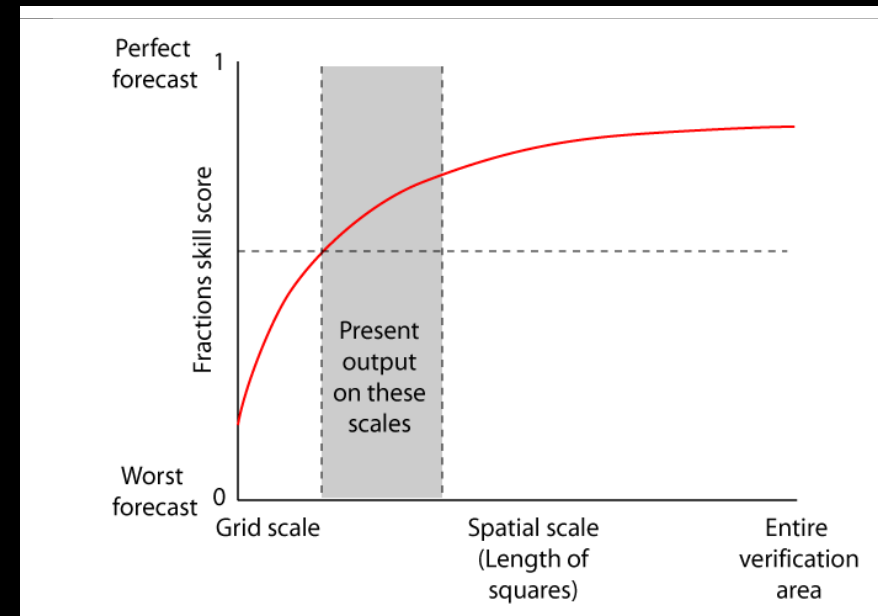
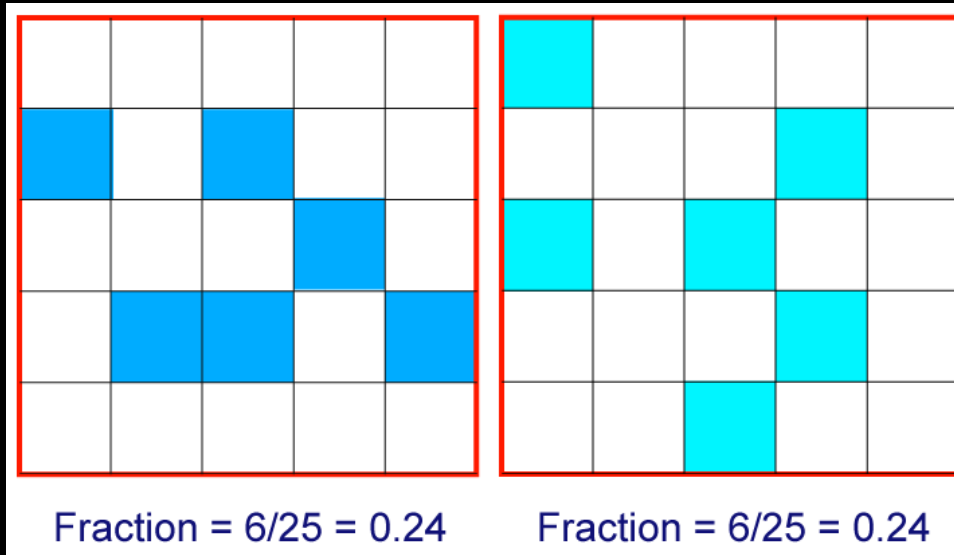
Fraction Skill Score

Scale-selective verification for rainfall accumulations

Comparing the fraction of rainy pixels for a given acc. threshold between Radar and model field at a given scale

