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Background

When radar measurements are interpreted quantitatively we always use a model microphysics of the backscattering targets.

Model microphysics is an approximation to a very complex reality

There is never sufficient information in radar measurement to resolve unambiguously the complexity of microphysics.

Thus, whatever model we use there will be a good deal of uncertainty in the quantitative interpretation of radar measurements.

Radar measurements are not proper measurements without a good assessment of their uncertainties.

In radar data assimilation this is particularly fundamental.

And all this applies to satellite measurements as well

What do we call a Retrieval

Inference of atmospheric parameters from observations related but not equal to the parameters of interest.

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Simplest example:
$$M = \frac{\pi}{6} \rho_w \int_0^\infty D^3 N(D) dD$$
; $Z = \int_0^\infty D^6 N(D) dD$

N(D) has a good deal of natural variability

Each combination of the possible values of the parameters leads to one set of physical relationships and to one corresponding retrieval.

Simplest example:

$$N(D) = N_0 D^{\mu} \exp(-\lambda D)$$

for a given set of possible values of N_0, μ, λ

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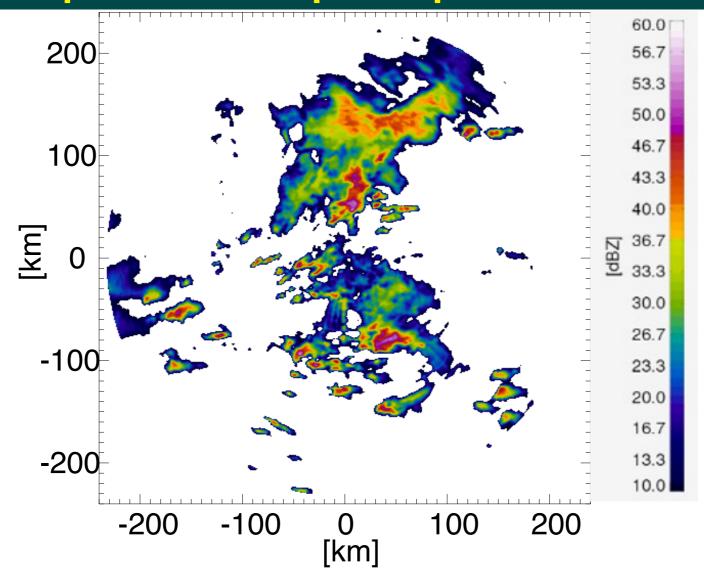
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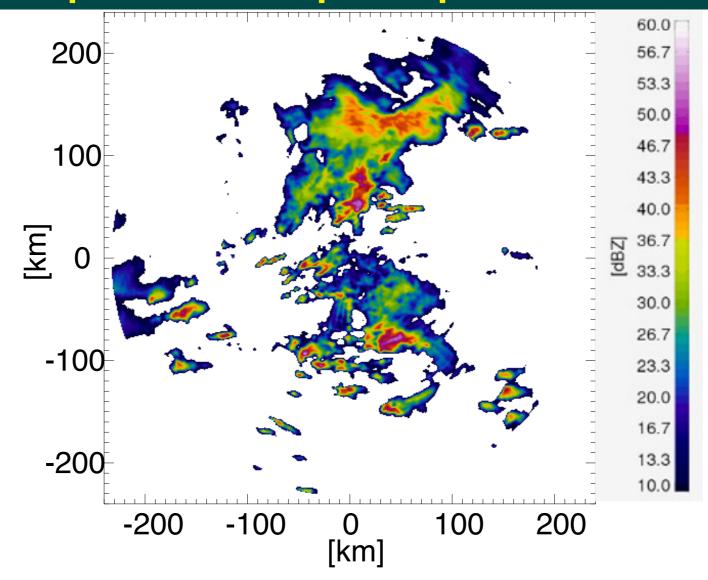
In our simplest example, the Z-M relationship, as an alternative we can use a set of observed DSDs to generate the ensemble.

A particular precipitation event



From our entire disdrometer data base we select the days which the DSDs records had maximum values of dBZ and durations compatible with this particular case, namely a mixture of convection and wide spread rain. We have ~200 days of DSD data of this type of events.

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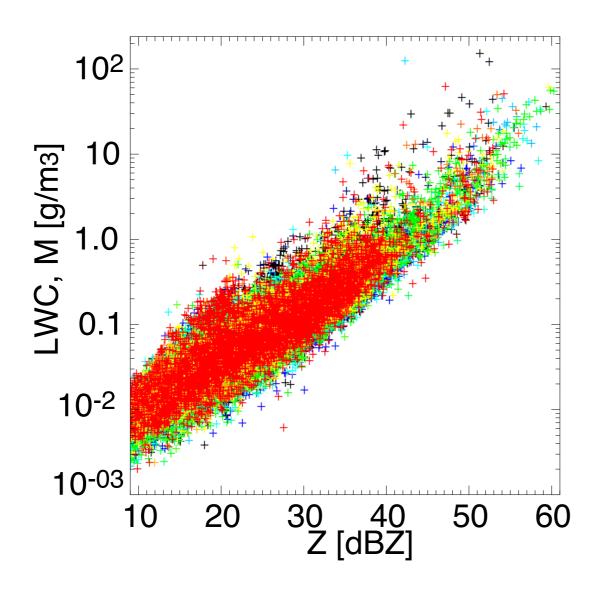


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We treat the 200 days as equiprobable realizations of the same process

Data Base

From the 200 days of distrometric records we have this distribution of logM versus logZ



Typically an average Z-M relationship, obtained by some kind of regression, is used in retrieving M from Z.

Let us apply ensemble retrieval to this problem.

