

LOCALIZATION OF THE ENSEMBLE COVARIANCES USING THE DIFFUSION OPERATOR APPROACH

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MOTIVATION

1. Schur product of the ensemble covariance with heuristic localization functions

+ computationally cheap

- flow dependence, positive definiteness

2. Enriching the ensemble with Schur cross-products of the ensemble members (Bishop and Hodyss, 2007)

- computationally expensive

+ flow dependence, positive definiteness

3. Approximating the ensemble covariance with a positive function of the diffusion operator

computationally inexpensive

flow dependence, positive definiteness

OBJECTIVE: explore (3) and compare it with (1-2) in terms of accuracy/computational cost in a realistic setting

OUTLINE

1. **The diffusion operator technique**
 - a. Gaussian and spline models*
 - b. Differential method*
 - c. Integral method*

2. **Experimental setting and comparison with adaptive and non-adaptive methods**
 - a. Diffusion tensor model*
 - b. Ensemble generation and error metrics*
 - c. Accuracy*
 - d. Computational efficiency*

3. **Summary**

Localization methods (1)

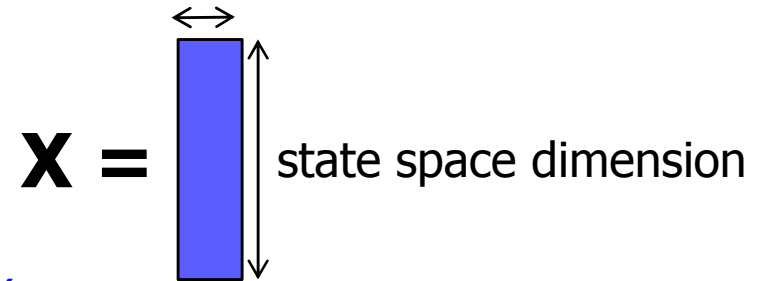
$$\mathbf{B} \equiv \text{COV}\{\mathbf{x}_k\} = \mathbf{X}\mathbf{X}^T$$

$$\mathbf{B}_l = \mathbf{B} \circ \mathbf{W}_d$$

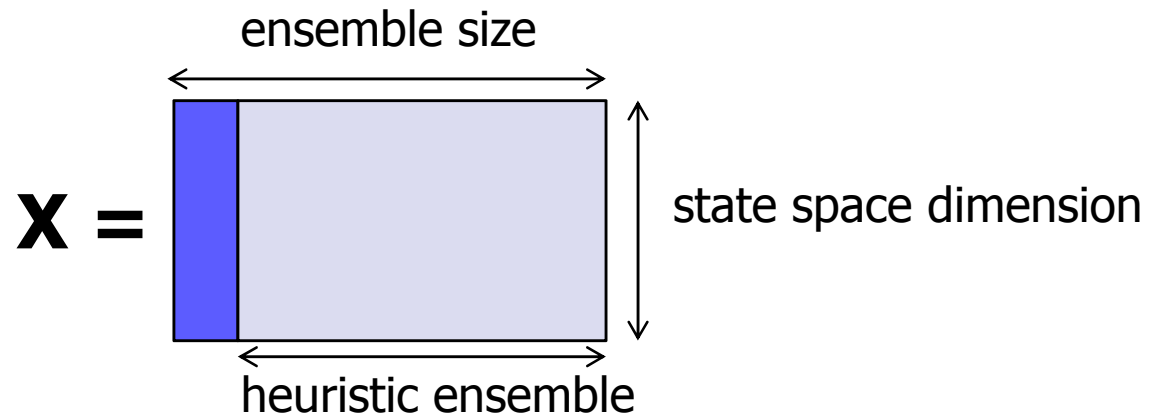
localization matrix

$$\mathbf{B}_l = \mathbf{V}\mathbf{C}_l\mathbf{V}$$

raw ensemble size



adaptive



Diffusion operator (DO) approach

$$\mathbf{B}_l = \mathbf{V} \mathbf{C}_l \circ \mathbf{W}_d \mathbf{V}$$

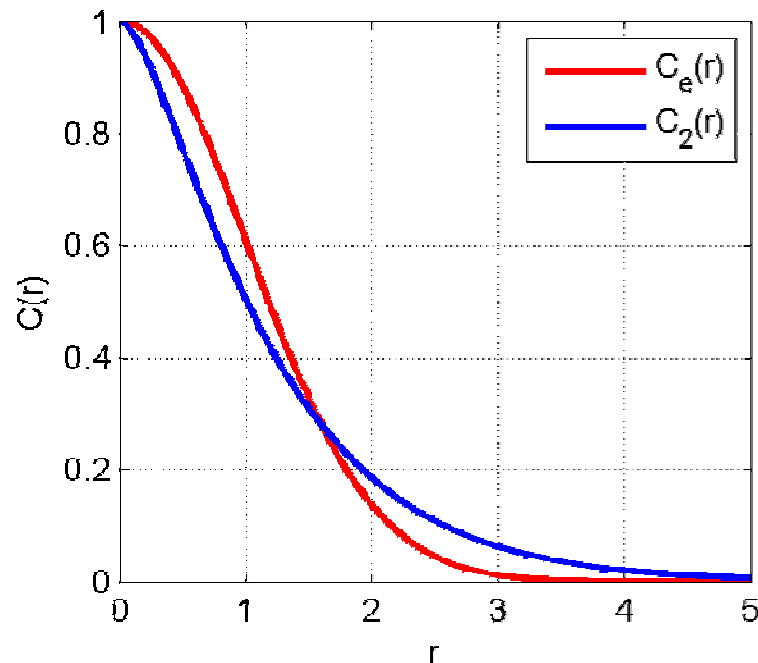
$$\mathbf{D} = -\nabla_\alpha D^{\alpha\beta} \nabla_\beta$$