Radar

Model

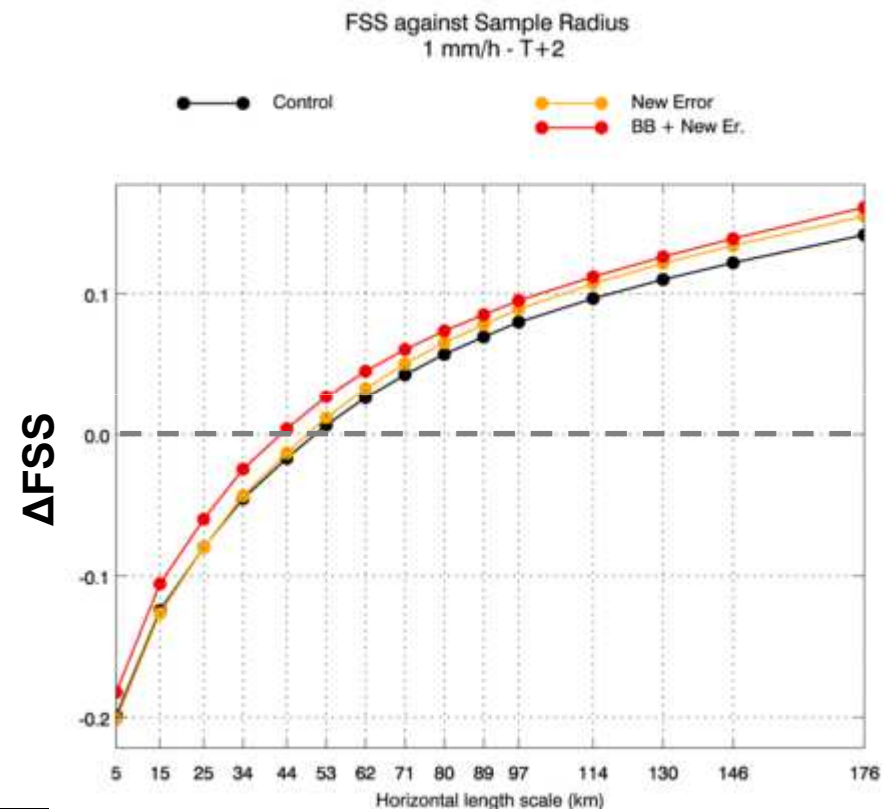
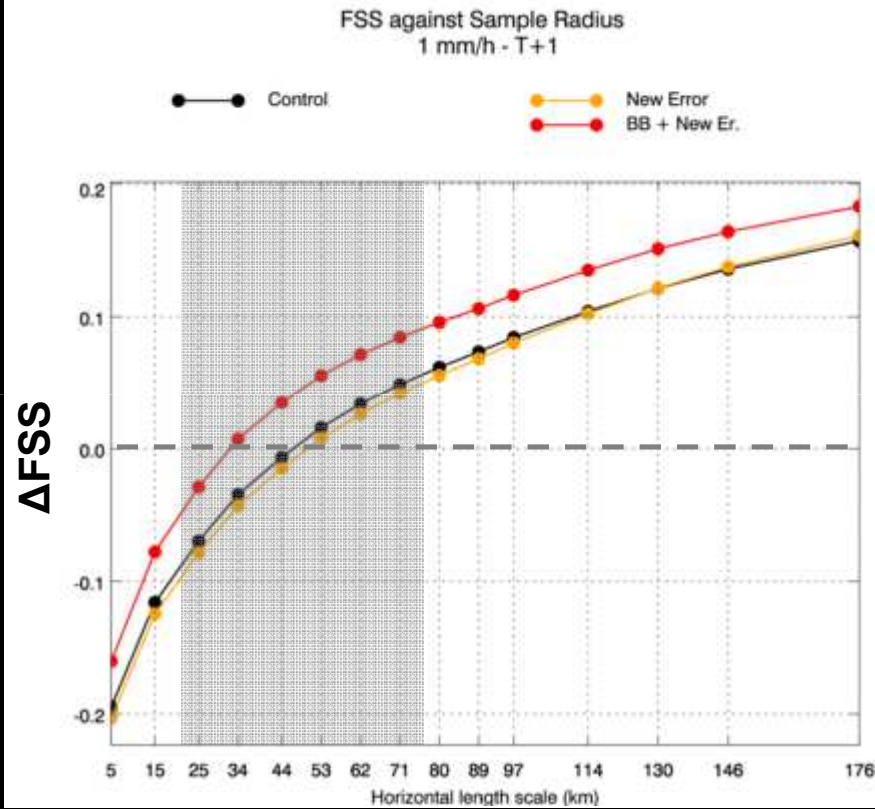


Roberts, N. M. & Lean, H. W. (2008)



