





- 1. 1D+3DVar assimilation method of reflectivity
  - Strength of the method
- 2. Estimates of spatial observation-error characteristics
  - Context
  - Methods and results
  - Conclusion and prospect
- 3. Attempts to assimilate X-band radars of the Rhytmme project
  - Rhytmme project context and experimental setup
  - Analysis and forecast impact
  - Prospect



## Outline

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Production of rain by moistening

Saturation in rainy areas









Production of rain by moistening

• Symetrically, use of « no-rain » information to remove rain by drying

Drying thanks to the observed valid non-rainy pixels



Toujours un temps d'avance





roujours un temps u avance

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## Cost function of the 3DVar:

$$J(x) = \frac{1}{2} (x - x_b)^T \mathbf{B}^{-1} (x - x_b) + \frac{1}{2} (y^o - H(x))^T \mathbf{R}^{-1} (y^o - H(x))$$

#### R to be specified: standard deviation of obs. error and covariances

- Instrumental error, calibration error, representativity error, errors on observation operator, quality control
- $\Rightarrow$  Induce spatial correlations a priori to be included in R matrix

## But currently R is diagonal in the system !

Thinning to counteract possible spatial error correlations: only 1 obs. per box of 16 km x 16 km



## **Questions:**

- Is it possible to revisit the current horizontal thinning?
- Do we need to specify spatial observation-error correlations?



 It depends on the ratio between the length-scales of the background-error (in observation space) and the observation-error correlation (Liu and Rabier, 2002)

Context





- Hollingsworth-Lönnberg method: estimate of the observation-error standard deviation by extrapolation of the (o-g) spatial covariances
  - Main assumptions: ~ linear obs. operator and observation errors are spatially uncorrelated!





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#### **First Method:**

- Hollingsworth-Lönnberg method: estimate of the observation-error standard deviation by extrapolation of the (o-g) spatial covariances
  - Main assumptions: ~ linear obs. operator and observation errors are spatially uncorrelated!





#### Second Method:

- Desroziers's diagnostic to estimate spatial observation and background covariances
- Main assumptions: agreement between specified observation-error and true error covariances, and large differences between FG and Obs. lenght-scales of correlation structures



## **Conclusion and prospect**

• Both methods give similar values for the estimate of the standard deviation of observation-error

- The spatially uncorrelated part of the observation error dominates for separation greater than 10 km. Current thinning scale (15 km) is close to this interval
- To reduce observation interval need to introduce explicitly observation-error covariances in the observation-error matrix

However, unexpected results on spatial correlations: it suggests possible no separation between FG lenght scale and Obs. lenght scale of correlation structures!

## Prospect

- Randomized estimates of HBH<sup>t</sup> to deduce  $R = E(d_b d_b^t) HBH^t$  to be compared to DES's diagnostics
- Similar computations for humidity relative retrievals (from reflectivity) are underway
- ditto to estimate inter-radar correlations: could lead to assimilate more data in areas coveraged by several radars



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## X-band technology and Rhytmme Project Context

- Project to prevent HYdrometeorological Risk in Mediterranean and Mountain areas : *S. Westrelin 11.5, F.Kabeche 6.5, J. Beck 13A.4*
- 4 polarimetric X-band radars to be deployed before 2013
- Improvement of the radar coverage in the Southeast of France
- Complement the S-band radars coverage (less clutter, better in lower rain, but strong rain attenuation, wet radome...)

## Experimental setup:

- Separated impact of radial wind, SPOL and DPOL reflectivity (technical problems from the radar production team)
- Evaluation of Mt-Maurel X-band radar added  $_{_{45^{\circ}N}}$  in the assimilation system (10 elevations)
- Evaluation of
  - ✓ convective rain assimilation (during Autumn 2011)
  - ✓ snow cases (3 weeks January/Febrary 2012)
  - ✓ Convective case studies (July 2011)







## **Doppler Radial Wind**

Triple PRF are needed to get a non-ambiguous velocity around 50 m/s
Ratio of PRF needed to be close to 1 to get such high velocities (important for assimilation purposes)

- Important noise after unfolding of the wind (low PRF)
- Median filter may be insufficiently reliable (oversmoothing if raw data are too noisy). First-guess QC is enhanced: 15 m/s against 20 m/s





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![](_page_19_Figure_5.jpeg)

## 2

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![](_page_20_Figure_5.jpeg)

![](_page_21_Picture_0.jpeg)

## Reflectivity

- Removal of beam-blocked pixels and correction of rain-attenuation up to 15 db
- DPOL reflectivity meaning: clutter removing algorithms and PIA correction of Z<sub>h</sub>
- Use of the differential phase  $\Phi_{DP}$  to estimate the Path Integrated Attenuation PIA:
  - Pixel identified as "RAIN":  $Z_{corr}$  (dbZ) = Z (dbZ) +  $\gamma_{H}$ . $\Phi_{DP}$  : Z corrected !
  - Pixel identified as "NO-RAIN":  $Z_{corr}$  (dbZ)  $\leq$  MDZ (dbZ) +  $\gamma_{H}$ . $\Phi_{DP}$

Extinction : Minimum Detection Reflectivity is enhanced: 40 dbZ !

![](_page_21_Figure_8.jpeg)

![](_page_22_Picture_0.jpeg)

### Reflectivity

![](_page_22_Figure_2.jpeg)

## Prospect

 $\Rightarrow$  X-band polarimetric Mt-Maurel radial wind and reflectivity monitored in AROME parallel E-suite

 $\Rightarrow$  Real-time assimilation of radial wind in AROME-WMED SOP1 (Autumn 2012) of the Hymex Project

## Limitations:

 $\Rightarrow$  Improvement of radial wind quality is required to have a better impact on the model

 $\Rightarrow$  Dual-polarisation PIA correction absolutely necessary to assimilate the reflectivity

 $\Rightarrow$  No shown added value by DPOL reflectivity assimilation

## **Questions:**

- $\Rightarrow$  PIA correction used too far away from the radar?
- $\Rightarrow$  Can the high non ambiguous velocity required for assimilation be revisited?

## © Question: Can X-band radar be propitious for our current assimilation systems?

![](_page_24_Figure_0.jpeg)

![](_page_25_Picture_0.jpeg)

## Strength of the 1D+3DVar method: original quality control

• What happens if the model doesn't contain enough consistent thermodynamic profiles with the observed « radar »reality?

• Artificially saturation (or dryness) unwanted (because of humidity positive biais)

![](_page_25_Picture_4.jpeg)

![](_page_26_Picture_0.jpeg)

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![](_page_26_Picture_5.jpeg)

![](_page_27_Picture_0.jpeg)

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![](_page_27_Figure_5.jpeg)

![](_page_27_Picture_6.jpeg)

![](_page_28_Picture_0.jpeg)

1D+3D-Var methodology

![](_page_28_Figure_2.jpeg)

![](_page_29_Figure_0.jpeg)

![](_page_30_Figure_0.jpeg)

![](_page_31_Figure_0.jpeg)

![](_page_32_Figure_0.jpeg)

Convection better analyzed and forecasted in Soutwest of France

![](_page_32_Picture_2.jpeg)

![](_page_33_Figure_0.jpeg)