

# Impact of microwave radiometer accuracy and stability on retrieved parameters

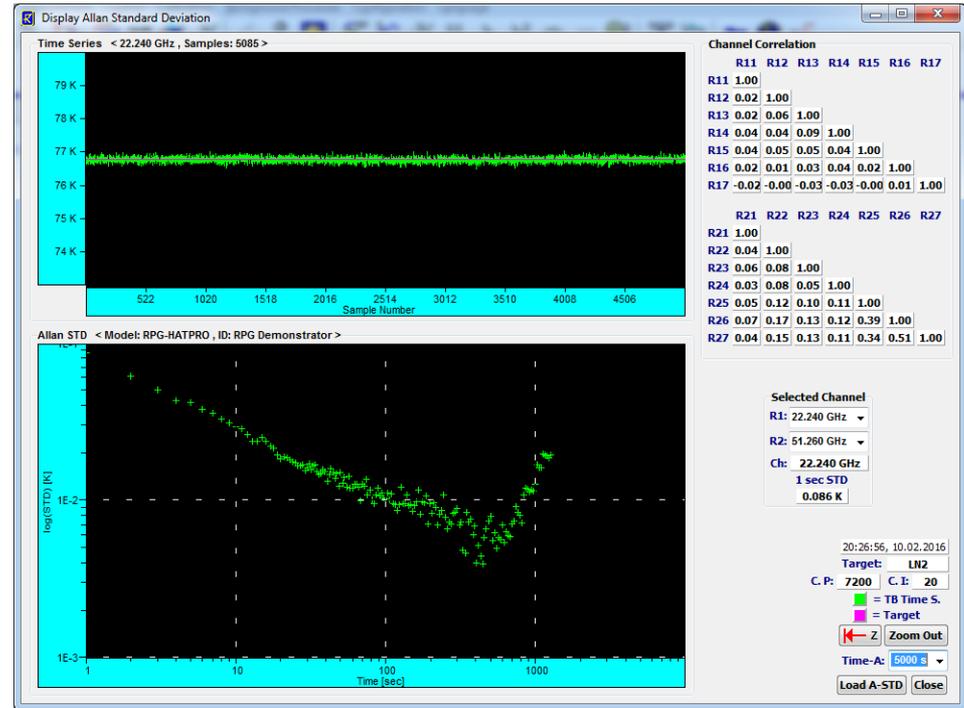
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# Recap

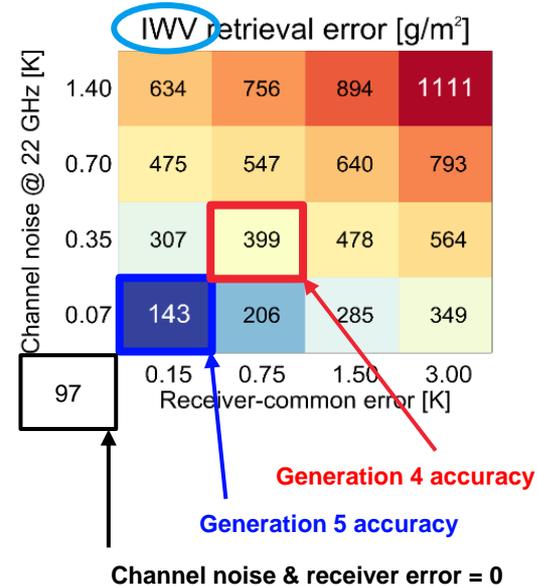
## RPG-HATPRO generation 5 improvements

- **Rapid noise switching** (64 Hz) and rework of data acquisition system (4 kHz)
  1. **Correction of gain drift** on short time scales  
Allan Standard Deviation shows -1/2 slope  
100 s integration → reduction of NeDT by 10
  2. **Reduction of NeDT**  
0.07 K in K-band @ 1s integration time  
0.05 K to 0.14 K in V-band @ 1s
  3. **Uncorrelated channel noise**
- Improved **calibration process**
  1. **Improved cold load**: no secondary reflector, no reflection, **no standing waves**, no condensation and oxygen entrainment
  2. **Improved ambient load**: finer calibration of temperature sensors.