Results

Impact on Precipitation

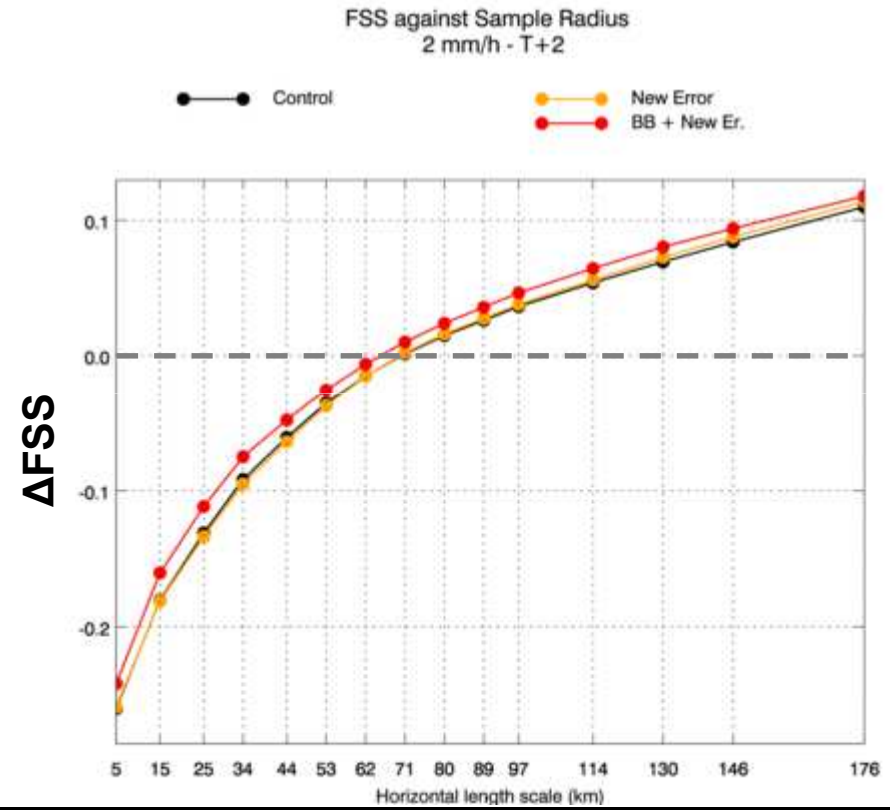
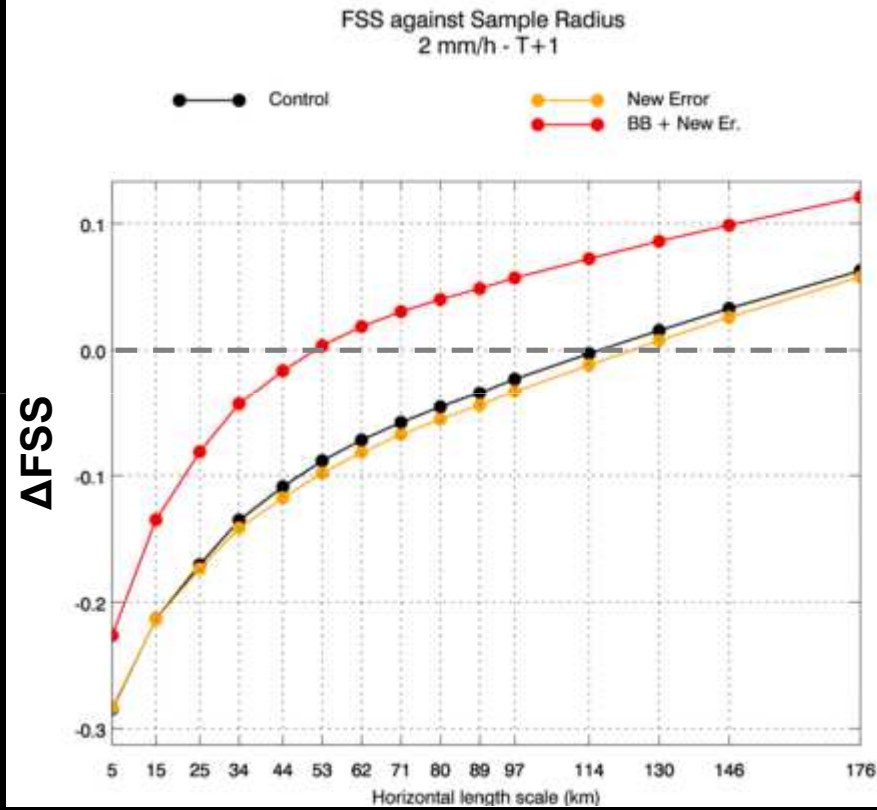


Scale of interest



Results

Impact on Precipitation



© Crown copyright Met — Control — New Error — New Obs Op. + New Er.