Gauss: $F_e\{\mathbf{D}\} = \exp\left(-\frac{\mathbf{D}}{2}\right)$

$$\mathbf{C}_l^e(\mathbf{r}) = \exp\left(-\frac{r^2}{2}\right)$$

Spline: $F_n\{\mathbf{D}\} = \left(\mathbf{I} + \frac{\mathbf{D}}{2n}\right)^{-n}$

$$\mathbf{C}_l^n(\mathbf{r}) = \frac{(\sqrt{2nr})^{n-1} \mathcal{K}_{n-1}(\sqrt{2nr})}{2^{n-2}(n-2)!}$$



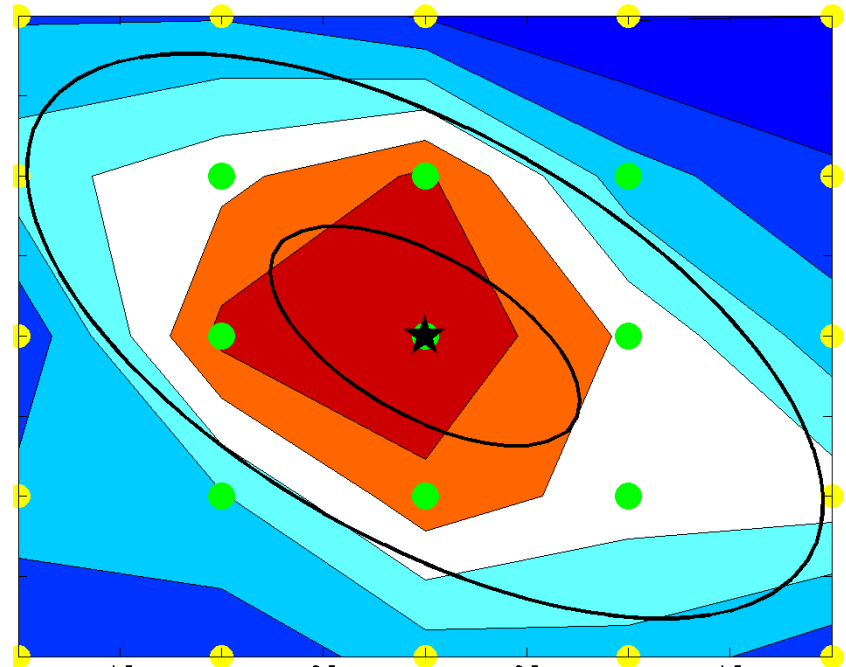
$$\mathbf{r}^2 = r^\alpha D_{\alpha\beta}^{-1} r^\beta; \quad \mathbf{r} = \mathbf{x} - \mathbf{y}$$

DO approach: differential method

$$D_{\alpha\beta}^{-1} = -\frac{1}{a} \nabla_{\alpha} \nabla_{\beta} C(r) \quad a = \lim_{r \rightarrow 0} \frac{1}{r} \frac{\partial C}{\partial r}$$
$$a^e = 1 \quad a^n = 1 - \frac{2}{n}$$

$$[\nabla_{\alpha} \nabla_{\beta} \mathbf{C}] = \frac{\langle (\nabla_{\alpha} \mathbf{x}) \circ (\nabla_{\beta} \mathbf{x}) \rangle - (\nabla_{\alpha} \mathbf{v}) \circ (\nabla_{\beta} \mathbf{v})}{\mathbf{v} \circ \mathbf{v}}$$

Estimate **the inverse of D** from the curvature of the sample correlation matrix at the diagonal