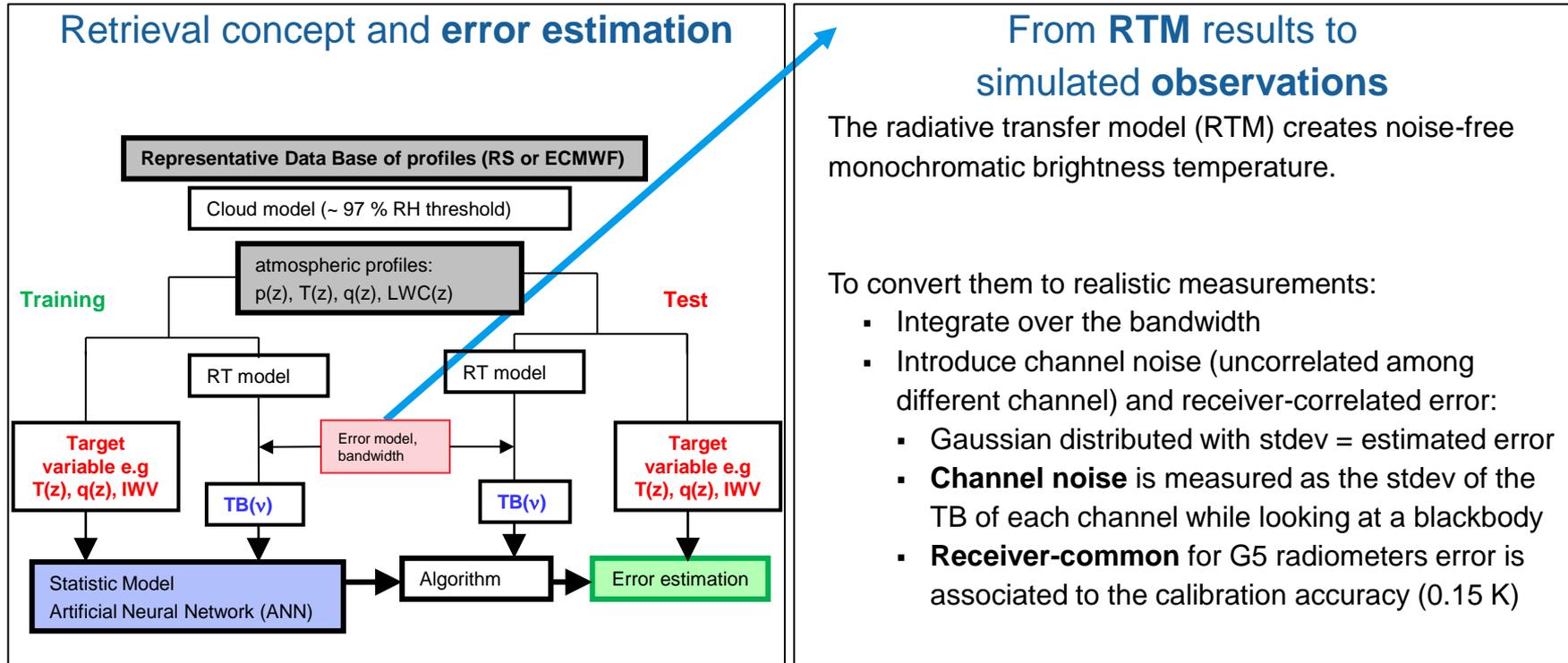
# TB error impact on level 2 products

- How reduced noise and improved stability impact retrieved (level 2) products?
- In this study we quantify this impact for several products
- In these examples the **IWV** retrieval accuracies are plotted as a function of
  - Receiver common error – **x-axis**
  - Individual channel noise – **y-axis**
- Generation-5 RPG radiometer performance is enclosed in blue square.
- The previous generations has both errors increased by a factor 5 (red square).
- Retrieval with no added noise are shown at bottom left corner
- **Lindenberg** (central European) radiosondes profiles (~35 k) have been used