Example

Here we formulate the retrieval of M as

$$M = \int m \ p(m \mid [Z \pm \delta]) \ dm$$

Let us take $\delta = 0.5 \text{ dB}$

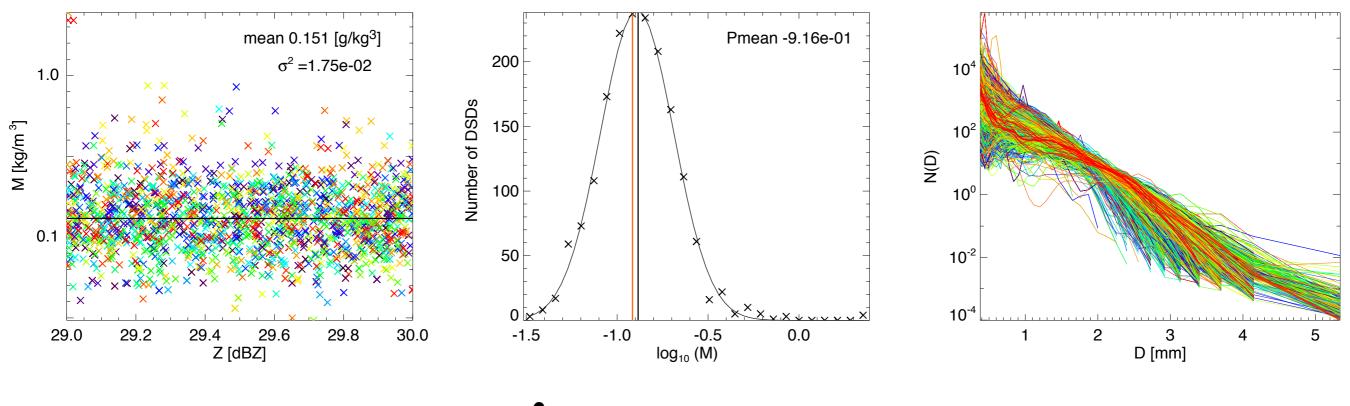
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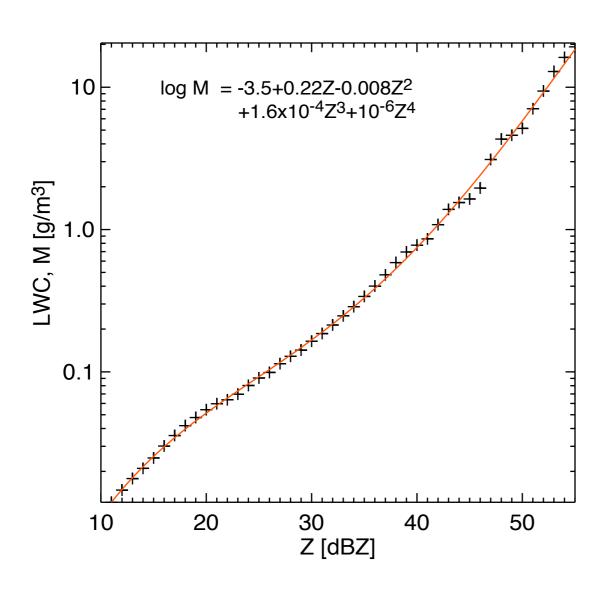
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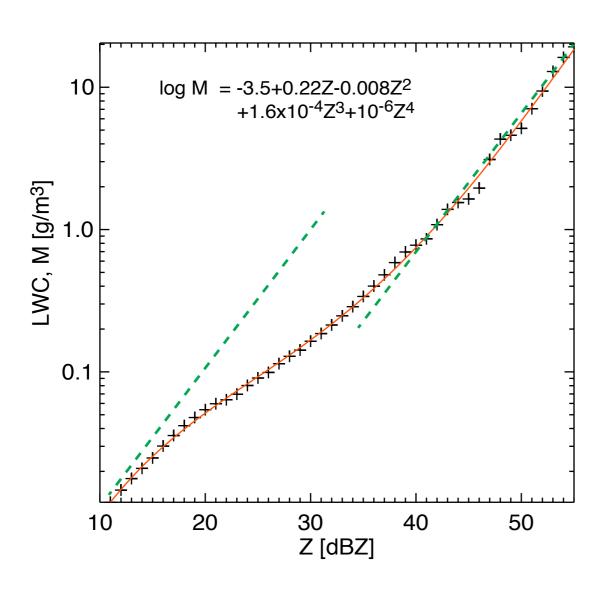


$$M = 0.15 = \int m \ p(m \mid [29 - 30 \, dBZ]) \, dm$$

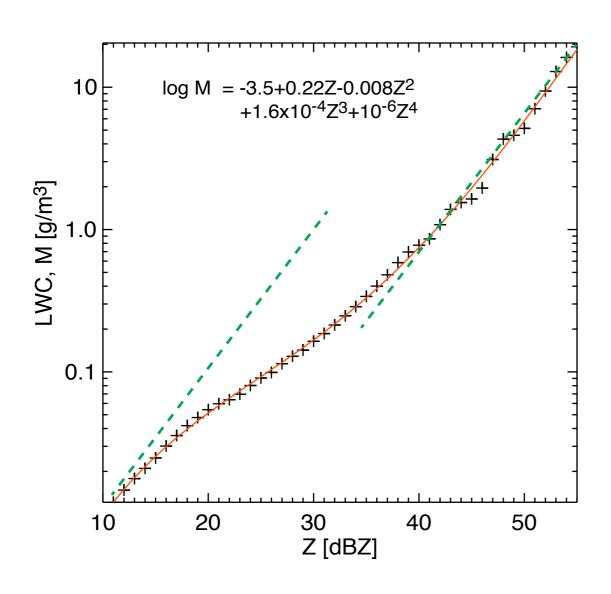
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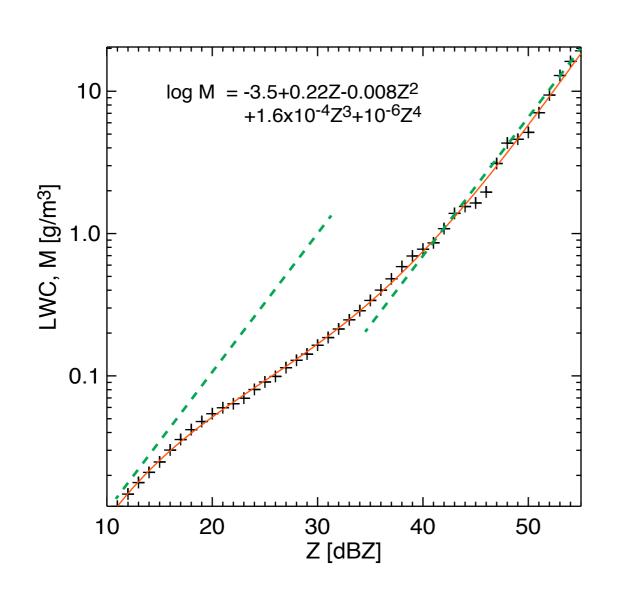
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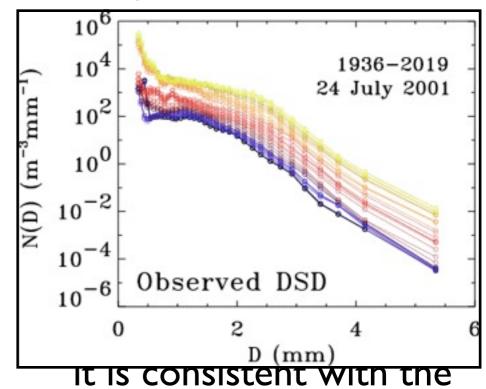


Some small progress here!

We get a more complex relationship that in fact has some physical sense: it is consistent with the tendency to equilibrium DSDs at Z>40dBZ and the expected behaviour at very low rates where cloud collection is the prevailing mechanism of precipitation growth

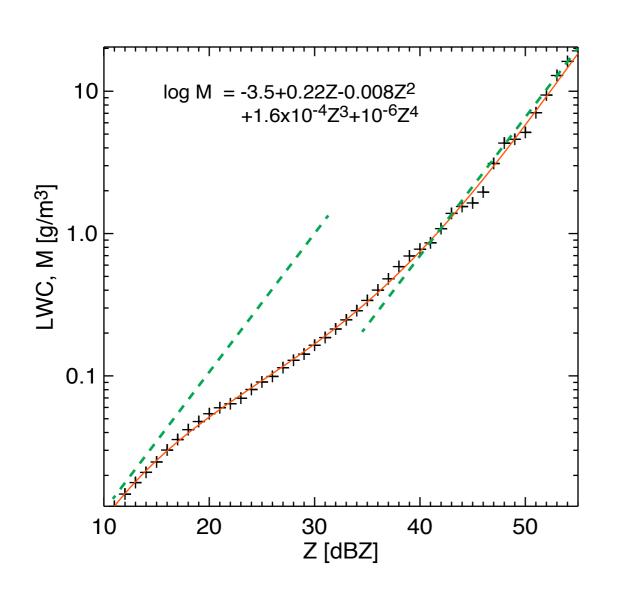
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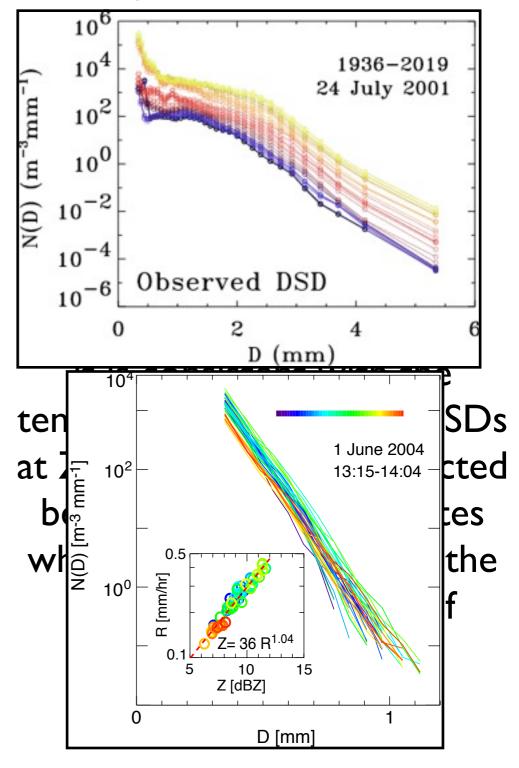




