

On the Transport of Chemically Reactive Pollutants over Urban Roughness in the Atmospheric Boundary Layer



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Outline

- \circ Background
- \circ Objectives
- Methodology
- \circ Results
- \circ Conclusion & Outlook

Urban Climate





Fig.2

- High pollution levels in urban street canyons due to the increased traffic emissions
- The main traffic-related pollutants are CO, NOx, hydrocarbons, and particles

Street canyon Street height-to-width ratio AR=h/b

Street Canyon



- (1) skimming (h/b > 0.7, isolated recirculations)
- (2) wake interference (0.3 < h/b < 0.7, entrainment)
- (3) isolated roughness (h/b < 0.3, reattachment and separation)

These regimes characterize the mechanisms of flow, transport and pollutant removal from the street level to the atmospheric boundary layer (ABL) through the urban canopy layer (UCL). Idealized street canyon is an infinitely long street flanked by high-rise buildings. Its building-height-to-street-width ratio, h/b, is a key geometric factor determining the flow regime.



Fig.4 Flow regime

Objectives

- Formulate a CFD model for simple NO_x-O₃ chemistry
- Look into the pollutant concentrations and dispersion characteristics over the street canyons
- Analyze the characteristics of plume dispersion of passive scalar and chemically reactive pollutant
- Examine the relative contribution between chemistry and turbulent dilution to NO consumption along the plume dispersion using time scale analysis

Large-Eddy Simulation

- Reynolds-averaged Navier–Stokes equations (RANS)
 - the full range of turbulence scales is simplified to one parameterization.
 - cost-effective but merely captures the important aspects of recirculating flow in street canyons
- Large-Eddy Simulation (LES)
 - calculates explicitly the large-scale energy-carrying turbulence
 - small portions of the fluxes are modeled by subgrid-scale (SGS) models
 - Improved prediction accuracy of the pollutant dispersion compared with that of the $k-\varepsilon$ models.
- Direct Numerical Simulation (DNS)
 - computes the whole spectrum of turbulence
 - unaffordable expense of lengthy computation time and costly resources.

Methodology

Subgrid-scale (SGS) model

Spatial filtering

$$f = \overline{f} + f'$$
 $\overline{f}(x_i, t) = \int_{\Omega} f(x_i, t) G(x_i - \xi_i, \overline{\Delta}) d\xi_i$

 \bar{f} : the large filtered-scale component f': the SGS component

Conservation of momentum		$\frac{\partial u_i}{\partial t} + \frac{\partial}{\partial x_j} u_i u_j =$	$-\frac{\partial p}{\partial x_i} + \frac{\partial p}{\mathbf{I}}$	$\frac{1}{\operatorname{Re}} \frac{\partial^2 u_i}{\partial x_j \partial x_j}$	$\frac{\partial u_i}{\partial t} + \frac{\partial}{\partial x_j} \overline{u_i u_j} = -$	$-\frac{\partial \overline{p}}{\partial x_i}$	$-\frac{\partial au_{ij}}{\partial x_j} +$	$\frac{1}{\text{Re}}\frac{1}{\hat{c}}$	$\frac{\partial^2 \overline{u_i}}{\partial x_j \partial x_j}$
The continuity		$\frac{\partial u_i}{\partial x_i} = 0$			$\frac{\partial \overline{u_i}}{\partial x_i} = 0$				
The scalar transpo	rt equation	$\frac{\partial c}{\partial t} + \frac{\partial u_i c}{\partial x_i} = \frac{1}{\operatorname{Re} So}$	$\frac{\partial^2 c}{\partial x_i \partial x_i}$		$\frac{\partial \overline{c}}{\partial t} + \frac{\partial \overline{u_i c}}{\partial x_i} = -\frac{\partial \sigma_i}{\partial x_i}$	$+\frac{1}{\text{Re}S}$	$\frac{\partial^2 \bar{c}}{\partial x_i \partial x_i}$		
	<i>t</i> : time <i>u_i</i> : velocity components <i>p</i> : kinematic pressure Re: Reynolds number				Sc = v / D $\tau_{ij} = \overline{u_i u_j} - \overline{u_i u_j}$	idt nu SGS	mber stres	S	

Chemistry Model

$$\frac{\partial C_a}{\partial t} + U_j \frac{\partial C_a}{\partial x_j} = \frac{\partial}{\partial x_j} \left(D \frac{\partial C_a}{\partial x_j} \right) + S_a(\mathbf{C}) \longrightarrow \text{Source term}$$

Here C denotes a vector of all the reacting species in the flow.

$$NO_2 + hv \xrightarrow{j_1} NO + O$$
 $\qquad \qquad \frac{\delta[O_3]}{\delta t} = j_1 - k_3[O_3][NO]$

In the presence of sunlight

$$O + O_2 + M \xrightarrow{k_2} O_3 + M$$

$$\frac{\delta[NO_2]}{\delta t} = k_3[O_3][NO] - j_1$$

independent of solar radiation

$$O_3 + NO \xrightarrow{k_3} NO_2 + O_2$$

$$\frac{\delta[NO]}{\delta t} = j_1 - k_3[O_3][NO]$$

Geometry Information



Fig.5 Computational Domain



Description	Parameters	Value
Grid Number	Nx Ny Nz	864 96 84
Grid Number in Street Canyon	Ncx Ncz	12 12
Total Grid Number	Ν	6,400,000

Fig.6 Grid information in Street Canyon

Methodology

Boundary Conditions



Fig.7 Boundary Condition

Result

Velocity & NO Field



Reaction time scale

$NO_2 + hv \rightarrow NO + O$	photolysis rate j_1	In the presence of sunlight
$O + O_2 + M \rightarrow O_3 + M$	rate constant k_2	Independent of solar radiation
$O_3 + NO \rightarrow NO_2 + O_2$	rate constant k_{3}	

• Ground-state oxygen atom O is highly reactive such that its formation is fast enough to counterbalance its depletion.