Conclusion

- New and more realistic observation operator for Doppler radial wind
- New definition of the observation error for Doppler radial wind

Assimilation

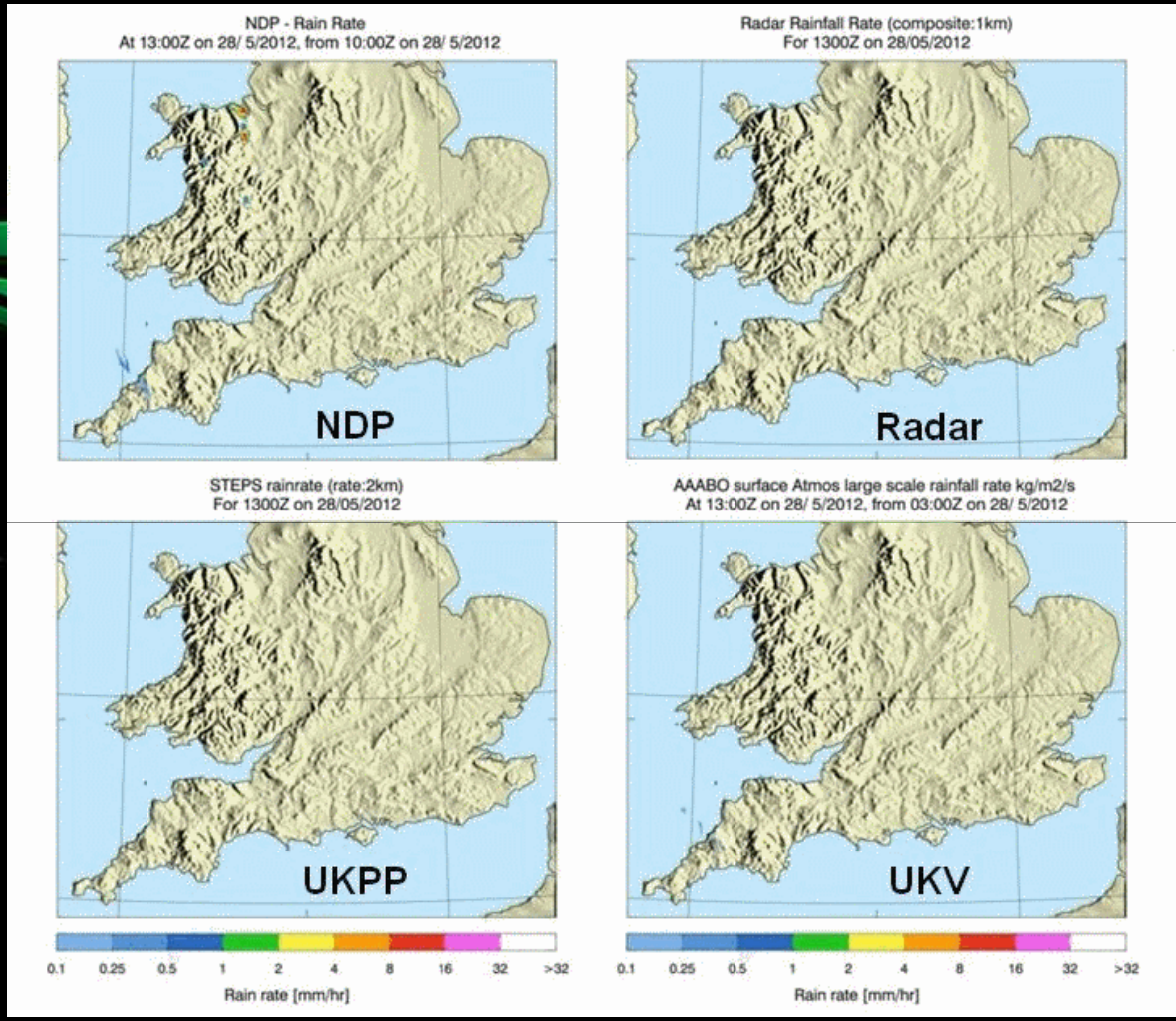
- No extra cost
- More balance

Forecast

- Positive impact on precipitation up to T+2/T+3
- Improvement at low predictability scale



Questions?



NDP run @ 10:00 Z on the 28th June 2012
From T+3 to T+6