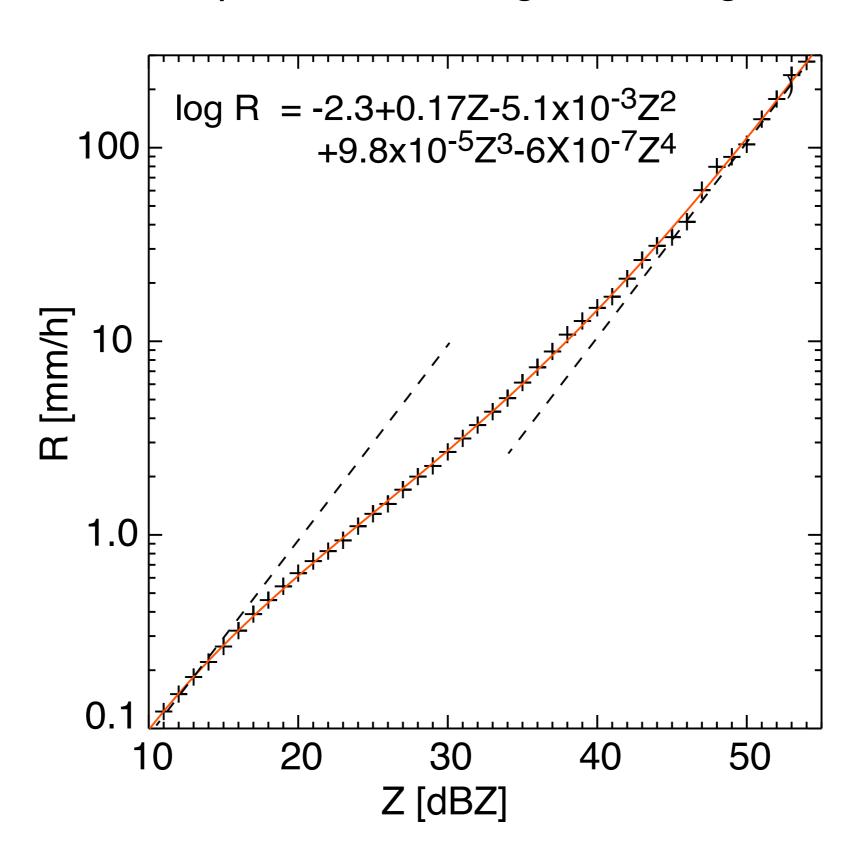
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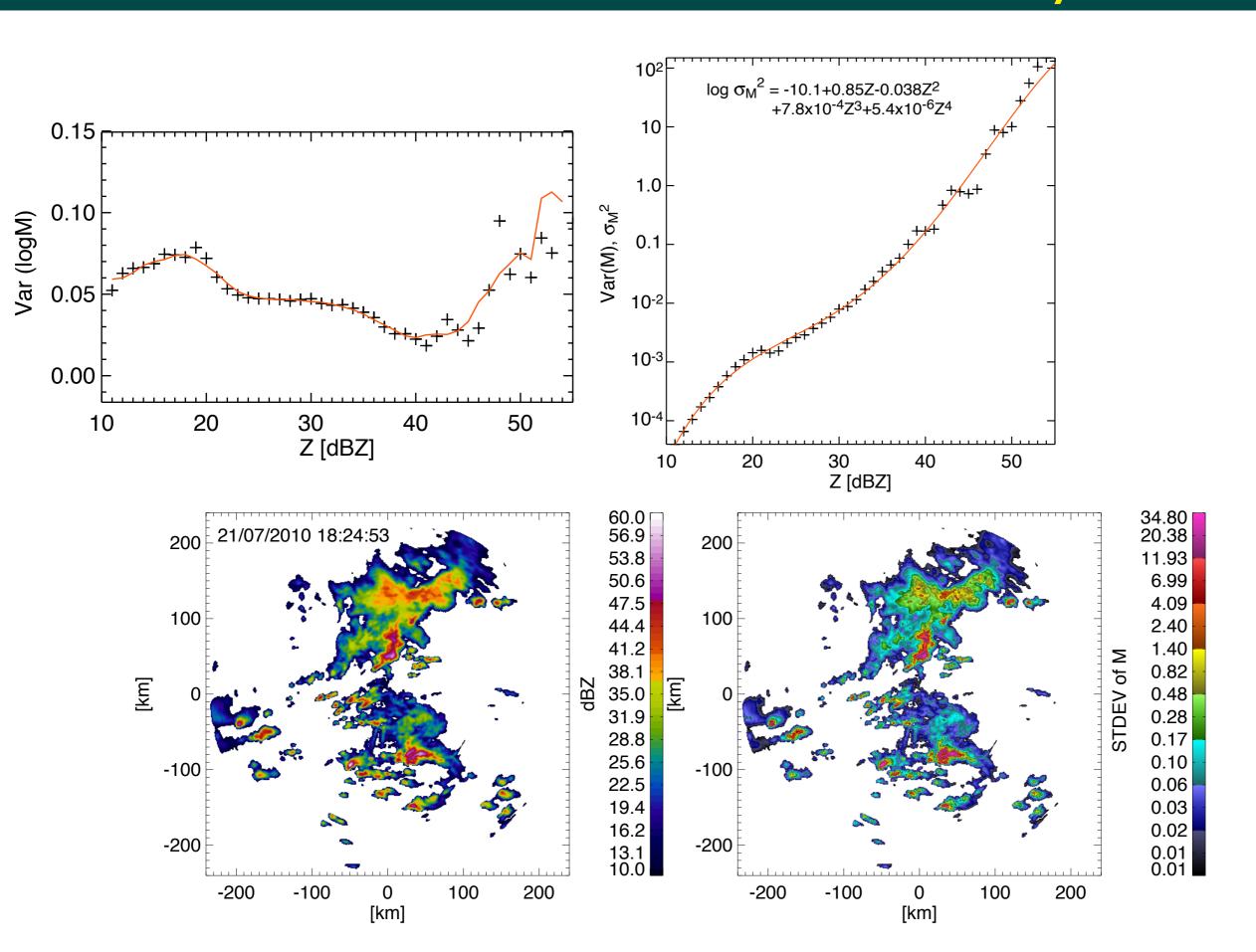




