



COUPLED OCEAN-ATMOSPHERE 4DVAR

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Coupled Ocean-Atmos 4DVAR: motivation

On-going efforts at the US Naval Research Laboratory (NRL) have led the implementation of the Coupled Ocean/Atmosphere Mesoscale Prediction System (COAMPS-5): atmosphere-wave-ocean

The analyses in COAMPS-5 are produced from separate 3DVAR based DA systems

Problem 1, separate analyses: the assimilation in one fluid does not take into account the observations or lack thereof in the adjacent fluid

Problem 2: the absence of a cross-covariance between the fluids prevents the corrections in one fluid from propagating into the other.

This results in unbalanced analyzes and initialization shocks.





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What is needed is a fully coupled and dynamically balanced analysis.

In the meantime, NRL has also developed individual 4dvar systems for the atmosphere and ocean models.

This study aims to coupled those 4dvar systems. The new coupled assimilation system will

- 1. Provide a fully balanced (dynamically consistent) analysis that accounts for all combined observations in both fluids.
- 2. Reduce the errors in the state estimation and the forecast.
- 3. Exploit the cross-covariance between the two fluids to provide corrections from observations in one fluid to the other



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Analysis/update equation

$$\widehat{u} = u^{b} + BH^{T} (HBH^{T} + R)^{-1} (y - Hu^{b}) = u^{b} + LCL^{T}H^{T} (HLCL^{T}H^{T} + R)^{-1} (y - Hu^{b})$$

$$B = \begin{bmatrix} B^{a} & B^{oa} \\ B^{oa} & B^{o} \end{bmatrix} \qquad \qquad The action of the fully coupled tangent linear and adjoint models provides the cross correlations that are needed to propagate information from the observation in one fluid to the other$$

$$L = \begin{bmatrix} \frac{\partial F}{\partial u}(u) \end{bmatrix} \qquad \qquad \text{Linearization of atmospheric and ocean models, and all nonlinear air-sea fluxes exchange (coupling terms)}$$

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Coupled Ocean-Atmos 4DVAR: sensitivity to SST



Day -4 Day -3 Day -2 Day -1 $Pa_{x 10}^{-4}$ To Atmos. 30N Pressure 25N TULIODE $^{-2}$ 20N W/m² 30N 1000 **To Solar** 25N 25N 500 Radiation -500 -100020NW/m² 30N 1000 25N TATITUDE 500 **To Heat** 0 -500 Flux -1000 20N30N Pa 0.05 25N TULIDE -0.05**To Wind** 20N **Stress** 95W 90W 85W 80W 95W 90W 85W 80W 95W 90W 85W 95W 90W 85W 80W 80W LONGITUDE LONGITUDE LONGITUDE LONGITUDE 11/17/2016 International workshop on coupled data assimilation, Oct. 18-21, 2016, Toulouse (France) 6

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Why a coupled TLM/ADJ?



-0.2

-0.4 -0.7

-1 -1.5

0.4

-0.1 -0.1 -0.2 -0.4

--0.7 --1

Analysis increment evolution of *T* by TLM (z=10m)

Analysis increment evolution of *T* by NLM (z=10m)



The increment evolution by the TLM does not match the NLM well near the sea surface because the atmosphere doesn't "see" changes to the ocean during the assimilation process



Coupled TLM





6 h evolution of atmospheric TLM *T* forced only by the upper level ocean in the box indicated in the figure (all initial atmospheric fields are 0) Cross section indicated by the line in the above figure. The atmospheric response is confined to the boundary layer



Coupled TLM



Atmospheric response to a 1 K perturbation of the top level ocean temp over whole ocean domain (purple box)

9 h forecast, ocean is perturbed at initial time, no other perturbations



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Coupled adjoint







6 h sensitivity of atmospheric winds at 2000 m to the upper level ocean temperature (all initial atmospheric adjoint fields were 0) Cross section of sensitivity indicated by line in above figure. Greatest sensitivity is above boundary layer.





- A fully coupled global Atmos-Waves-Ocean-Acoustics 4DVAR system
 - Improves accuracy of initialization of coupled system
 - Bring the benefits of 4DVAR to the global model
 - Minimize the effect of erroneous BCs when forecasting the regional model
- What needs to be done to get there
 - Global Atmos 4DVAR already exists
 - New developments
 - Global ocean 4dvar
 - Global wave 4dvar
 - Leverage existing coupling infrastructure



Global ocean/waves 4dvar



- First, ensure that NCOM-4DVAR can be used for global analysis
- Global HYCOM provides the forecast

$$\hat{u}(x,t) = u_F(x,t) + \sum_{m=1}^{M} \hat{\beta}_m r_m(x,t)$$

The same forecast is taken as the background for NCOM-TLM
Use NCOM TLM and adjoint for computing the correction

Global waves 4DVAR

Global

ocean

4DVAR

- Develop a 4DVAR system for WaveWatch 3 in the same way that SWAN-FAR was developed
 - WW3 TLM and adjoint
 - ESMF interfaces



- Work is underway in developing a fully/strongly coupled atmosphere-ocean 4dvar system
- Preliminary results of coupled TLM and coupled adjoint show the ability to propagate the information properly across the fluids
- The system will be tested for regional applications first

Conclusion

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- Future plans include the expansion to global applications that also include waves coupling
- That will require the development of global 4dvar for both ocean and waves models