DO approach: integral method

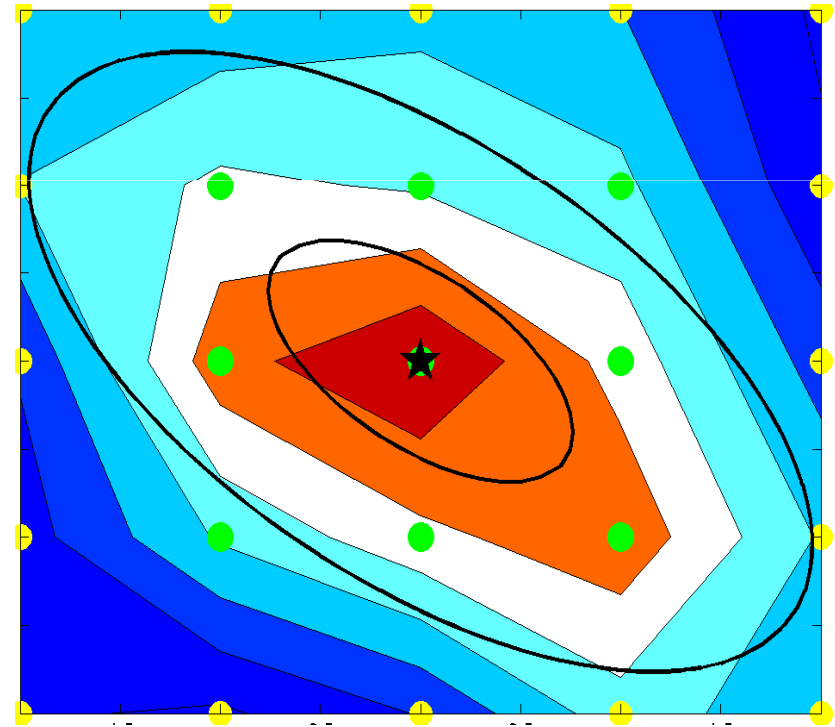
$$J(\mathbf{x}) = \int_{\omega} \left(\mathbf{C}_{\ell}(\mathbf{x} - \mathbf{y}) - \tilde{\mathbf{C}}(\mathbf{x}, \mathbf{y}) \right)^2 d\mathbf{y} \rightarrow \min_{D(\mathbf{x})}$$

$$\mathbf{C}_{\ell}^e(\mathbf{r}) = \exp\left(-\frac{r^2}{2}\right)$$

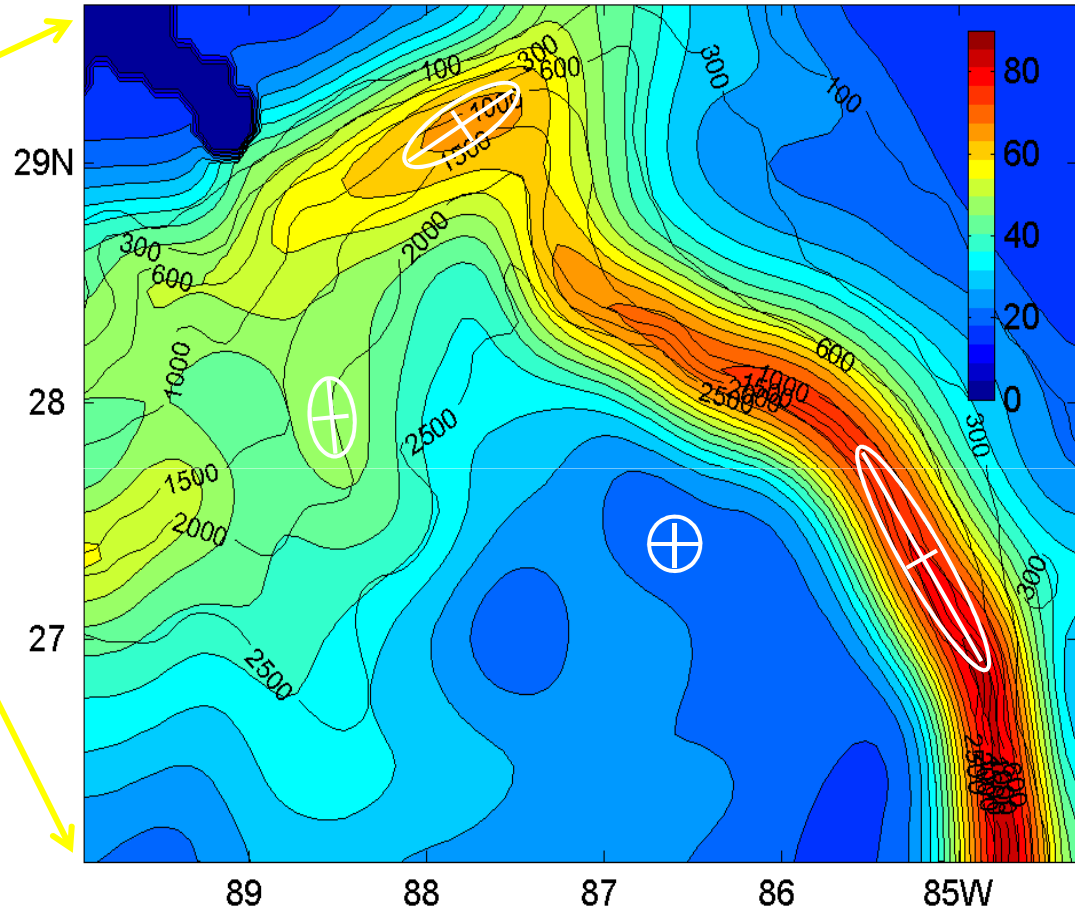
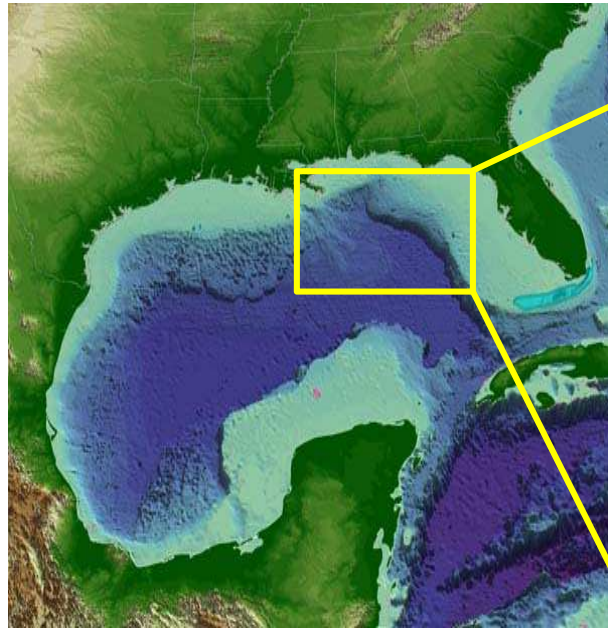
$$\mathbf{C}_{\ell}^n(\mathbf{r}) = \frac{(\sqrt{2nr})^{n-1} \mathcal{K}_{n-1}(\sqrt{2nr})}{2^{n-2}(n-2)!}$$