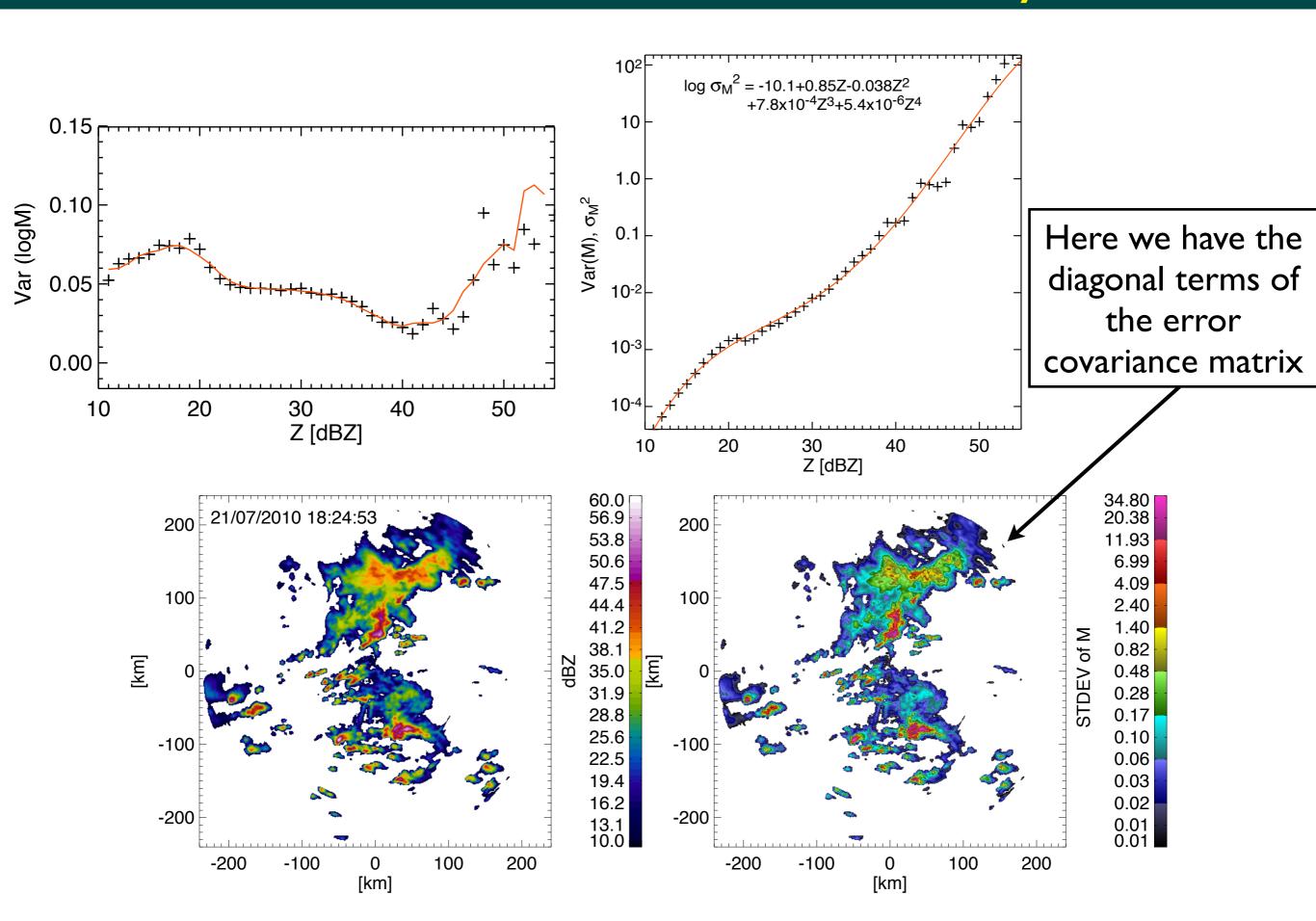
From our sample of 200 days of disdrometric records we have this expected value of logR versus logZ



Variance is a function of intensity

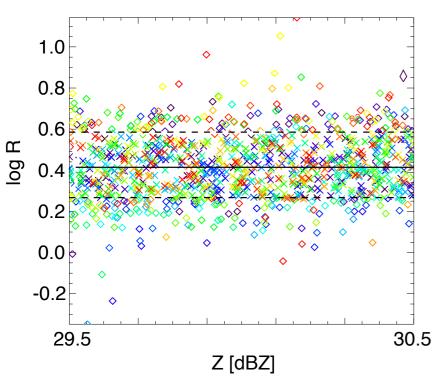


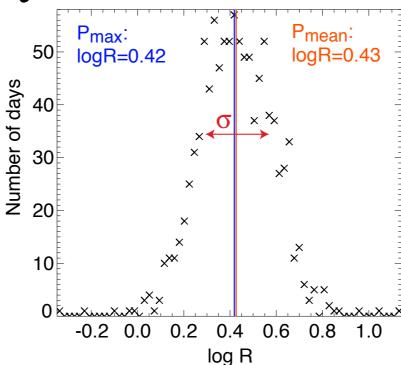
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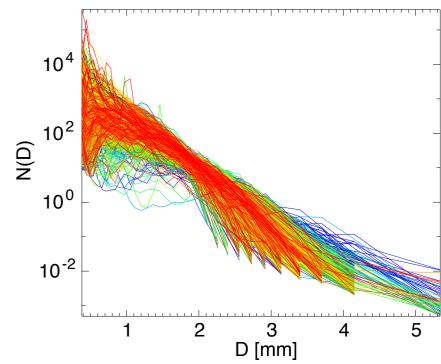


Extremes (shown here for logR)