# Methodology:

train several ANN with different error assumptions

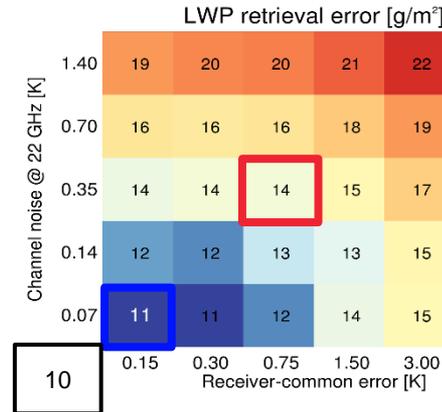
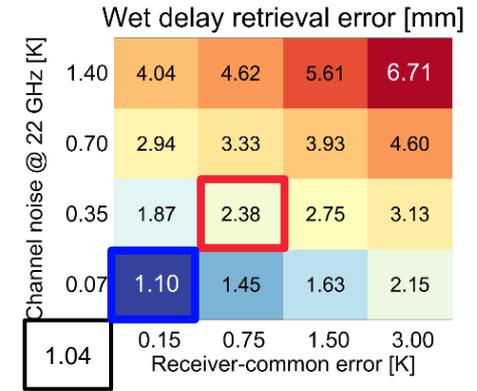
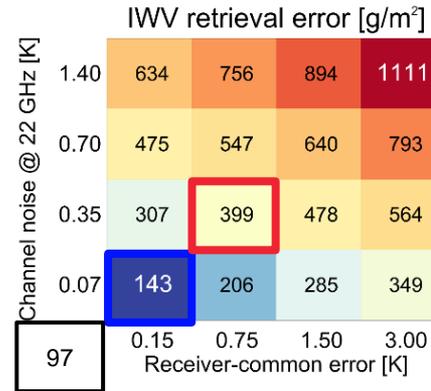


# Integrated variables

Level-2 Root Mean Squared (**RMS**) errors are calculated for zenith viewing.

- IWV, wet delay, and LWP are all sensitive to both error types: channel noise and receiver-common bias
- Increasing the channel noise has stronger impact than increasing by the same factor the receiver-common bias on integrated product
- Due to redundant information contained in the 7 K-band HATPRO channels, doubling of the channel-noise do not imply doubling of the retrieved product RMS error