$$r^2 = r^{\alpha} D_{\alpha\beta}^{-1} r^{\beta}; \quad \mathbf{r} = \mathbf{x} - \mathbf{y}$$

Estimate \mathbf{D} by minimizing the misfit between the sample correlation matrix and its analytic approximation in the given vicinity ω of the diagonal



Diffusion tensor model

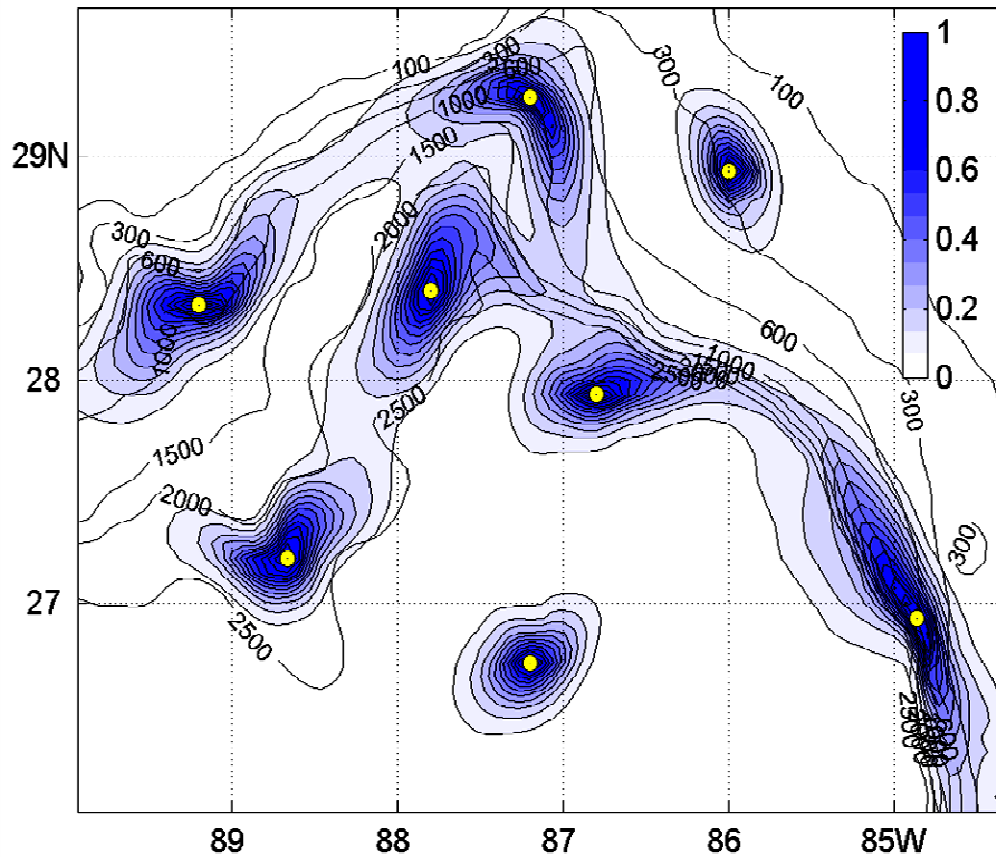


$$\mathbf{D} = \nabla_{\alpha} D^{\alpha\beta} \nabla_{\beta} \quad D = K^T K$$

$$K = \rho_b \begin{pmatrix} \xi & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \cos \gamma & -\sin \gamma \\ \sin \gamma & \cos \gamma \end{pmatrix}$$

$$\xi = \max(1, \sqrt{|\mathbf{u}\tau|/\rho_b}) \quad \tan \gamma = \frac{v}{u} \theta(|\mathbf{u}\tau| - \rho_b)$$