$$\log R = \int \log r \ p(\log r \mid dBZ \pm \delta) \ dr$$

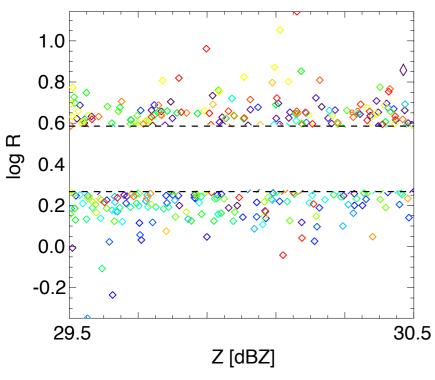


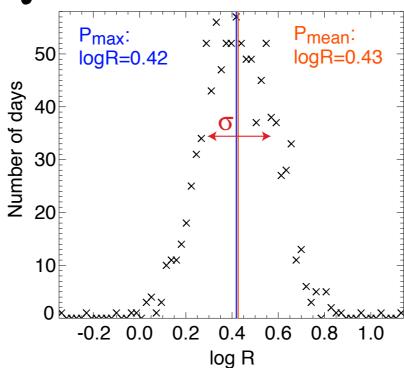


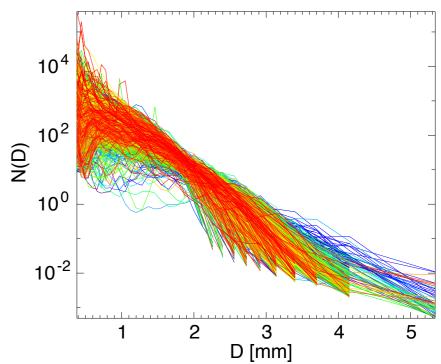


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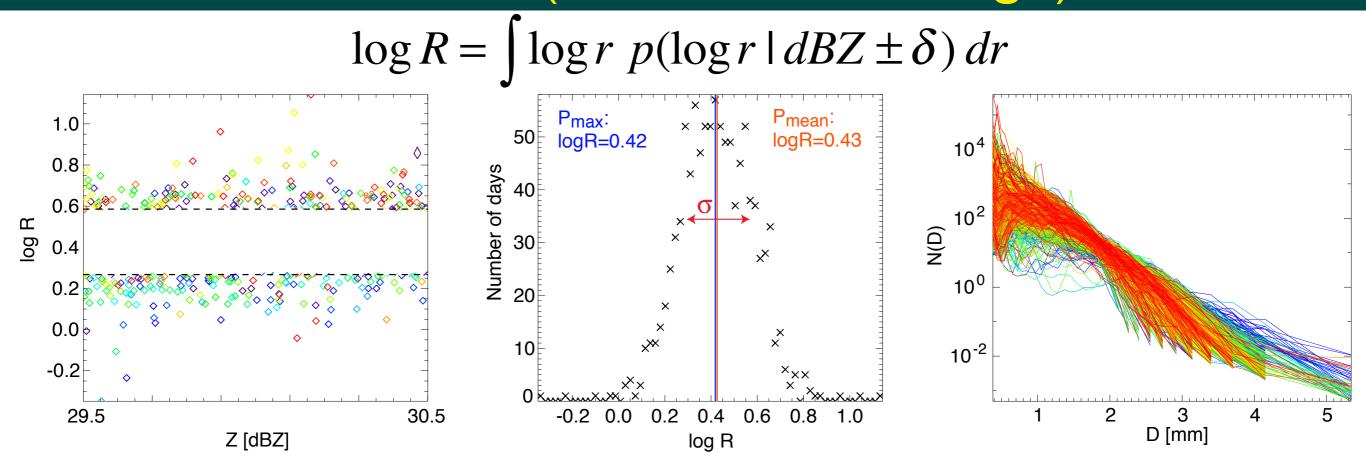
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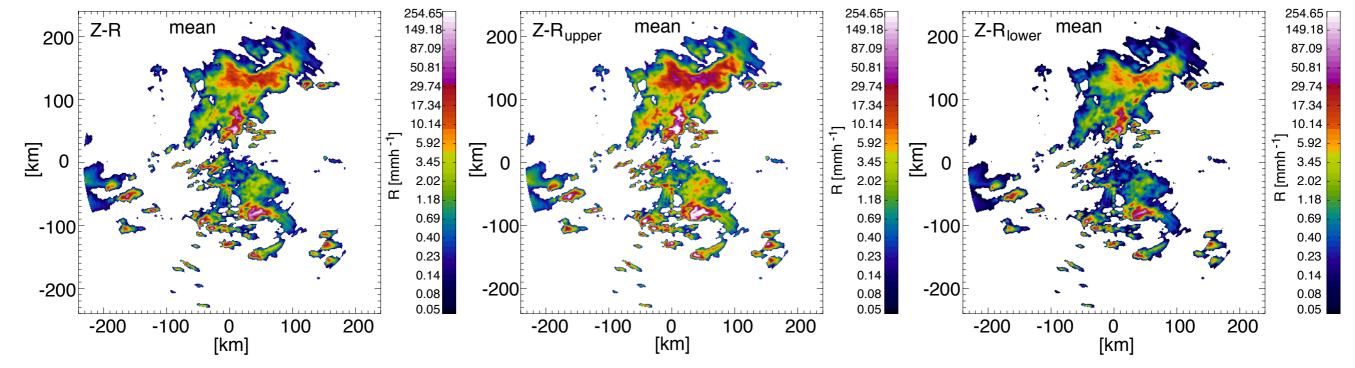




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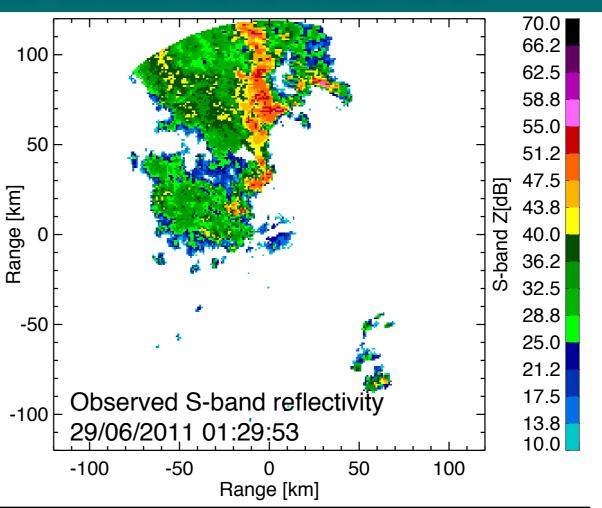


Here are some extreme members of the ensemble. The last two are averages of all possibilities outside the SD of the entire population



A more complete ensemble member

A single Z-R relationship smoothes-out existing variability in rain rate and eliminates high values

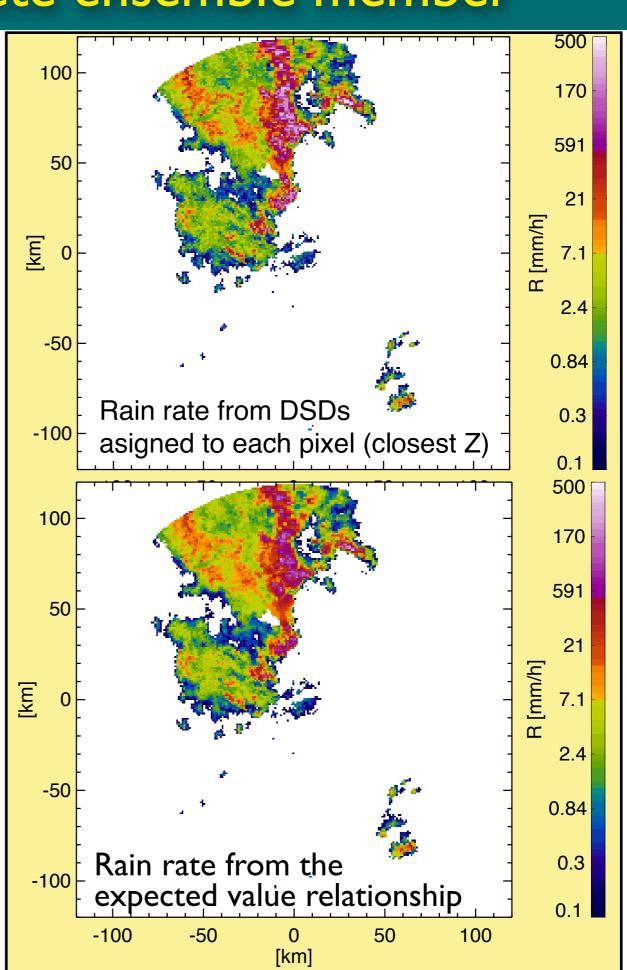


For each pixel take a DSD with the closest Z, selected from a sample of 34000 of spectra taken during convective situations (max. Z > 42dBZ).

For the selected DSD compute R for that pixel.