WMO goal for NWP: 1 kg/m<sup>2</sup>

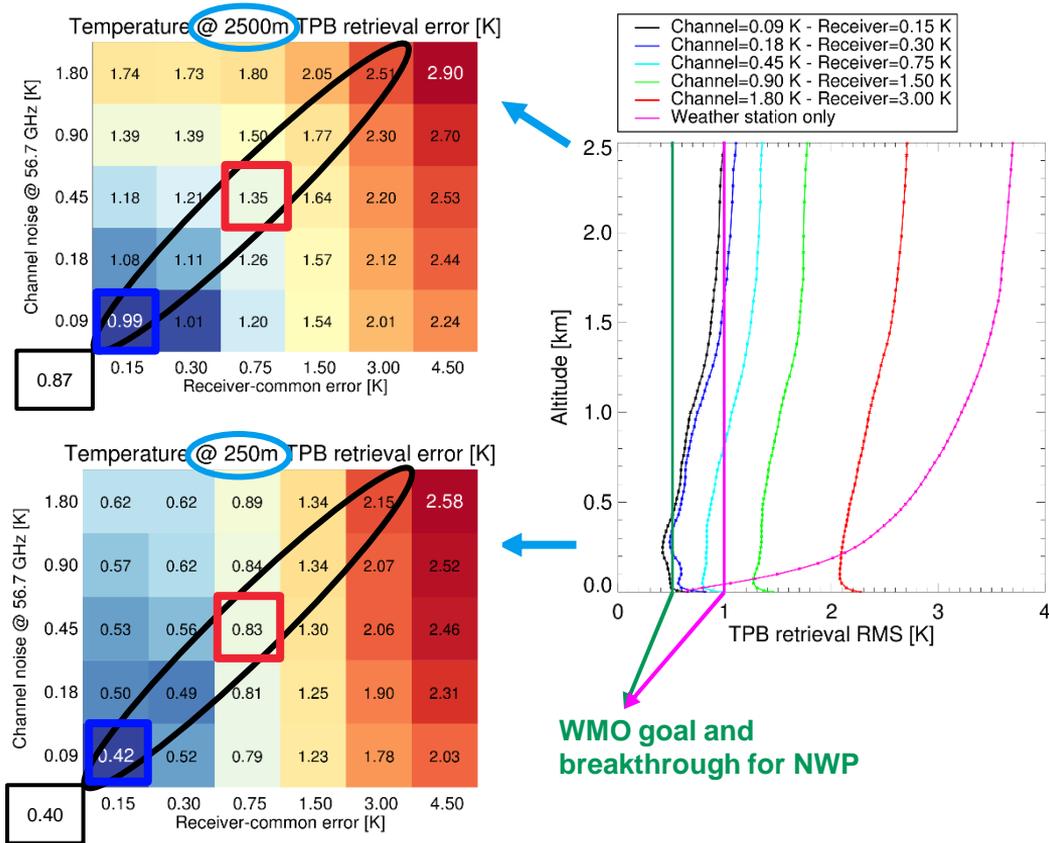


# Temperature profile: multi-angle retrieval

**Tables** show the temperature profile dependence of RMS on receiver-common and channel noise  
**Plot** shows the vertical profile of RMS for error along the diagonal of the tables

- At **low altitude** (250 m):
  - strong sensitivity to receiver-common bias
  - high redundancy of multi-channel, multi-angle retrieval → low sensitivity to channel-noise
  - receiver-common bias (calibration error) results in biased retrieved temperature
- At **2.5 km** channel noise and receive-common error have similar impact
- G5 radiometer RMS is meeting WMO breakthrough below 2.5 km

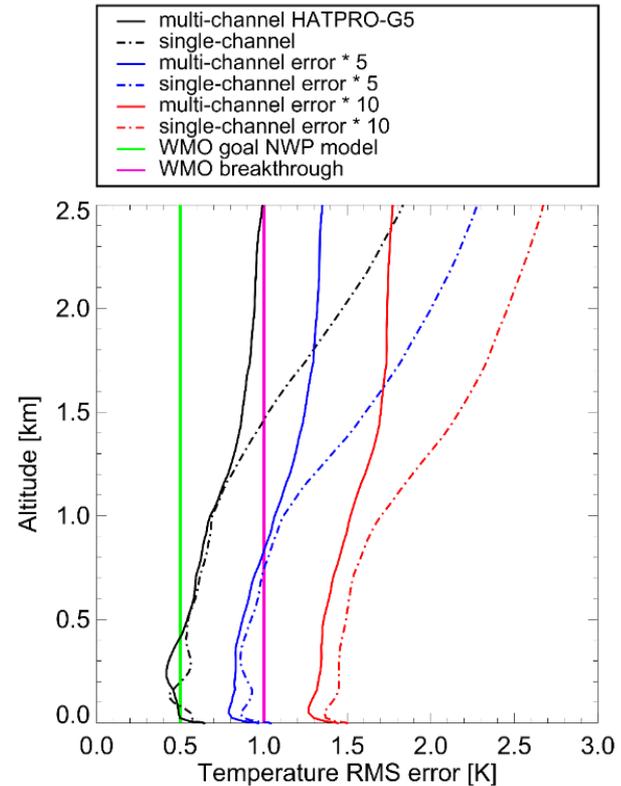
RPG do NOT use ground temperature readings for temperature profiling



# Temperature profile: multi- versus single-channel retrieval

**Plot:** thin solid lines are for multi-angle **multi-channel** retrieval; dashed lines for multi-angle **single-channel**.

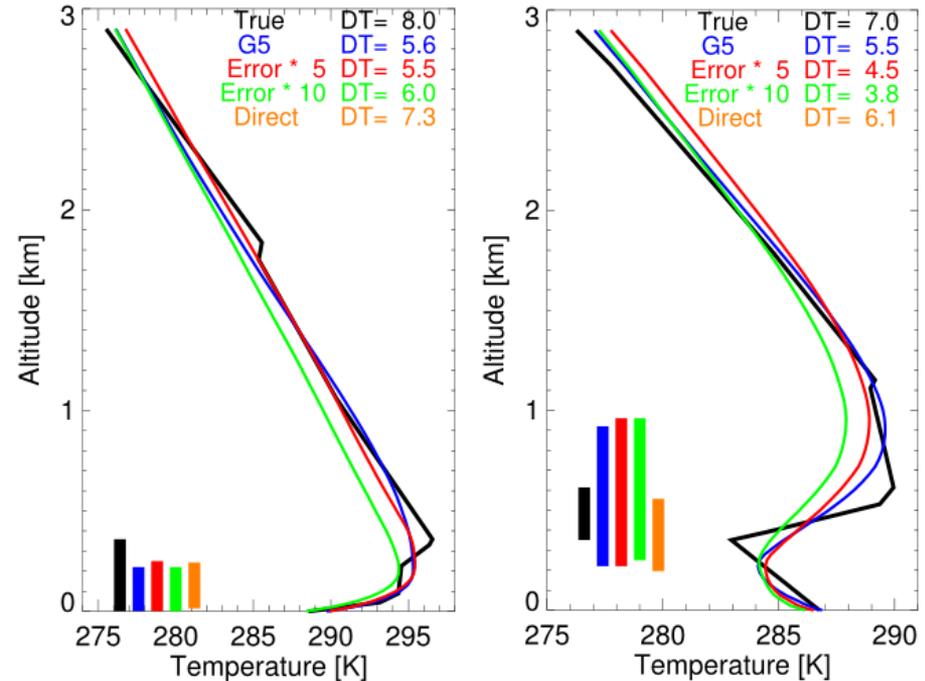
- Multi-channel RMS error is similar to single-channel RMS up to 1 km
- Above 1 km multi-channel retrievals outperform single-channel ones because of the information of the more transparent channels