Ensemble generation



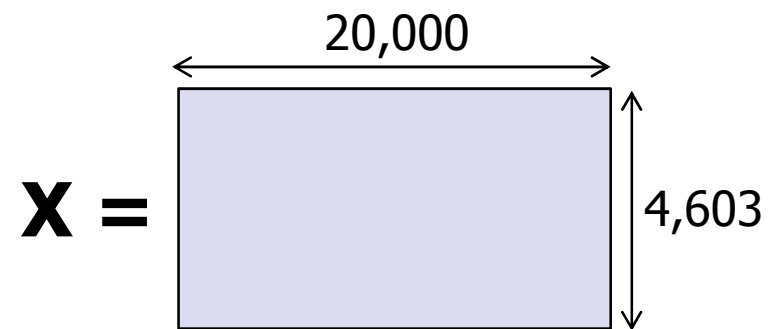
**true correlation
(spline model)**

$$\exp\left(-\frac{\mathbf{D}}{2}\right)\mathbf{x} \simeq \left(\mathbf{I} - \frac{\mathbf{D}}{2n}\right)^n \mathbf{x}$$

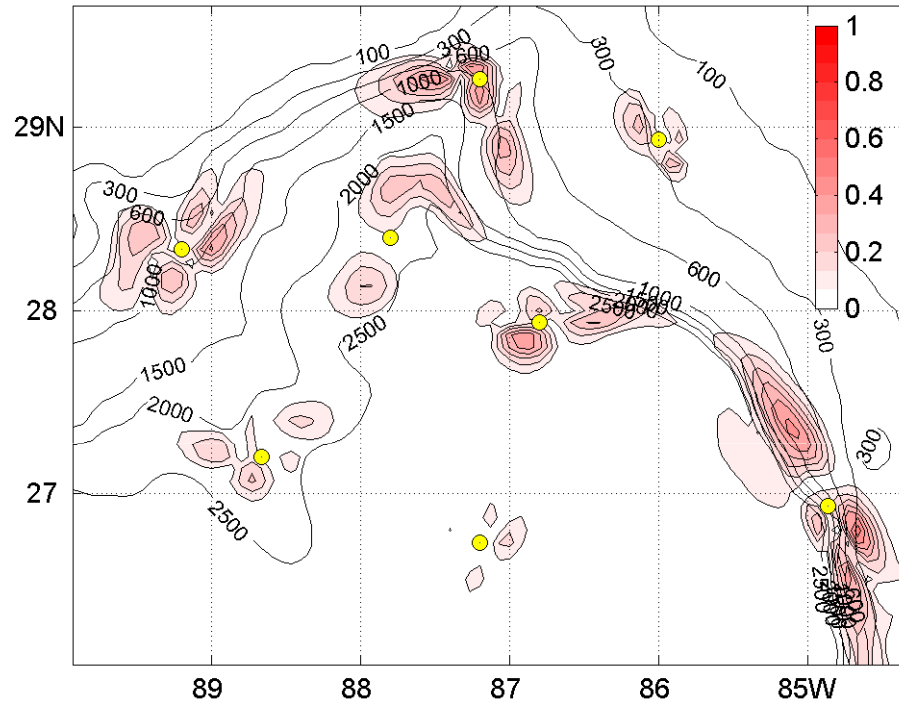
$$\mathbf{C}_\ell^e = (\text{diag } \mathbf{c})^{-1/2} \exp\left(-\frac{1}{2}\mathbf{D}\right)(\text{diag } \mathbf{c})^{-1/2}$$

$$\mathbf{c} = (2\pi)^{-1} \exp\left(-\frac{1}{6}\mathbf{D}\right)(\det \mathbf{D})^{-1/2}$$

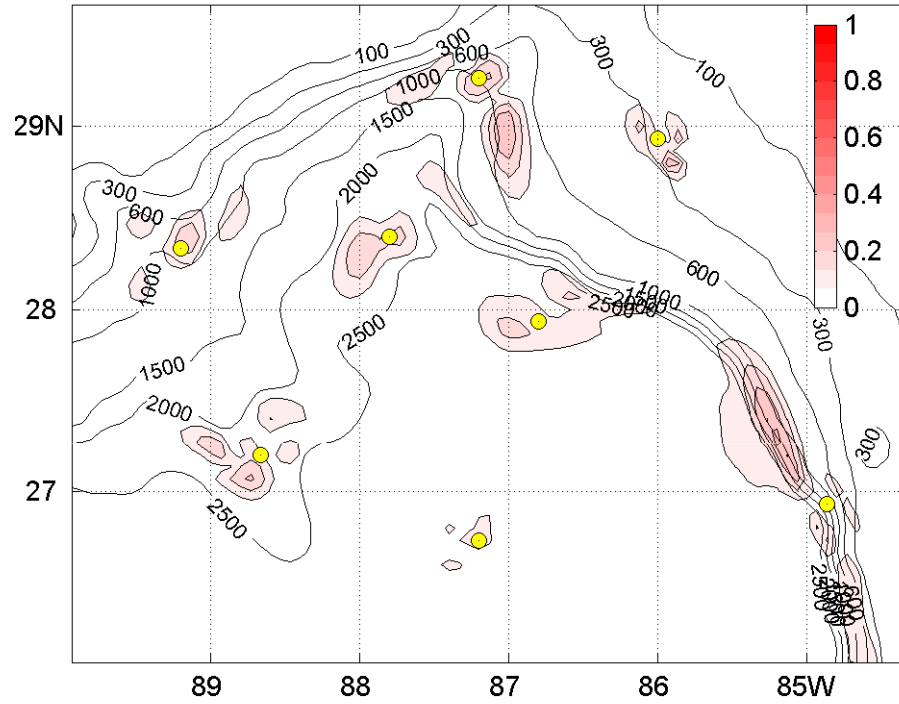
$$\mathbf{X}_e = \mathbf{V}\mathbf{C}_e^{1/2}\mathbf{R}$$