A more complete ensemble member

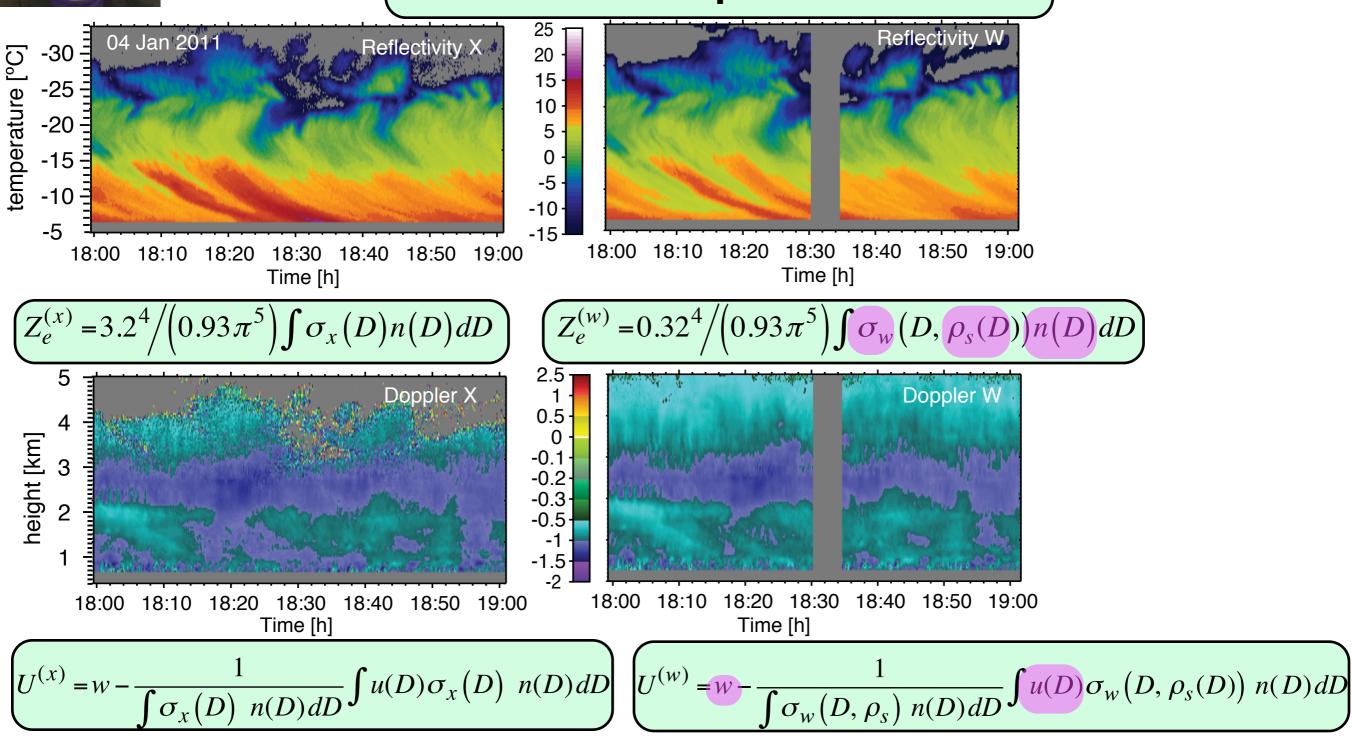
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Observations

and their representation



four measurements and four equations, but...

Observations

$$DWR = dBZ_e^{(X)} - dBZ_e^{(W)}$$
 $DDV = V^{(X)} - V^{(W)}$

Observation are considered with their uncertainty interval. Thus, a microphysical model descriptor satisfies an observation if it falls within its uncertainty interval.

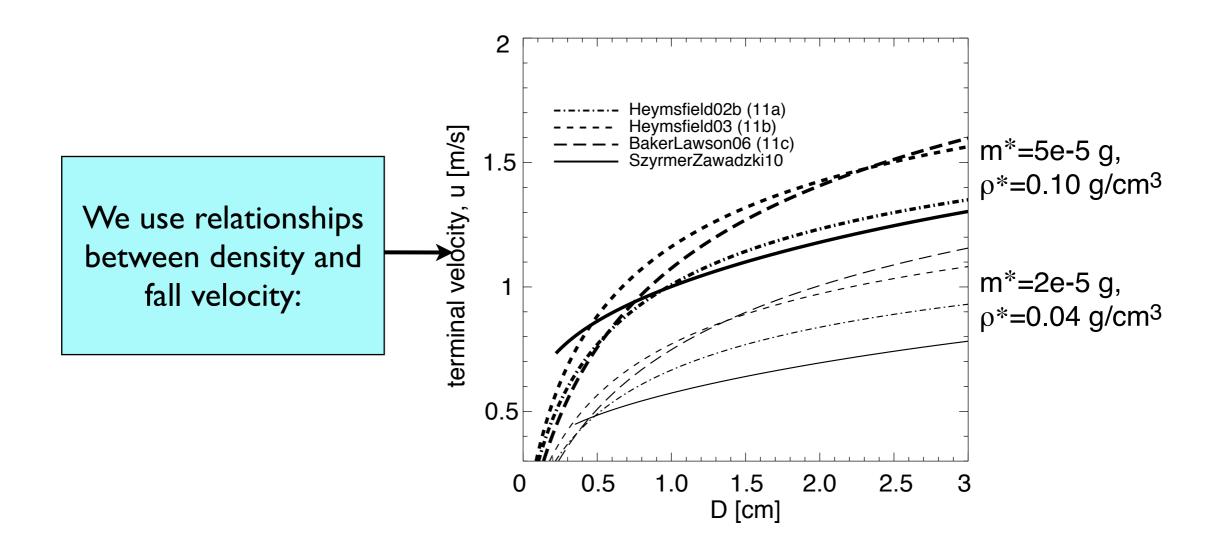
Here we formulate the retrievals as

$$N_0^* = \int n_0^* p(n_0^* | [DWR \pm \delta_{\Delta Z}], [DDV \pm \delta_{\Delta U}], [U_D^{(X)} \pm \delta_{Ux}], [dBZ^{(X)} \pm \delta_{Zx}]) dn_0^*$$

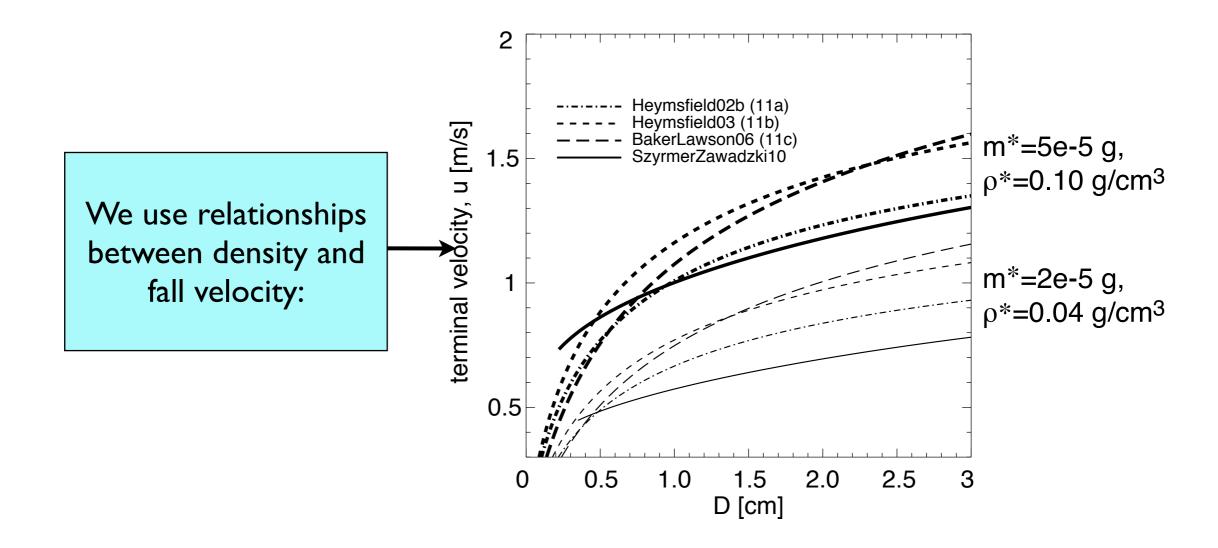
for every combination of model descriptors. And 3 similar equations for ρ^* , $D_{2,3}$, IWC



