



A comparison of Ensemble-Variational (EnVar) data assimilation and 4D-Var for global deterministic weather prediction

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Contents

- Background
- The ensemble-variational (EnVar) data assimilation approach
- Recent results from using EnVar compared with standard 3D-Var and 4D-Var (but NO comparisons with 4D-Var-Ben or EnKF)
- Conclusions and next steps





Background

- Environment Canada currently has 2 relatively independent state-ofthe-art global data assimilation systems
- 4D-Var (Gauthier et al 2007) and EnKF (Houtekamer et al 2009):
 - both operational since 2005
 - both use GEM forecast model and assimilate similar set of observations
 - current effort towards unifying code of the two systems
- 4D-Var is used to initialize medium range global deterministic forecasts (GDPS)
- EnKF is used to initialize global ensemble forecasts (GEPS)
- Intercomparison of approaches and various hybrid configurations was performed in carefully controlled context: similar medium-range forecast quality from EnKF and 4D-Var analyses, 4D-Var-Ben best
- Results presented at WMO workshop on intercomparison of 4D-Var and EnKF, Buenos Aires, November 2008 (Buehner et al 2010)



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Ensemble-Variational assimilation: EnVar

- EnVar approach is currently being tested in the context of replacing 4D-Var in the operational Global Deterministic Prediction System
- EnVar uses a variational assimilation approach in combination with the already available 4D ensemble covariances from the EnKF
- By making use of the 4D ensembles, EnVar performs a 4D analysis without the need of the tangent-linear and adjoint of forecast model
- Consequently, it is more computationally efficient and easier to maintain/adapt than 4D-Var
- Hybrid covariances can be used in EnVar by averaging the ensemble covariances with the static NMC-method covariances
- Like 4D-Var, EnVar uses an incremental approach with:
 - analysis increment at the horizontal/temporal resolution of EnKF ensembles
 - background state and analysis at the horizontal/temporal resolution of the higher-resolution deterministic forecast model

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EnVar formulation

• In 4D-Var the 3D analysis increment is evolved in time using the TL/AD forecast model (here included in H_{4D}):

$$J(\Delta \mathbf{x}) = \frac{1}{2} (H_{4D}[\mathbf{x}_{b}] + \mathbf{H}_{4D}\Delta \mathbf{x} - \mathbf{y})^{T} \mathbf{R}^{-1} (H_{4D}[\mathbf{x}_{b}] + \mathbf{H}_{4D}\Delta \mathbf{x} - \mathbf{y}) + \frac{1}{2} \Delta \mathbf{x}^{T} \mathbf{B}^{-1} \Delta \mathbf{x}$$

• In EnVar the background-error covariances and analysed state are explicitly 4-dimensional, resulting in cost function:

$$J(\Delta \mathbf{x}_{4\mathrm{D}}) = \frac{1}{2} (H_{4\mathrm{D}}[\mathbf{x}_{\mathrm{b}}] + \mathbf{H} \Delta \mathbf{x}_{4\mathrm{D}} - \mathbf{y})^{T} \mathbf{R}^{-1} (H_{4\mathrm{D}}[\mathbf{x}_{\mathrm{b}}] + \mathbf{H} \Delta \mathbf{x}_{4\mathrm{D}} - \mathbf{y}) + \frac{1}{2} \Delta \mathbf{x}_{4\mathrm{D}}^{T} \mathbf{B}_{4\mathrm{D}}^{-1} \Delta \mathbf{x}_{4\mathrm{D}}$$

 Computations involving ensemble-based B_{4D} can be more expensive than with B_{nmc} depending on ensemble size and spatial/ temporal resolution, but significant parallelization is possible





EnVar formulation: Preconditioning

Preconditioned cost function formulation at Environment Canada:

$$J(\boldsymbol{\xi}) = \frac{1}{2}\boldsymbol{\xi}^{T}\boldsymbol{\xi} + \frac{1}{2}(\boldsymbol{H}_{4\mathrm{D}}(\mathbf{x}_{\mathrm{b}}) + \mathbf{H}\Delta\mathbf{x}(\boldsymbol{\xi}) - \mathbf{y})^{T}\mathbf{R}^{-1}(\boldsymbol{H}_{4\mathrm{D}}(\mathbf{x}_{\mathrm{b}}) + \mathbf{H}\Delta\mathbf{x}(\boldsymbol{\xi}) - \mathbf{y})$$

In EnVar with hybrid covariances, the control vector (ξ) is composed of 2 vectors: 1ع

$$\begin{bmatrix} \boldsymbol{\xi} \end{bmatrix} = \begin{bmatrix} \boldsymbol{\xi}_{nmc} \\ \boldsymbol{\xi}_{ens} \end{bmatrix} \rightarrow \begin{bmatrix} \boldsymbol{\xi}_{ens} \end{bmatrix} = \begin{bmatrix} \boldsymbol{\xi}_{ens} \\ \vdots \\ \boldsymbol{\xi}_{ens}^{N_{ens}} \end{bmatrix}$$