# Temperature inversion: Direct retrieval

- RPG developed a new direct retrieval for temperature inversions
- The retrieval use as target the inversion height, strength, and thickness
- The advantage is that the cost function minimized for the retrieval training is not the RMS for the whole profile
- Simulated results shows better performances of the direct retrieval, especially for **lifted inversion**
- Direct comparison with radiosonde is in progress
- The new retrieval will be implemented into the RPG software after validation

Munich airport radiosondes



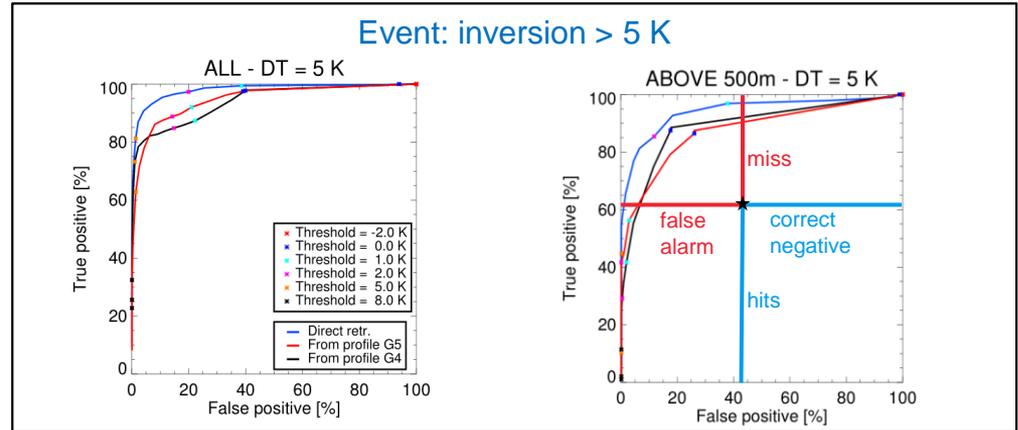
# Temperature inversion: classification

Receiver Operating Characteristic (**ROC**) plot:

- ROC plot summarizes several contingency tables in one plot
- Retrieved strength is used for classification
- By varying the threshold used for detection, different **hits** ratio (true positive) and **false-alarm** ratio (false positive) can be achieved
- Tailored threshold to fit customers needs:
  - E.g. Airports may need 95% **hits** ratio and can leave with 20% **false alarm** ratio

Performance:

- Direct retrieval inversion has better performances than diagnosing inversions from retrieved temperature profiles
- Direct retrieval is especially successful for elevated inversions



# Summary and outlook

## ■ Level 2 products accuracy:

- IWV and wet-delay are more sensitive to channel noise than receiver-common bias
- Temperature profile in BL is most sensitive to receiver-common biases
- Multi-channel multi-angle retrievals perform better above BL than single-channel
- Reduced noise and stability are crucial to meet WMO and customer requirements