Uncertainties in fall velocity representation

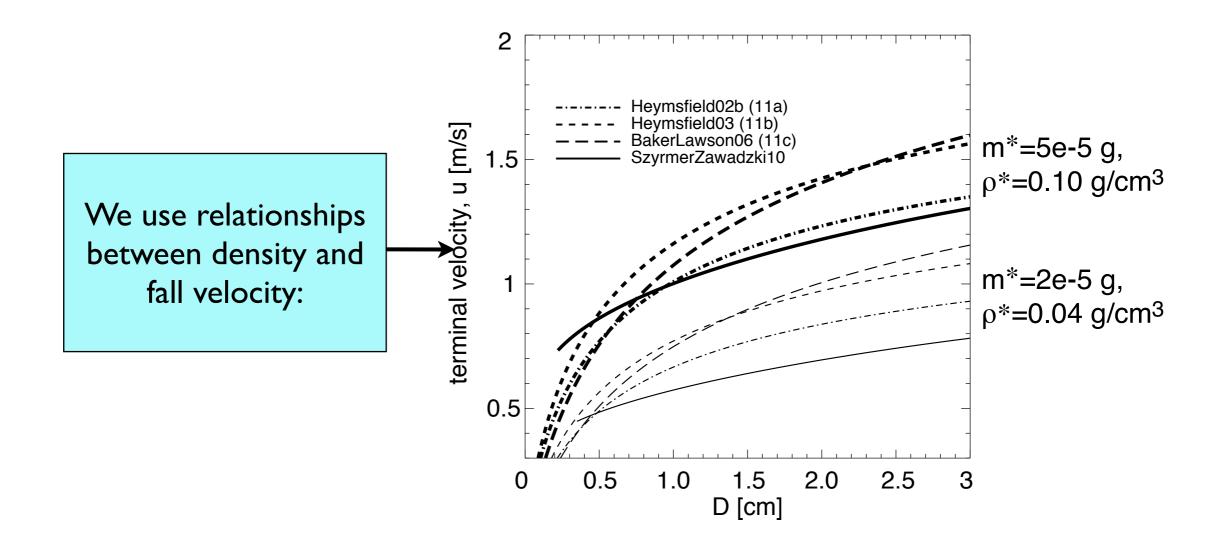


Uncertainties in fall velocity representation



The uncertainty of the model is represented by all combinations of various functional size distributions and velocity-mass relationships.

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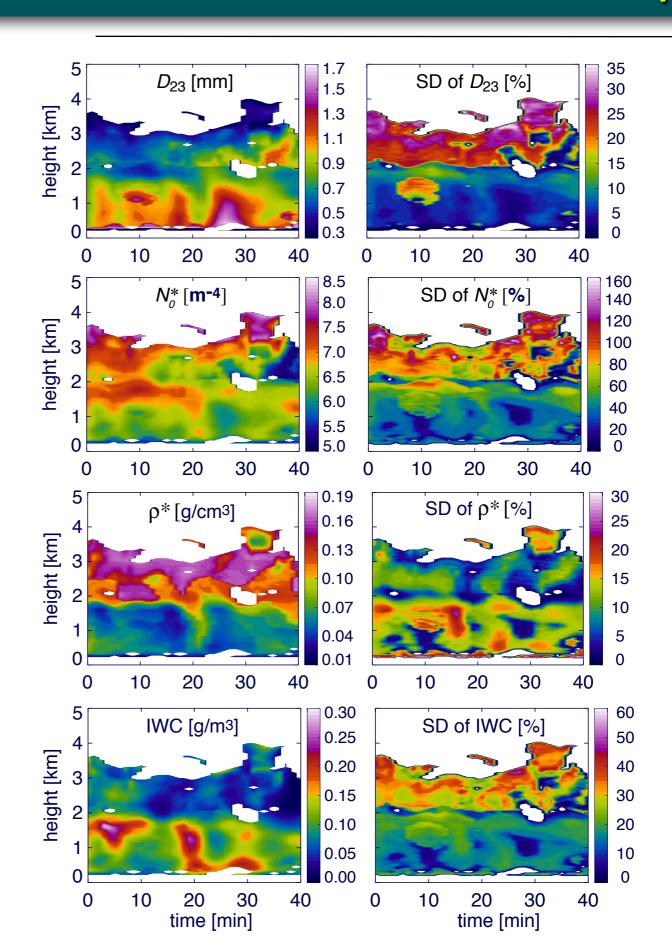


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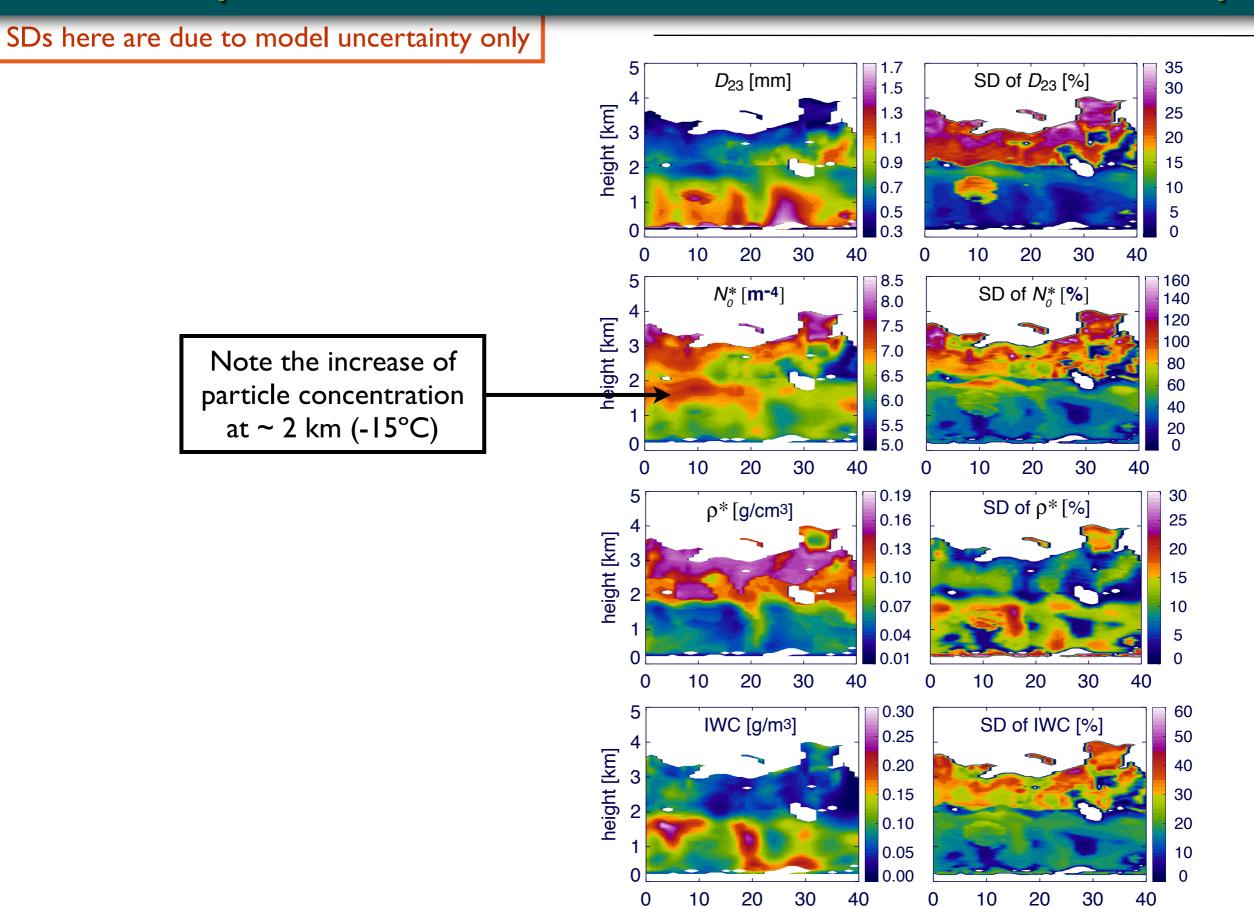
All of the possible combinations of relationships are used as perturbations of the model and are assumed here to be equiprobable