Error metrics



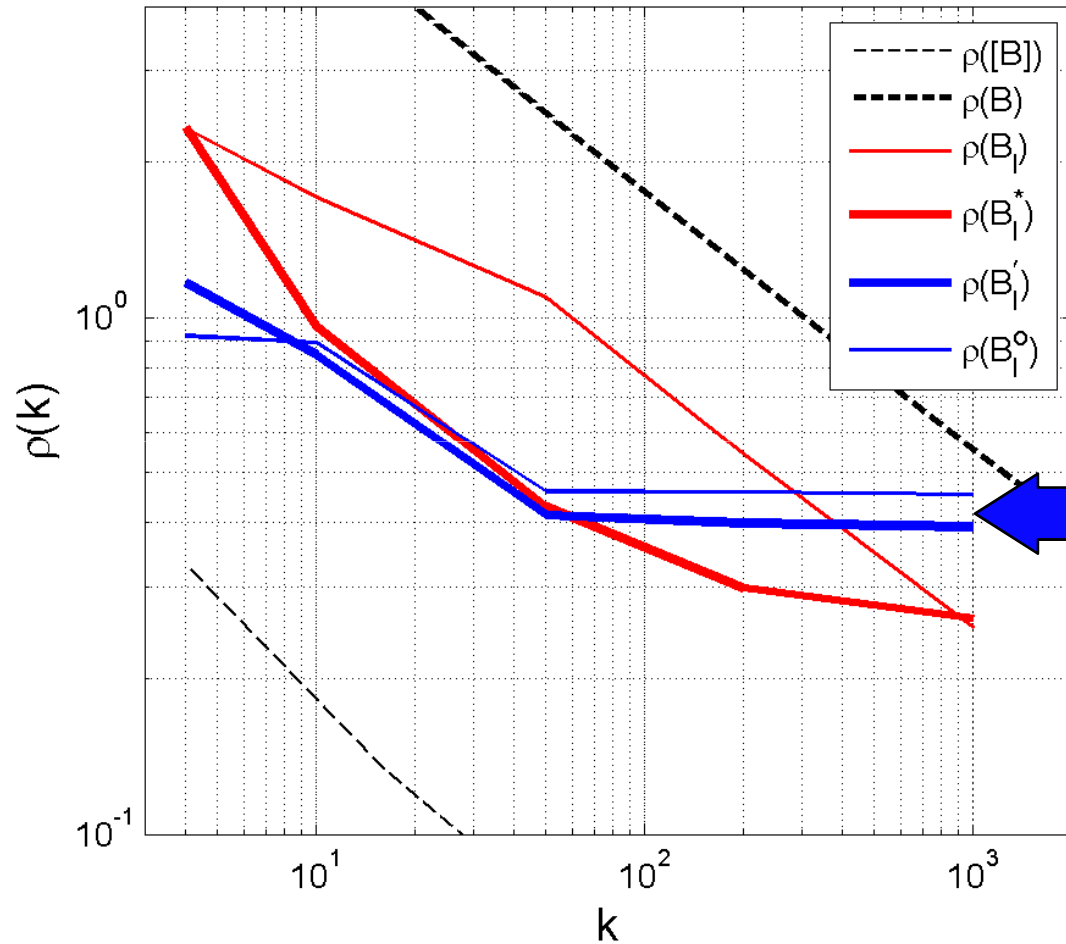
differential method



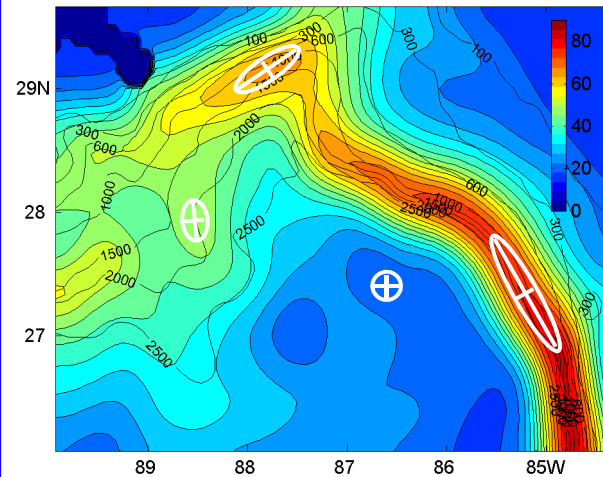
integral method

$$\rho(\mathbf{B}_l, \mathbf{B}) = \sqrt{\frac{|\mathbf{B}_l - \mathbf{B}|}{|\mathbf{B}|}}$$