## ■ Temperature inversion:

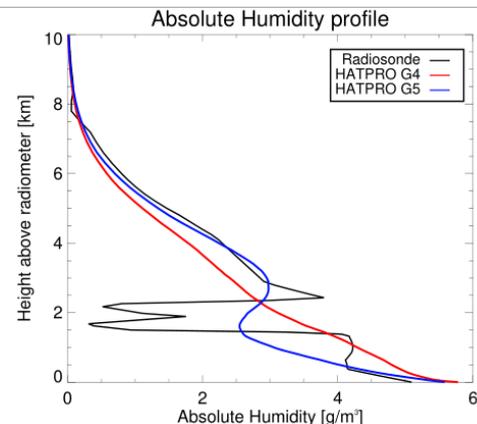
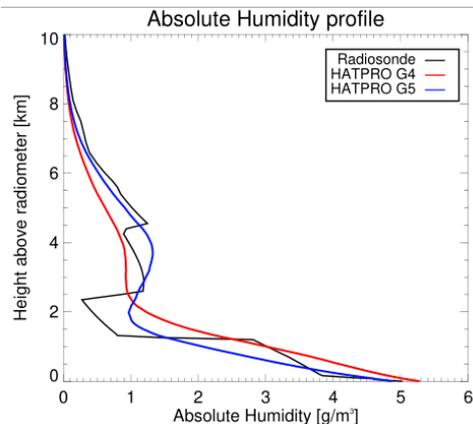
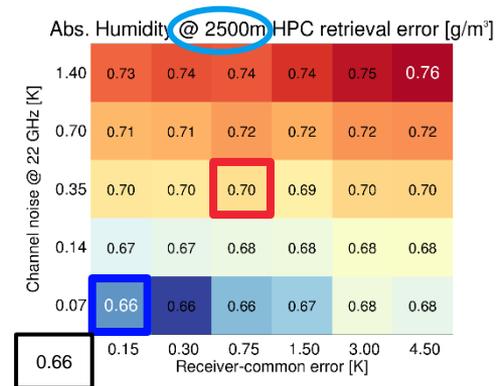
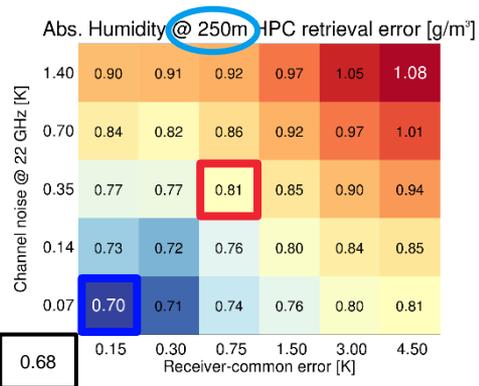
- New direct retrieval developed
- Implementation in RPG software after validation with radiosonde comparison
- Direct retrieval shows higher accuracy, especially for lifted inversions

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# Absolute humidity profile:

- On average, RMS improvements from G4 to G5 series are between 5 and 15%
- Most of the sensitivity to channel noise and correlated error is in the boundary layer
- For non-standard cases, the improvement is significant
- Higher information content → more feature in the vertical profile



# Temperature inversion

**Definition:** atmospheric layers where  $dT/dz$  is positive. As opposed to the standard atmospheric behaviour, temperature increases with height.

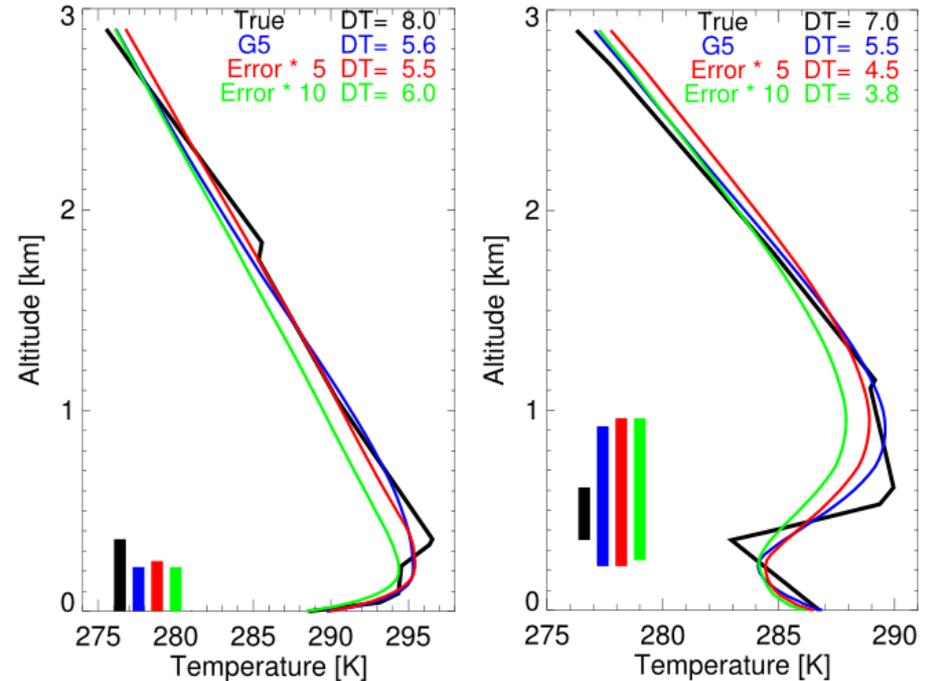
## Impacts:

- Vertical motion is inhibited within layers with temperature inversion, pollutants get trapped below inversion top
- Strong wind shear is often found at the inversion top, endangering airport take-off and landing operations
- Ground based inversions are often associated with fog formation, reducing the visibility
- Inversions can lead to imprecise take-off and landing performance calculations.

## Mitigation:

- Real-time temperature inversion classification (strength, height) at high temporal resolution
  - helps airport take-off and landing operations
  - helps fog formation and dissipation forecast
  - can be used to regulate emissions (pollutants, PM)

Munich airport radiosondes



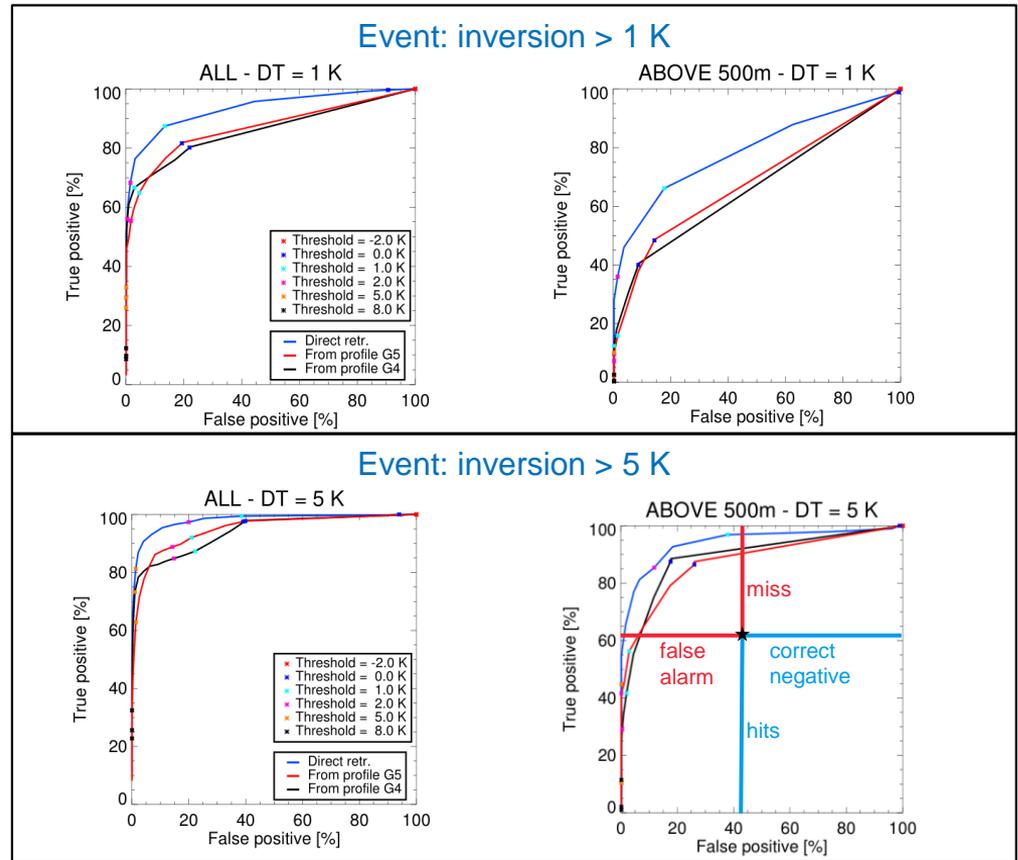
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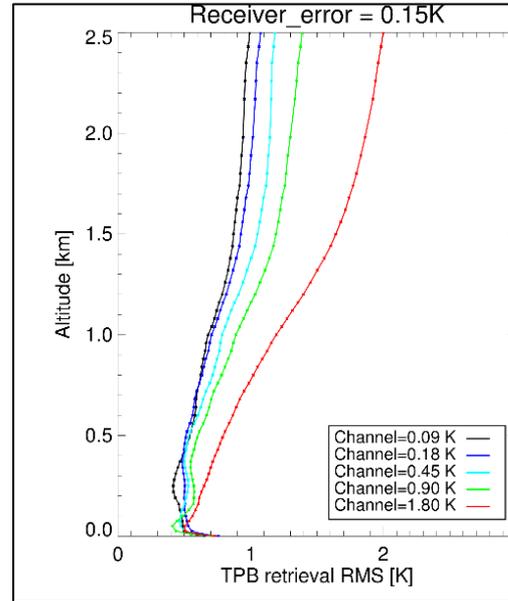
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- Direct retrieval is especially successful for elevated inversions