Results: Expected values and SDs of retrieved snow descriptors

SDs here are due to model uncertainty only



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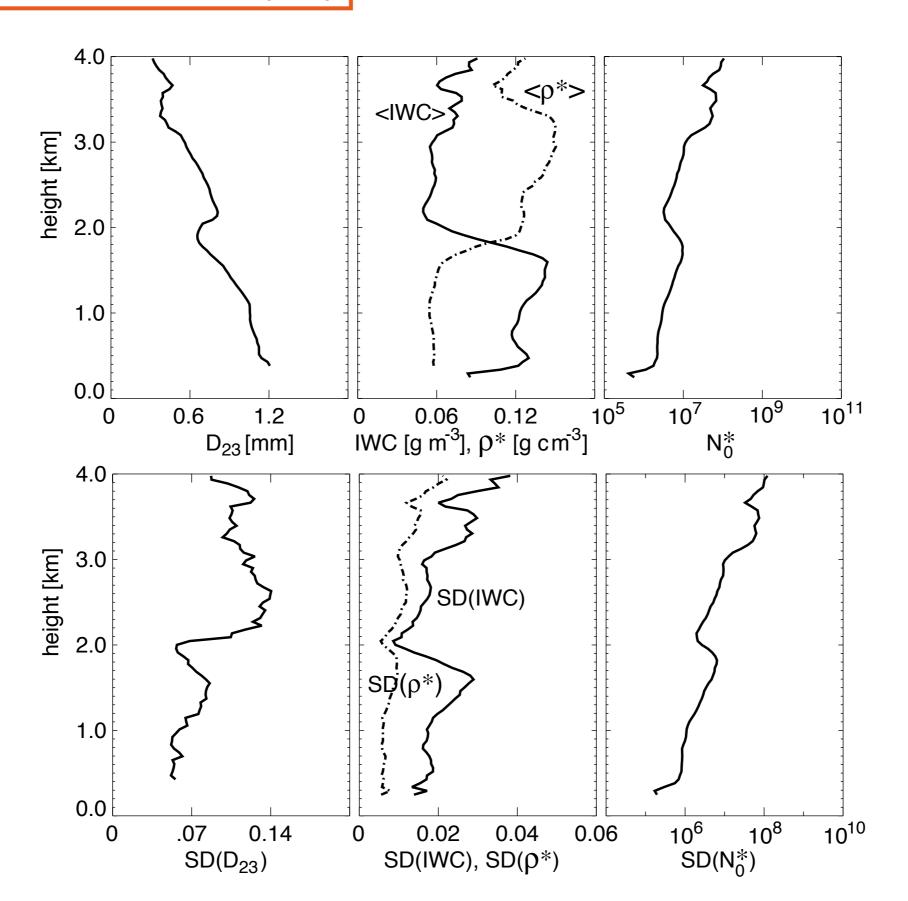


time [min]

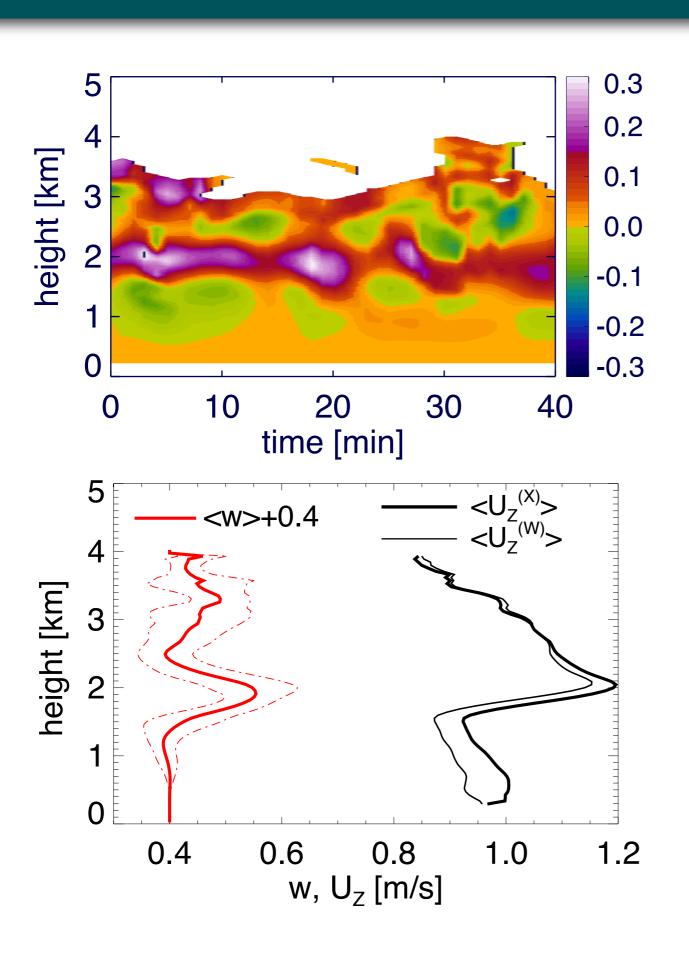
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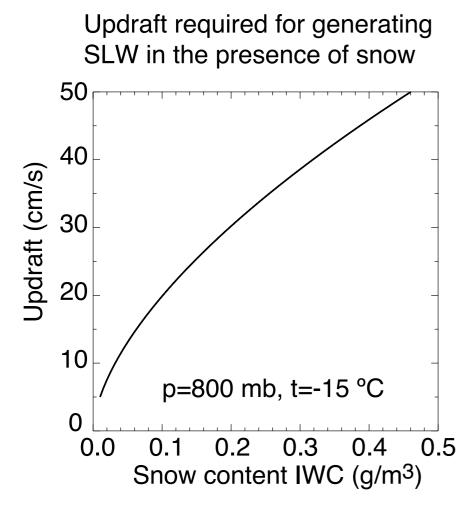
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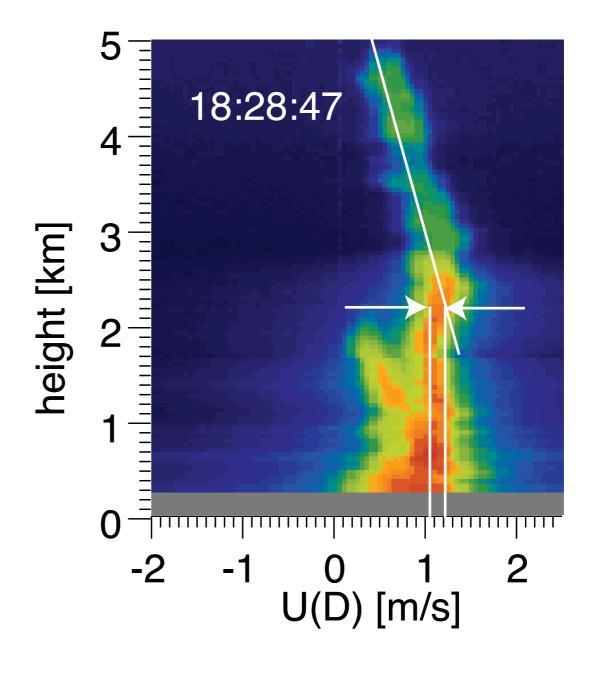


Results: Vertical air motions



Verification





Ensemble retrievals reduce biases

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Give information on the error covariance matrix

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There is no reason for not doing things this way