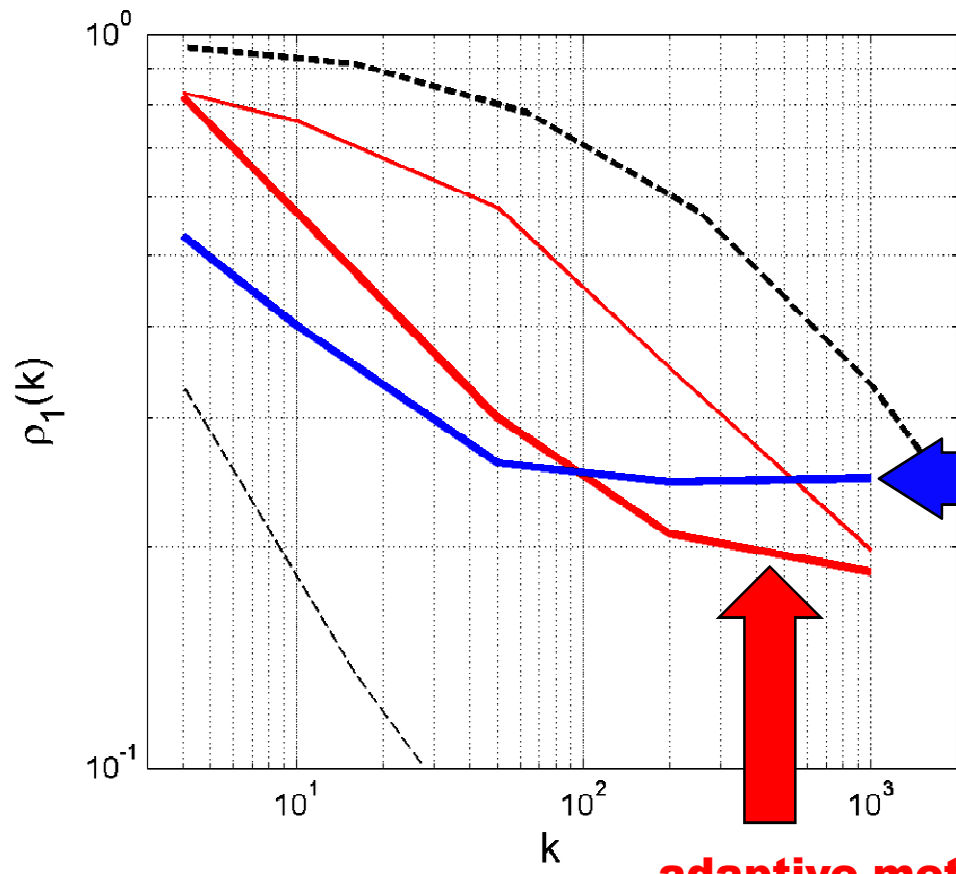
Accuracy: Gaussian model



**saturation imposed
by violation of local
homogeneity**



Accuracy: spline model

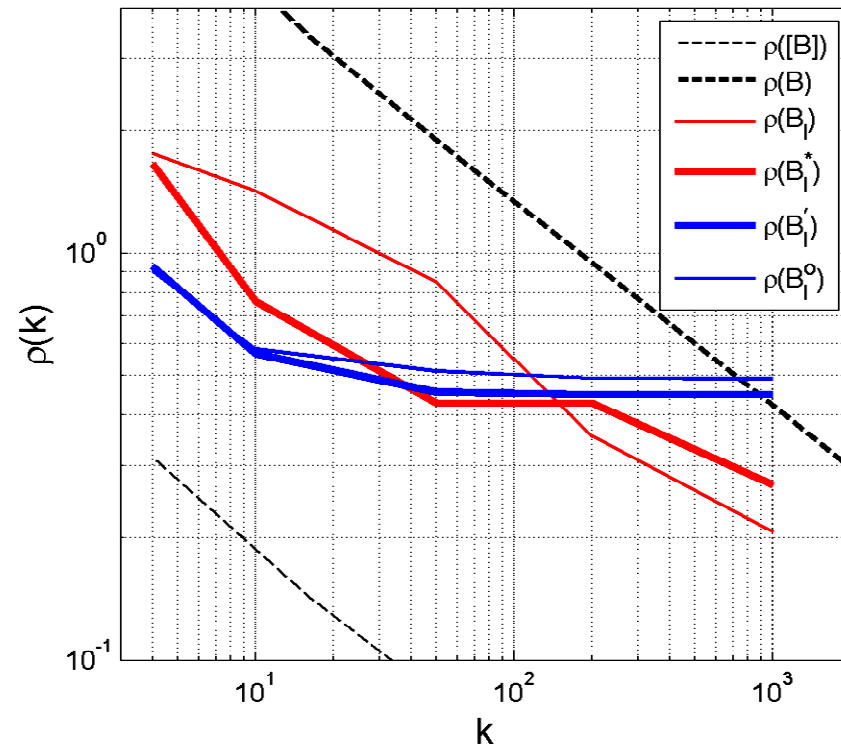
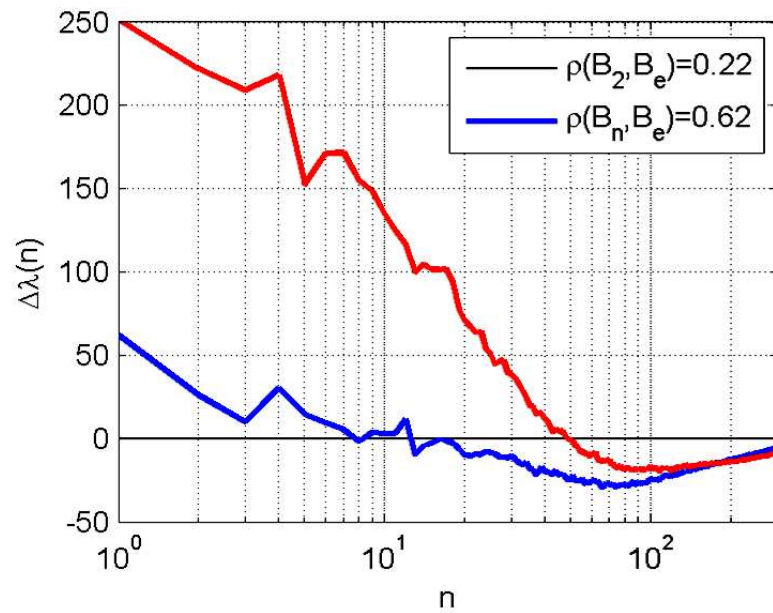
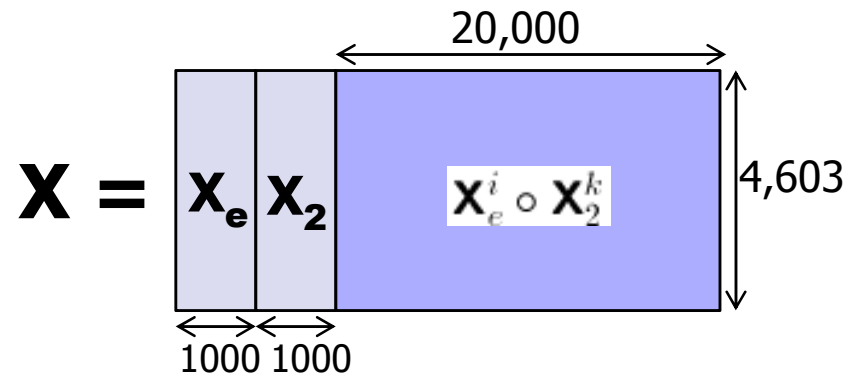