• Reaction time scale of NO:
$$\tau_{NO} = \frac{1}{k_3[O_3]_0}$$

• Reaction time scale of O3: $\tau_{O_3} = \frac{1}{k_3[NO]_0}$

Result

Diffusion Time Scale

Mass conservation of species:

$$\frac{\partial c_i}{\partial t} + \frac{\partial}{\partial x_j} (u_j, c_i) = D_i \frac{\partial^2 c_i}{\partial x_j \partial x_j} + R_i (c_1, \dots, c_N, T) + S_i (x, t)$$

 c_i :species concentration of interest D_i : molecular diffusion constant R_i : rate of c_i generated reaction S_i : rate of c_i generated by source

 There exists a closure approximation in introducing the concept of eddy diffusivity and its statistical approximations for the random concentration and velocity components from turbulent mixing.

$$\langle u_j^{"}c_i^{"}\rangle = -K\frac{\partial \overline{c_i}}{\partial x_j}$$

K is the eddy diffusivity

 $K_{\emptyset} = -\frac{\langle w^{"} \emptyset^{"} \rangle}{\partial \langle \overline{\emptyset} \rangle}$

• For passive scalar Ø

$$\langle w'' \phi'' \rangle = -K_{\phi} \frac{\partial \langle \overline{\phi} \rangle}{\partial z}$$

• For pollutant NO

$$\langle w"NO" \rangle = -K_{NO} \frac{\partial \langle \overline{NO} \rangle}{\partial z} \qquad K_{NO} = -\frac{\langle w"NO"}{\frac{\partial \langle \overline{NO} \rangle}{\partial z}}$$

$$\tau_d = \frac{\sigma_z^2}{4K_{\emptyset}}$$

$$\tau_{dNO} = \frac{\sigma_{zNO}^2}{4K_{NO}}$$

Result

Time scale of NO



- The diffusion time scale τ_d of NO (normalized by the diffusion time scale near the roof level τ_{d0} at z = 1.1h)
- Near the first street canyon (x = 6h), σ_z is relatively small and the plume is not yet fully developed.
- The pollutant concentration gradient is small near the domain top so the diffusion time scale remains small from z = 3h and thereafter.
- In the far field, the vertical coverage is notable and the diffusion time scale also increases.
- The normalized diffusion time scale exhibits linear characteristic within the plume $(z/\sigma_z \ge 10)$

Time scale of NO



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- The O₃ concentration is lower than that in the upper domain
- The reaction time scale of NO in the near-wall region is longer than that in the upper domain.
- In the far field the gradient of reaction time scale in the vertical direction become larger than that in the near field

Da>1: The pollutants are not mixed uniformly for complete reactions.

 $\tau_{\rm NO}$

Da<1: slow chemical reactions occur in the well-٠ mixed condition.

Branching point



Conclusion & Outlook

- The reaction time scale is much longer compared with the turbulent time scale when the initial concentration is small.(NO = O₃ = 1ppb)
- Two time scales are coupled with each other. In particular, pollutant chemistry could increase or decrease the diffusion time scale, i.e. dispersion coefficient.
- More different concentration cases are needed to analyze the relative contribution between chemistry and turbulent dilution to NO consumption along the plume dispersion.

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Thank you!

Q&A

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Gaussian Plume Model



- The larger σ means the broader distribution. Further from the source the plume becomes broader and so the value of σ is greater.
- The Gaussian plume pollutant dispersion model can gives a fairly good estimate of the pollutant concentration when using accurate parameters.
- σy and σz are related to atmospheric turbulence, surface roughness and distance from the pollutant source.

σz: Dispersion Coefficient

$$\sigma_z^2 = \frac{\iiint (z - z_c)^2 \emptyset dy dt dz}{\iiint \emptyset dy dt dz}$$

time and spanwise average

$$\sigma_z^2 = \frac{\int (z - z_c)^2 \emptyset dz}{\int \emptyset dz}$$

$$z_c = \frac{\int z \emptyset dz}{\int \emptyset dz}$$

$$\sigma_z^2 = \frac{\sum_{i=1}^N (z_i - z_c)^2 \emptyset_i \Delta z_i}{\sum_{i=1}^n \emptyset_i \Delta z_i}$$

 ϕ_i :concentration at a certain position z_c : plume center height

$$z_c = \frac{\sum_{i=1}^{N} z_i \phi_i \Delta z_i}{\sum_{i=1}^{n} \phi_i \Delta z_i}$$

Basically, σ_z is the length scale of the pollutant plume width