The analysis increment is computed as (\mathbf{e}_k is k'th ensemble perturbation divided by $sqrt(N_{ens}-1)$):

$$\Delta \mathbf{x}(\boldsymbol{\xi}) = \boldsymbol{\beta}_{nmc}^{1/2} \mathbf{B}_{nmc}^{1/2} \boldsymbol{\xi}_{nmc} + \boldsymbol{\beta}_{ens}^{1/2} \sum_{k=1}^{N_{ens}} \mathbf{e}_{k} \circ \left(\mathbf{L}^{1/2} \boldsymbol{\xi}_{ens}^{k}\right) \rightarrow \mathbf{B} = \boldsymbol{\beta}_{nmc} \mathbf{B}_{nmc} + \boldsymbol{\beta}_{ens} \sum_{k=1}^{N_{ens}} \left(\mathbf{e}_{k} \mathbf{e}_{k}^{T}\right) \circ \mathbf{L}$$

- Better preconditioned than original "alpha control vector" formulation (with L^{-1} and $1/\beta$ in background term of J)
- Most, but maybe not all, applications of the approach use the better preconditioned formulation

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Experimental results: Configuration

EnVar tested in comparison with new version of forecast system currently being implemented in operations:

- model top at 0.1hPa, 80 levels
- ~25km grid spacing
- 4D-Var analysis increments with ~100km grid spacing

EnVar experiments use ensemble members from new configuration of EnKF:

- 192 members every 60min in 6-hour window
- model top at 2hPa, 75 levels
- ~66km grid spacing → EnVar increments ~66km grid spacing





Experimental results: Computational cost

Overall, EnVar analysis ~3X faster than 4D-Var on half as many cpus, even though higher resolution increments Wall-clock time of 4D-Var already close to allowable time limit; increasing number of processors has negligible impact To progress with 4D-Var, significant work would be required to improve scalability of TL/AD versions of forecast model at resolutions and grid configuration used in 4D-Var Current focus for model is on development of higherresolution global Yin-Yang configuration that scales well Decision made to try to replace 4D-Var with more efficient $EnVar \rightarrow$ if EnVar is at least as good as current 4D-Var





EnVar uses Hybrid Covariance Matrix Model top of EnKF is lower than GDPS

Benkf and Bnmc are averaged in troposphere $\frac{1}{2}$ & $\frac{1}{2}$, tapering to 100% Bnmc at and above 6hPa (EnKF model top at 2hPa)

Therefore, EnVar not expected to be better than 3D-Var above ~10-20hPa

Also tested 75% Benkf and 25% Bnmc in troposphere, but results slightly worse

Also did preliminary tests with a full outer loop, but degraded the results



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BIAIS m_ua110201_110314_120_celoc_ua_k3h125_i.ua_keh125_g

BIAIS m_ua110201_110314_120_coloc_ua_keh125_q.ua_k3h125_j

E-T m_ua110201_110314_120_coloc_ua_keh125_g.ua_k3h125_j (83)

Lat-lon: (90S, 180W) (20S, 180E)

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Forecast Results: EnVar vs. 3D-Var and 4D-Var Verification against ERA-Interim analyses – 6 weeks, Feb/Mar 2011 Tropics 250hPa U-wind STDDEV



Verification against ERA-Interim analyses – 6 weeks, July-Aug 2011



Verification against ERA-Interim analyses – 6 weeks, July-Aug 2011



Verification against ERA-Interim analyses – 6 weeks, July-Aug 2011



Experimental results: 4D-EnVar vs. 3D-EnVar

3D version of EnVar also tested: only uses EnKF flowdependent ensembles valid at the centre of the 6h assimilation window, instead of every 60 minutes throughout the window

3D-EnVar compared with:

• 4D-EnVar: impact of 4D covariances, and

• 3D-Var: impact of flow dependent vs stationary (NMC) covariances (both 3D)



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Forecast Results: 4D-EnVar vs. 3D-EnVar





Forecast Results: 4D-EnVar vs. 3D-EnVar

1.00





Forecast Results: 4D-EnVar vs. 3D-En-Var



Conclusions

- Comparison of EnVar with 3D-Var and 4D-Var:
 - EnVar produces similar quality forecasts as 4D-Var below ~20hPa in extra-tropics, significantly improved in tropics
 - above ~20hPa, scores similar to 3D-Var, worse than 4D-Var; potential benefit from raising EnKF model top to 0.1hPa
- EnVar is an attractive alternative to 4D-Var:
 - like EnKF, uses full nonlinear model dynamics/physics to evolve covariances; no need to maintain TL/AD version of model
 - makes use of already available 4D ensembles
 - more computationally efficient and easier to parallelize than 4D-Var for high spatial resolution and large data volumes
 - computational saving allows increase in analysis resolution and volume of assimilated observations; more computational resources for EnKF and forecasts



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Next Steps

- Finalize testing EnVar with goal of replacing 4D-Var in operational prediction system during 2013 in combination with other changes:
 - GEM global model on 15km Yin-Yang grid
 - CALDAS: new surface analysis system based on EnKF
 - modified satellite radiance bias correction scheme that gives conventional observations more influence on correction
 - improved use of radiosonde and aircraft data
 - additional AIRS/IASI channels and modified observation error variances for all radiances
 - − possibly increased resolution of EnKF 66km \rightarrow 50km
- Testing of EnVar in regional prediction system as possible replacement of 4D-Var already started

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