$$\rho_1(\mathbf{C}_\ell, \mathbf{C}) = \sqrt{1 - \frac{\text{tr} \mathbf{C}_\ell \mathbf{C}}{|\mathbf{C}_\ell| |\mathbf{C}|}}$$

**integral method only
(non-differentiability at r=0)**

adaptive method

Accuracy: synthetic model



Computational cost

$$M \simeq n_s k N$$

$$m \sim 10^2 - 10^3 \quad \text{B-iterations (DO methods)}$$

$$M^* \simeq n_s k N J$$

$$k \sim 10^2 \quad \text{ensemble size}$$

$$M' \simeq n_s k N \left(0.2 + \frac{1}{k} + \frac{m}{5k}\right)$$

$$N \sim 10^6 - 10^7 \quad \text{state space dimension}$$

$$M^\circ \simeq n_s k N \left(0.5 + \frac{2}{k} + \frac{m}{5k}\right)$$

$$n_s \sim 50 \quad \text{correlation stencil size}$$

cost relative to the non-adaptive scheme

$$M^*/M = J \quad M'/M = 0.2\left(1 + \frac{m}{k}\right) \quad M^\circ/M = 0.5\left(2.5 + \frac{m}{k}\right)$$

Summary

Accuracy and computational cost of the DO-based covariance localization methods have been tested

1. **An integral DO method has been proposed**
2. **DO methods demonstrate better accuracy at ensemble sizes less than one hundred.**
3. **At larger ensemble sizes the accuracy of DO methods is limited by the violation of the local homogeneity assumption in realistic applications.**
4. **Integral method is more accurate, but 1.5-3 times more computationally expensive than the differential method.**
5. **DO localization methods are more computationally efficient than the adaptive method while providing similar accuracies at $K < 100$.**

These features indicate that DO localization methods could be tested with larger problems emerging in real applications

Appendix

$$R_{ik} = - \left(\frac{1}{r} \frac{\partial C}{\partial r} \right)_{r=0}^{-1} \nabla_i \nabla_k C$$

$$r^2 := x^i R_{ik} x^k$$

$$\nabla_i \nabla_k C = \frac{C_r}{r} R_{ik} + \left(C_{rr} - \frac{C_r}{r} \right) \frac{1}{r^2} R_{ij} x^j R_{km} x^m$$

$$C(r) = (2\pi)^{-n} \int_{\mathbb{R}^n} C(\mathbf{k}) \exp(-i\mathbf{k}\mathbf{x}) d\mathbf{k} \simeq \int_0^\infty C(k) k^{n/2} \frac{J_{n/2-1}(kr)}{r^{n/2-1}} dk$$

$$\left[\frac{\partial^2 C}{\partial r^2} - \frac{1}{r} \frac{\partial C}{\partial r} \right]_{r=0} = 0$$