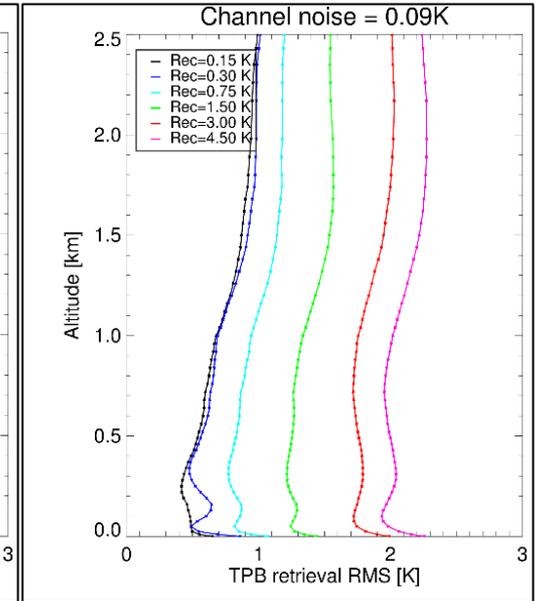
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- At 2.5 km the dependency on channel noise is stronger

Variable **channel noise**

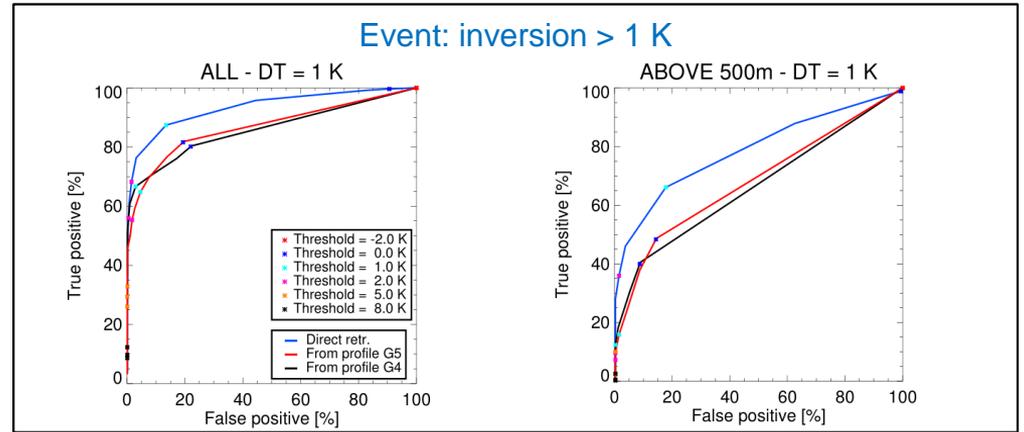


Variable **receiver-common bias**



# Temperature inversion: classification

| 2x2 Contingency Table |     | Event Observed |                       |
|-----------------------|-----|----------------|-----------------------|
|                       |     | Yes            | No                    |
| Event Forecast        | Yes | a (hits)       | b (false alarms)      |
|                       | No  | c (misses)     | d (correct negatives) |



True positive rate = probability of detection (POD)

True positive rate = hits / condition positive

True positive rate = hits / (hits+misses)

False positive rate = probability of false alarm (POFD)

False positive rate = misses / condition negative

False positive rate = misses / (false alarm + corr. negative)